Sri Sivasubramaniya Nadar College of Engineering

(An Autonomous Institution, Affiliated to Anna University, Chennai)



Regulation 2021

Curriculum and Syllabi for B.E. Electrical and Electronics Engineering

DEPARTMENT OF ELECTRICAL AND ELECTRONICS ENGINEERING

VISION

- To inculcate the right mix of knowledge, attitudes and character in students to enable them take up positions of responsibility in the society and make significant contributions.
- To produce talented Electrical and Electronics Engineers through quality education, to be a Centre of Excellence and become a source of cutting-edge technologies in the field of Electrical and Electronics Engineering.
- To become a preferred partner in the area of collaborative research among national and international organizations.

MISSION

- To achieve global eminence in the field of Electrical and Electronics Engineering.
- To be a highly preferred destination comparable with the best in the world for students aspiring to enter the field of Electrical and Electronics Engineering.
- To nurture the talent and to facilitate the students with all round personality development to make a positive difference to society through education.

PROGRAM EDUCATIONAL OBJECTIVES (PEOs)

PEO1: Graduates of the programme will have successful career by their ability to contribute in the electrical and electronics engineering or related professional fields

PEO2: Graduates of the programme can work in teams with technical competencies, discharging their professional and social responsibilities.

PEO3: Graduates of the programme will exhibit demonstrable attributes in lifelong learning to contribute to their chosen professional field.

PROGRAMME OUTCOMES (POs)

After the successful completion of the B.E. Electrical and Electronics Engineering degree programme, the students should be able to:

PO1.Engineering knowledge: Apply the knowledge of mathematics, science, engineering fundamentals, and an engineering specialization to the solution of complex engineering problems.

PO2.Problem analysis: Identify, formulate, review research literature, and analyze complex engineering problems reaching substantiated conclusions using first principles of mathematics, natural sciences, and engineering sciences.

PO3.Design/development of solutions: Design solutions for complex engineering problems and design system components or processes that meet the specified needs with appropriate consideration for the public health and safety, and the cultural, societal, and environmental considerations.

PO4.Conduct investigations of complex problems: Use research - based knowledge and research methods including design of experiments, analysis and interpretation of data, and synthesis of the information to provide valid conclusions.

PO5.Modern tool usage: Create, select, and apply appropriate techniques, resources, and modern engineering and IT tools including prediction and modeling to complex engineering activities with an understanding of the limitations.

PO6. The engineer and society: Apply reasoning informed by the contextual knowledge to assess societal, health, safety, legal and cultural issues and the consequent responsibilities relevant to the professional engineering practice.

PO7. Environment and sustainability: Understand the impact of the professional engineering solutions in societal and environmental contexts, and demonstrate the knowledge of, and need for sustainable development.

PO8. Ethics: Apply ethical principles and commit to professional ethics and responsibilities and norms of the engineering practice.

PO9. Individual and team work: Function effectively as an individual, and as a member or leader in diverse teams, and in multidisciplinary settings.

PO10. Communication: Communicate effectively on complex engineering activities with the engineering community and with society at large, such as, being able to comprehend and write effective reports and design documentation, make effective presentations, and give and receive clear instructions.

PO11. Project management and finance: Demonstrate knowledge and understanding of the engineering and management principles and apply these to one's own work, as a member and leader in a team, to manage projects and in multidisciplinary environments.

PO12. Life-long learning: Recognize the need for and have the preparation and ability to engage in self, and lifelong learning in the broadest context of technological change.

PROGRAMME SPECIFIC OUTCOMES (PSOs)

After the successful completion of the B.E. Electrical and Electronics Engineering degree programme, Graduate will have the ability to:

PSO1: To apply advanced science and engineering knowledge to analyse and design complex electrical and electronic devices, software and systems containing hardware and software components.

PSO2: To design and analyze systems used in advanced power applications, renewable energy, electrical drives for the transportation, manufacturing industries and in allied technical fields.

PEO /PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	P08	PO9	PO 10	PO 11	PO 12	PSO 1	PSO 2
PEO1	3	3	3	3	3	2	2	2	2	2	2	2	3	3
PEO2	1	1	1	1	1	3	3	3	3	3	2	2	1	1
PEO3	1	1	1	1	1	1	2	2	2	2	3	3	1	2

PEOs Mapping with POs and PSOs

	POs										PSO			
Course	1	2	3	4	5	6	7	8	9	10	11	12	1	2
			Se	mest	ter I									
Technical English									2	3		2		
Matrices and Calculus	3	2											1	
Engineering Physics	3	2	1											
Engineering Chemistry	3	2	1											
Problem Solving and Programming in Python	2	2	2	1										
Engineering Graphics	3	2	2			2				3				
Programming in Python Lab	3	3	2	1		2		1	3	2				
Physics and Chemistry Lab	3	5		1				1	5					
	5		Ser	nest	er II	r								
Complex Functions and Laplace				nest										
Transforms	3	2										1		
Basic Electrical and Electronics	3	3	2	3									2	2
Engineering	0	0	0	2	0		0		0	2	0	4	~	
Electrical circuits and systems -	3	3	2	2	2		3		3	3	3	1	3	
Fundamentals and practices (TCP - EFP)														
Environmental Science (Non-	2	2	1											
credit)	3	2	1											
Engineering Mechanics for	3	2	2											
Electrical Engineers	3	2	2											
Design Thinking and	3	3	3	3		1			3	1		1	3	
Engineering Practices Lab	5	5		-					5	1		1	5	
		1	Sen	neste	er II	I				1	1	1		
Transform Techniques and	3	2											1	
Partial Differential Equation						-		2	2	2		2		
UHV: Understanding Harmony	2	2	2	2	2	2	1	3	3	2	2	3	2	2
Signals and Systems	3	3	2	3	3	2	1		2	1	2	3	3	2
Electromagnetic Theory	3	2	1						1	1		1	3	
Object Oriented Programming and Data Structures for	3		2	1	3								3	
Electrical Engineering	5		2	1	5								5	
Electronic Devices and Circuits	3	2	3	2	2							1	1	3
Electronics Lab	$\frac{3}{2}$	$\frac{2}{2}$	$\frac{3}{1}$	3	2			1	3	1		1	2	3
Object Oriented Programming	-	-		5					5	-				5
and Data Structures Laboratory	3		2	2	3								3	
for Electrical Engineering	-				-								-	
			Sen	neste	er IV	/								
Probability and Statistics for	3	2		1									1	
Electrical Engineering	3	2		1									1	
Indian Constitution						2		2	2	2	2	1		
Electrical Machines -I	3	2	1	2						1		1	1	3
Analog Electronic Circuits	3	1	3	1	2							1	1	3
Control Systems Engineering	3	3	3	2	2								3	2

	r –	1	1	1	r –						1		1	
Generation, Transmission and	3	3	2	1	3			1					1	
Distribution				_	_				-	_				
Electrical Machines -I Lab	2	2	1	3				1	3	1			2	3
Analog Electronic Circuits Lab	3	2	3	2	2				2			1	2	1
				nest		r				1	1			
Power Electronics	3		2	2	2								1	2
Electrical Machines -II	3	2	1	2	1		1		1	1		1	1	3
Electrical Measurements and	3	2	3	2		2						3	3	2
Instrumentation Systems	5	2	5	2		2						5	5	2
Digital Logic System Design	3	2	3	3	3	1	1	1	2	1	2	1	2	1
and Practices (TCP – EFP)			_	_	_	1	1	1		1	2	1		
Electrical Machines -II Lab	3	3	1	3	1			1	3	1		1	2	3
Control System and	1	2	2	3	2	2	3					2	3	3
Instrumentation Lab	1	2	2	5	2	2	5					7	2	5
			Sen	neste	er V	Ι								
Microprocessors and														
Microcontrollers -Fundamentals	3	3	3	3	3				2	2			3	3
and Practices (TCP – EFP)														
Power System Analysis	3	3	2	2	3			2				2	1	1
Power System Operation and	3	3	3	3	2								3	2
Control	3	3	3	3	2								3	Z
Power Electronics and Drives	2	2	2	2	2								2	2
Lab	3	3	3	3	3								3	2
Power System Simulation Lab	3	3	3	3	3								3	2
		1	Sem	leste	r V	Ι					1			
Solid State Drives	3	2	3	1	2								1	3
Protection and Switchgear	3	2	1	1	2	2	2	2				2	3	2
High Voltage Engineering	3	3	3	2	3								2	1
Industrial Training /Internship	3	3	2	3	3	3	3	3	3	2	3	3	3	2
Advanced Electrical and							-				-		-	_
Electronics Design Lab	2	2	1	3	2		1	1	3	1		1		
Project Phase I	3	3	2	3	3	3	3	3	3	2	3	3	3	2
	5		Sem				5	5	5	2	5	5	5	4
Project Phase II	3	3	2	3	3	3	3	3	3	2	3	3	3	2
	-	-	_	-	-	ctive	-	5	5	2	5	5	5	2
Solar Energy Systems	3	3	2	3	2		2		2	1		1	1	2
Fundamentals of Digital Signal					2		2			1				
Processing	2	2	3	2	1				2			2	3	3
Energy Resources and														
Utilization	3	3	1	1				2				2	1	1
Communication Engineering	1	1			2				1			1	2	1
Low Voltage Direct Current		1										1		
Systems	3		2	2	2								1	2
Wind Energy Conversion														
	3	2	2	3	3				2	1		2	2	2
systems Advanced Control Theory	3	3	2	2	2								3	2
	3	3	2	2	2									2
Power System Dynamics	3				$\frac{3}{2}$	1						2	1	1
VLSI Design Techniques		3	2	2		1				1		2	2	1
Switched Mode Power Supplies	3	2	2	2	2					1		2	1	2

Energy Storage Systems		3	2	2	2					2			1	2
System Identification and	_	-											-	
Adaptive Control	3	1	2	2	2	2				1	1	3		
Artificial Intelligence for Power	•	•	_		•									
Systems	3	3	2	3	3							1	1	
Automotive Electronics	3	2	2	1		2	2						2	2
Electrical Machine Design	3	3	3	1	3	3	2		1	1	1	1	3	3
Smart Grid	3	2	2	1	1							1	1	2
Principles of Robotics	3	3	3	3	2								3	3
Internet of Things in Power	2		2	1		1	•	_			2	•	1	
System Engineering	3		2	1	2	1	2	2			2	2	1	
Power Semiconductor Devices	3	3	2	2								1		2
Flexible AC Transmission														
Systems and Custom Power	3	3	3	3	2									
Devices														
Distributed Generation and	3	3	3	2	2	1	1		1	1		1	1	2
Micro Grid	3	3	3	Z	2	1	1		1	1		1	1	Z
PLC and SCADA	3		3		2	1	2	2			2	2	1	3
Power System Transients	3	3	3	2	3									
Embedded Systems	3	3	2	3	2	1						2	2	2
High Voltage Direct Current	3	2	2	2	2							2	2	1
Transmission	5	2	2	2	2							2	2	1
Electric Vehicle and Power	3	2	3	2	2	1	1		1		1		1	2
Management						1	1		-		1		1	2
Digital Control Systems	3	3	3	3	3									
Energy Management and	3	2	2	2	1	2	2		2	2		1		
Auditing	5	-	-	-	-	-	_		_			-		
Microcontroller Based System	2		3	3	3							2	2	1
Design			-	_	_									
Power Quality	3	3	3	3	2		2	1		1		1	2	1
	Μ	lana	gen	ient		ctiv	es		-	-	-			
Principles of Management					3	_	-	_	2	2	2	1		
Total Quality Management					2	3	2	2	1		1	1		
Work Ethics, Corporate Social						3	2	3	1	1	3	2		
Responsibility and Governance					<u> </u>									
	H	ıma	niti	es I	eleo		es	1	•	-	<u> </u>		1	
Language and Communication									2	3		2		
Fundamentals of Linguistics									2	3		2		
Film Appreciation						-		<u> </u>	2	3		2		
Human Relations at Work						2		2	3	2		2		
Application of Psychology in						2		2	3	2		2		
Everyday Life														
Understanding Society and									2	3		2		
Culture Through Literature														

SUSTAINABLE DEVELOPMENT GOALS (SDG)

	SDG	Description
SDG1	No Poverty	End poverty in all its forms everywhere
SDG 2	Zero Hunger	End hunger, achieve food security and improved nutrition, and promote sustainable agriculture
SDG 3	Good health and well being	Ensure healthy lives and promote well-being for all at all ages
SDG 4	Quality education	Ensure inclusive and equitable quality education and promote lifelong learning opportunities for all
SDG 5	Gender Equality	Achieve gender equality and empower all women and girls
SDG 6	Clean water and sanitation	Ensure availability and sustainable management of water and sanitation for all
SDG 7	Affordable and clean energy	Ensure access to affordable, reliable, sustainable and modern energy for all
SDG 8	Decent work and Economic Growth	Promote sustained, inclusive and sustainable economic growth, full and productive employment and decent work for all
SDG 9	Industry, Innovation and Infrastructure	Build resilient infrastructure, promote inclusive and sustainable industrialization, and foster innovation
SDG 10	Reducing Inequality	Reduce income inequality within and among countries
SDG 11	Sustainable cities and communities	Make cities and human settlements inclusive, safe, resilient, and sustainable
SDG 12	Responsible consumption and production	Ensure sustainable consumption and production patterns
SDG 13	Climate action	Take urgent action to combat climate change and its impacts by regulating emissions and promoting developments in renewable energy
SDG 14	Life below water	Conserve and sustainably use the oceans, seas and marine resources for sustainable development
SDG 15	Life on Land	Protect, restore and promote sustainable use of terrestrial ecosystems, sustainably manage forests, combat desertification, and halt and reverse land degradation and halt biodiversity loss
SDG 16	Peace, justice and string Institutions	Promote peaceful and inclusive societies for sustainable development, provide access to justice for all and build effective, accountable and inclusive institutions at all levels
SDG 17	Partnerships for the goals	Strengthen the means of implementation and revitalize the global partnership for sustainable development

MAPPING OF SUBJECT RELEVANT TO SDG

		Sustainable Development Goals															
	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17
Technical English				✓													
Matrices and Calculus				\checkmark													
Engineering Physics				\checkmark													
Engineering Chemistry				\checkmark													
Problem Solving and				\checkmark													
Programming in Python																	
Engineering Graphics				\checkmark													
Programming in Python				\checkmark													
Lab				\checkmark													
Physics and Chemistry Lab				v													
Complex Functions and				\checkmark													
Laplace Transforms																	
Basic Electrical and				\checkmark													
Electronics Engineering																	
Electrical Circuits and				✓													
Systems - Fundamentals																	
and practices (TCP -																	
EFP) Environmental Science			\checkmark	\checkmark		✓	\checkmark						✓	\checkmark	\checkmark		
(Non-credit)				•		•	•						•	•	•		
Engineering Mechanics				✓													
for Electrical Engineers																	
Design Thinking and				\checkmark													
Engineering Practices																	
Lab																	
Transform Techniques and Partial Differential				~													
Equation																	
-				\checkmark													
UHV: Understanding			\checkmark														
Harmony																	
Signals and Systems				\checkmark													
Electromagnetic Theory				\checkmark													
Object Oriented				\checkmark													
Programming and Data																	
Structures for Electrical																	
Engineering Electronic Devices and				\checkmark													
Circuits																	
Electronics Lab	1			✓													
Object Oriented				\checkmark													
Programming and Data																	
Structures Laboratory																	

		Sustainable Development Goals															
	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17
for Electrical																	
Engineering																	
Probability and				\checkmark													
Statistics for Electrical																	
Engineering																	
Indian Constitution				\checkmark													
Electrical Machines -I				✓													
Analog Electronic				\checkmark													
Circuits																	
Control Systems				✓													
Engineering																	
Generation,				\checkmark													
Transmission and									\checkmark								
Distribution																	
Electrical Machines -I				\checkmark													
Lab				,													
Analog Electronic				\checkmark													
Circuits Lab																	
Power Electronics				✓													
Electrical Machines -II				\checkmark													
Electrical				\checkmark													
Measurements and																	
Instrumentation																	
Systems																	
Digital Logic System				\checkmark													
Design and Practices																	
(TCP – EFP)				\checkmark													
Electrical Machines -II				v													
Lab Control System and				\checkmark													
Control System and Instrumentation Lab				•													
Microprocessors and				\checkmark													
Microcontrollers -				•													
Fundamentals and																	
Practices (TCP – EFP)																	
Power System Analysis				✓													
Power System / Indrysis				✓													
Operation and Control																	
Power Electronics and				\checkmark													
Drives Lab																	
Power System				\checkmark													
Simulation Lab																	
Solid State Drives				\checkmark													
Protection and				\checkmark													
Switchgear																	
High Voltage				\checkmark													

	Sustainable Development Goals															
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17
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		Sustainable Development Goals															
	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17
Distributed Generation				\checkmark							\checkmark	\checkmark					
and Micro grid											v	v					
PLC and SCADA				\checkmark													
Power System				\checkmark													
Transients																	
Embedded Systems				\checkmark													
High Voltage Direct				\checkmark													
Current Transmission																	
Electric Vehicle and				\checkmark			~				~	~					
Power Management							•				•	•					
Digital Control Systems				\checkmark													
Energy Management				\checkmark			\checkmark				\checkmark	✓					
and Auditing							•				•	•					
Microcontroller Based				\checkmark													
System Design																	
Power Quality				\checkmark			\checkmark				\checkmark	\checkmark					
Principles Of			✓	\checkmark	✓												
Management																	
Total Quality			\checkmark	\checkmark	\checkmark				\checkmark								
Management																	
Work Ethics, Corporate	\checkmark	\checkmark	,	\checkmark				,									
Social Responsibility			✓		\checkmark			\checkmark		✓							
and Governance																	
Language and				\checkmark				\checkmark									
Communication																	
Fundamentals Of				\checkmark				\checkmark									
Linguistics																	
Film Appreciation																	
Human Relations at				\checkmark	\checkmark			\checkmark			\checkmark						
Work																	
Application Of				\checkmark													
Psychology in											✓						
Everyday Life																	
Understanding Society				✓							\checkmark						
and Culture Through											v						
Literature																	

	SEMESTER I													
Sl. No.	COURSE CODE	COURSE TITLE	CATE GORY	CONTACT PERIODS	L	Т	Р	С						
	THEORY													
1	UEN2176	Technical English	HS	4	2	0	2	3						
2	UMA2176	Matrices and Calculus	BS	4	3	1	0	4						
3	UPH2176	Engineering Physics	BS	3	3	0	0	3						
4	UCY2176	Engineering Chemistry	BS	3	3	0	0	3						
5	UGE2176	Problem Solving and Programming in Python	ES	3	3	0	0	3						
6	UGE2177	Engineering Graphics	ES	5	1	0	4	3						
		PRAC	CTICALS											
7	UGE2197	Programming in Python Lab	ES	3	0	0	3	1.5						
8	UGS2197	Physics and Chemistry Lab	BS	3	0	0	3	1.5						
	TOTAL 28 15 1 12 22													

I to VIII semesters Curriculum	- R 2021 (Choice Ba	sed Credit System)
		bed create by stemp

SEMESTER II											
SI. No.	COURSE CODE	COURSE TITLE	CATE GORY	CONTACT PERIODS	L	Т	Р	EL	С		
			THEORY								
1	UMA2276	Complex Functions and Laplace Transforms	BS	4	3	1	0	0	4		
2	UEE2276	Basic Electrical and Electronics Engineering	ES	3	3	0	0	0	3		
3	UEE2201	Electrical Circuits and Systems -Fundamentals and practices	ES	6	3	0	3	3	5.5		
4	UCY2276	Environmental Science	MC*	3	3	0	0	0	0		
5		Humanities I-Elective	HS	4	2	0	2	0	3		
6	UMA2276	Engineering Mechanics for Electrical Engineers	ES	3	3	0	0	0	3		
PRACTICALS											
7	UGE2297	Design Thinking and Engineering Practices Lab	ES	3	0	0	3	0	1.5		
			TOTAL	26	17	1	8	3	20		

*Non-credit

		SEMESTE	RIII								
Sl. No.	COURSE CODE	COURSE TITLE	CATE GORY	CONTACT PERIODS	L	Т	Р	С			
		THEOF	RY								
1	Partial Differential Equation										
2	UHS2376	Universal Human Values 2: Understanding Harmony	HS	4	2	0	2	3			
3											
4	UEE2301	Electromagnetic Theory	PC	3	2	1	0	3			
5	UEE2302	Object Oriented Programming and Data Structures for Electrical Engineering	ES	3	3	0	0	3			
6	UEE2303	Electronic Devices and Circuits	PC	3	3	0	0	3			
		PRACTIC	CALS								
7	UEE2311	Electronics Lab	PC	3	0	0	3	1.5			
8	UEE2312	Object Oriented Programming and Data Structures Laboratory for Electrical Engineering	ES	3	0	0	3	1.5			
			TOTAL	26	16	2	8	22			

		SEMES'	TER IV							
Sl. No.	COURSE CODE	COURSE TITLE	CATE GORY	CONTACT PERIODS	L	Т	Р	С		
		THE	ORY							
1	UMA2452	Probability and Statistics for Electrical Engineering	BS	3	2	1	0	3		
2	AHS2476	Indian Constitution	MC	4	3	0	0	0		
3	UEE2401	Electrical Machines -I	PC	3	3	0	0	3		
4	UEE2402	Analog Electronic Circuits	PC	3	3	0	0	3		
5	UEE2476	Control Systems Engineering	PC	3	3	0	0	3		
6	UEE2403	Generation, Transmission and Distribution	PC	4	4	0	0	4		
		PRACT	ICALS							
7	UEE2411	Electrical Machines -I Lab	PC	3	0	0	3	1.5		
8	UEE2412	Analog Electronic Circuits Lab	PC	3	0	0	3	1.5		
	TOTAL 26 18 1 6 19									

		SEN	IESTER V						
Sl. No.	COURSE CODE	COURSE TITLE	CATE GORY	CONTACT PERIODS	L	Т	Р	EL	С
			THEORY						
1	UEE2501	Power Electronics	PC	3	3	0	0		3
2	UEE2502	Electrical Machines -II	PC	3	3	0	0		3
3	UEE2503	Electrical Measurements and Instrumentation Systems	PC	3	3	0	0		3
4	UEE2504	Digital Logic System Design and Practices	PC	4	3	0	1	3	4.5
5		Management –Elective	HS	3	3	0	0		3
6		Professional Elective- I	PE	3	3	0	0		3
		F	PRACTICA	LS					
7	UEE2511	Electrical Machines -II Lab	PC	3	0	0	3		1.5
8	UEE2512	Control System and Instrumentation Lab	PC	4	0	0	4		2
			TOTAL	26	18	0	8		23

		SEM	ESTER V	[
Sl. No.	COURSE CODE	COURSE TITLE	CATE GORY	CONTACT PERIODS	L	Т	Р	EL	С
			THEORY	Y					
1	UEE2601	Microprocessors and Microcontrollers - Fundamentals and Practices	PC	4	3	0	1	3	4.5
2	UEE2602	Power System Analysis	PC	3	3	0	0		3
3	UEE2603	Power System Operation and Control	PC	3	3	0	0		3
4		Professional Elective- II	PE	3	3	0	0		3
5		Professional Elective -III	PE	3	3	0	0		3
6		Open Elective I	OE	3	3	0	0		3
		Р	RACTICA	LS					
7	UEE2611	Power Electronics and Drives Lab	PC	4	0	0	4		2
8	UEE2612	Power System Simulation Lab	PC	3	0	0	3		1.5
			TOTAL	26	18	0	8		23

		SEMEST	ER VII							
Sl. No.	COURSE CODE	COURSE TITLE	CATE GORY	CONTACT PERIODS	L	Т	Р	С		
		THEO	RY							
1	UEE2701	Solid State Drives	PC	3	3	0	0	3		
2	UEE2702	Protection and Switchgear	PC	3	3	0	0	3		
3UEE2703High Voltage EngineeringPC33003										
4		Professional Elective- IV	PE	3	3	0	0	3		
5		Professional Elective -V	PE	3	3	0	0	3		
		PRACTI	CALS			•				
6	UEE2716	Industrial Training /Internship*	EEC	0	0	0	0	2		
7	UEE2711	Advanced Electrical and Electronics Design Lab	PC	4	0	0	4	2		
8	UEE2718	Project Phase I	EEC	6	0	0	6	3		
	TOTAL 25 15 0 10 22									

* The students will undergo 4 weeks Industrial training / Internship/ In-house Research Projects during previous vacation

	SEMESTER VIII											
Sl. No.	COURSE CODE	COURSE TITLE	CATEGORY	CONTACT PERIODS	L	Т	Р	С				
THEORY												
1		Professional Elective -VI	PE	3	3	0	0	3				
2		Open Elective – II	OE	3	3	0	0	3				
	PRACTICALS											
3	UEE2818	Project Phase II	EEC	16	0	0	16	8				
			TOTAL	22	6	0	16	14				

CATEGORY WISE LISTING OF SUBJECTS

BASIC SCIENCE COURSES (BS)

S.No	COURSE TITLE	SEMESTER	CONTACT PERIODS	L	Т	Р	EL	С
1	Matrices and Calculus	Ι	4	3	1	0	0	4
2	Engineering Physics	Ι	3	3	0	0	0	3
3	Engineering Chemistry	Ι	3	3	0	0	0	3
4	Physics and Chemistry Lab	Ι	3	0	0	3	0	1.5
5	Complex Functions and Laplace Transforms	II	4	3	1	0	0	4
6	Transform Techniques and Partial Differential Equation	III	4	3	1	0	0	4
7	Probability and Statistics for Electrical Engineering	IV	3	2	1	0	0	3
Total Credits								

ENGINEERING SCIENCE COURSES (ES)

S.No	COURSE TITLE	SEMESTER	CONTACT PERIODS	L	Т	Р	EL	С
1	Problem Solving and Programming in Python	Ι	3	3	0	0	0	3
2	Engineering Graphics	Ι	5	1	0	4	0	3
3	Programming in Python Lab	Ι	3	0	0	3	0	1.5
4	Basic Electrical and Electronics Engineering	Π	3	3	0	0	0	3
5	Electrical Circuits and Systems - Fundamentals and practices (TCP – Type a)	П	6	3	0	3	3	5.5
6	Design Thinking and Engineering Practices Lab	Π	3	0	0	3	0	1.5
7	Engineering Mechanics for Electrical Engineers	Π	3	3	0	0	0	3
8	Object Oriented Programming and Data Structures for Electrical Engineering	III	3	3	0	0	0	3
9	Object Oriented Programming and Data Structures Laboratory for Electrical Engineering	III	3	0	0	3	0	1.5
Total Credits								

Sl. No	COURSE TITLE	SEMESTER	CONTACT PERIODS	L	Т	Р	EL	С
1	Technical English	Ι	4	2	0	2	0	3
2	Humanities I-Elective	II	4	2	0	2	0	3
3	Humanities II -UHV: Understanding Harmony	III	4	2	0	2	0	3
4	Management –Elective	V	3	3	0	0	0	3
	Total Credits							

HUMANITIES AND SOCIAL SCIENCE COURSES (HS)

PROFESSIONAL CORE COURSES (PC)

SL. No	COURSE TITLE	SEMES TER	CONTACT PERIODS	L	Т	Р	EL	С
1	Signals and Systems	III	3	3	0	0	0	3
2	Electromagnetic Theory	III	3	2	1	0	0	3
3	Electronic Devices and Circuits	III	3	3	0	0	0	3
4	Electronics Lab	III	3	0	0	3	0	1.5
5	Electrical Machines -I	IV	3	3	0	0	0	3
6	Analog Electronic Circuits	IV	3	3	0	0	0	3
7	Control Systems Engineering	IV	3	3	0	0	0	3
8	Generation, Transmission and Distribution	IV	4	4	0	0	0	4
9	Electrical Machines -I Lab	IV	3	0	0	3	0	1.5
10	Analog Electronic Circuits Lab	IV	3	0	0	3	0	1.5
11	Power Electronics	V	3	3	0	0	0	3
12	Electrical Machines -II	V	3	3	0	0	0	3
13	Electrical Measurements and Instrumentation Systems	V	3	3	0	0		3
14	Digital Logic System Design and Practices (TCP – EFP)	V	4	3	0	1	3	4.5
15	Electrical Machines -II Lab	V	3	0	0	3	0	1.5
16	Control System and Instrumentation Lab	V	4	0	0	4	0	2
17	Microprocessors and Microcontrollers - Fundamentals and Practices (TCP -EFP)	VI	4	3	0	1	3	4.5
18	Power System Analysis	VI	3	3	0	0	0	3
19	Power System Operation and Control	VI	3	3	0	0	0	3
20	Power Electronics and Drives Lab	VI	4	0	0	4	0	2
21	Power System Simulation Lab	VI	3	0	0	3	0	1.5
22	Solid State Drives	VII	3	3	0	0	0	3
23	Protection and Switchgear	VII	3	3	0	0	0	3
24	High Voltage Engineering	VII	3	3	0	0	0	3
25	Advanced Electrical and Electronics Design Lab	VII	4	0	0	4	0	2
					To	tal Cr	edits	68.5

EMPLOYABILITY ENHANCEMENT COURSES (EEC)

Sl. No	COURSE TITLE	SEMESTER	CONTACT PERIODS	L	Т	Р	EL	С
1	Industrial Training /Internship	VII	0	0	0	0	0	2
2	Project Phase I	VII	6	0	0	6	0	3
3	Project Phase II	VIII	16	0	0	16	0	8
Total Credits								

MANDATORY COURSES (MC)

Sl. No	COURSE TITLE	SEMESTER	CONTACT PERIODS	L	Т	Р	EL	С
1	Environmental Science	Π	3	3	0	0	0	0
2	Indian Constitution	IV	4	2	0	2	0	0
					To	0		

PROFESSIONAL ELECTIVES (PE)

Sl. No	COURSE TITLE	SEMESTER	CONTACT PERIODS	L	Т	Р	EL	С
1	Professional Elective- I	V	3	3	0	0	0	3
2	Professional Elective- II	VI	3	3	0	0	0	3
3	Professional Elective -III	VI	3	3	0	0	0	3
4	Professional Elective- IV	VII	3	3	0	0	0	3
5	Professional Elective -V	VII	3	3	0	0	0	3
6	Professional Elective -VI	VIII	3	3	0	0	0	3
					To	18		

OPEN ELECTIVE (OE)

S.No	COURSE TITLE	SEMESTER	CONTACT PERIODS	L	Т	Р	EL	С
1	Open Elective I	VI	3	3	0	0	0	3
2	Open Elective – II	VIII	3	3	0	0	0	3
					Tot	al Cr	edits	6

SEMESTER	HS	BS	ES	РС	PE	OE	EEC	Total Credits (Sem Wise)
Ι	3	11.5	7.5					22
II	3	4	13					20
III	3	4	4.5	10.5				22
IV		3		16				19
V	3			17	3			23
VI				14	6	3		23
VII				11	6		5	22
VIII					3	3	8	14
Total Credits	12	22.5	25	68.5	18	6	13	165

SUMMARY OF CATEGORY WISE CREDITS

PROFESSIONAL ELECTIVES

Sl. No.	Course Code	Course Title	Specialization/ Domain	Contact Periods	L	Т	Р	С
		Professional Ele	ctive – I- Semeste	er V				
1	UEE2521	Solar Energy Systems	Renewable Energy Systems	3	3	0	0	3
2	UEE2522	Fundamentals of Digital Signal Processing	Control and Automation	3	3	0	0	3
3	UEE2523	Energy Resources and Utilization	Power Engineering	3	3	0	0	3
4	UEE2524	Communication Engineering	Electronic systems	3	3	0	0	3
5	UEE2525	Low Voltage Direct Current Systems	Power Electronics and Drives	3	3	0	0	3
		Professional Elec	tive - II - Semeste	er VI				
6	UEE2621	Wind Energy Conversion Systems	Renewable Energy Systems	3	3	0	0	3
7	UEE2622	Advanced Control Theory	Control and Automation	3	3	0	0	3
8	UEE2623	Power System Dynamics	Power Engineering	3	3	0	0	3
9	UEE2624	VLSI Design Techniques	Electronic Systems	3	3	0	0	3
10	UEE2625	Switched Mode Power Supplies	Power Electronics and Drives	3	3	0	0	3
		Professional Elect	ive - III - Semest	er VI				
11	UEE2626	Energy Storage Systems	Renewable Energy Systems	3	3	0	0	3
12	UEE2627	System Identification and Adaptive Control	Control and Automation	3	3	0	0	3
13	UEE2628	Artificial Intelligence for Power Systems	Power Engineering	3	3	0	0	3
14	UEE2629	Automotive Electronics	Electronic systems	3	3	0	0	3
15	UEE2631	Electrical Machine Design	Power Electronics and Drives	3	3	0	0	3

		Professional Elect	ive - IV - Semeste	er VII				
16	UEE2721	Smart Grid	Renewable Energy Systems	3	3	0	0	3
17	UEE2722	Principles of Robotics	Control and Automation	3	3	0	0	3
18	UEE2723	Internet of Things in Power System Engineering	Power Engineering	3	3	0	0	3
19	UEE2724	Power Semiconductor Devices	Electronic systems	3	3	0	0	3
20	UEE2725	Flexible AC Transmission Systems and Custom Power Devices	Power Electronics and Drives	3	3	0	0	3
		Professional Elect	ive - V - Semeste	r VII				
21	UEE2726	Distributed Generation and Micro grid	Renewable Energy Systems	3	3	0	0	3
22	UEE2727	PLC and SCADA	Control and Automation	3	3	0	0	3
23	UEE2728	Power System Transients	Power Engineering	3	3	0	0	3
24	UEE2729	Embedded Systems	Electronic systems	3	3	0	0	3
25	UEE2731	High Voltage Direct Current Transmission	Power Electronics and Drives	3	3	0	0	3
	1	Professional Electi	ve - VI - Semester	r VIII	1	T	1	
26	UEE2821	Electric Vehicles and Power Management	Renewable Energy Systems	3	3	0	0	3
27	UEE2822	Digital Control Systems	Control and Automation	3	3	0	0	3
28	UEE2823	Energy Management and Auditing	Power Engineering	3	3	0	0	3
29	UEE2824	Microcontroller Based System Design	Electronic systems	3	3	0	0	3
30	UEE2825	Power Quality	Power Electronics and Drives	3	3	0	0	3

SL. No.	COURSE CODE	COURSE TITLE	CONTACT PERIODS	L	Т	Р	С
1	UEN2241	Language and Communication	4	2	0	2	3
2	UEN2242	Fundamentals of Linguistics	4	2	0	2	3
3	UHS2243	Film Appreciation	4	2	0	2	3
4	UHS2241	Human Relations at Work	4	2	0	2	3
5	UHS2242	Application of Psychology in Everyday Life	4	2	0	2	3
6	UEN2243	Understanding Society and Culture Through Literature	4	2	0	2	3

HUMANITIES I - ELECTIVES (II SEMESTER)

MANAGEMENT ELECTIVE (V SEMESTER)

SL. No.	COURSE CODE	COURSE TITLE	CONTACT PERIODS	L	Т	Р	С
1	UBA2541	Principles of Management	3	3	0	0	3
2	UBA2542	Total Quality Management	3	3	0	0	3
3	UBA2543	Work Ethics, Corporate Social Responsibility and Governance	3	3	0	0	3

HONOURS DEGREE (Minimum 6 courses)

Specialization title: Artificial Intelligence and Machine Learning for Electrical Systems

Sl. No	Course Code	Course Title	Contact Periods	L	Т	Р	EL	С
1	UEE2H21	Principles of Artificial Intelligence	3	3	0	0	0	3
2	UEE2H22	Fundamentals of Machine Learning	3	3	0	0	0	3
3	UEE2H23	Fundamentals of Information Theory	3	3	0	0	0	3
4	UEE2H24	Big Data Analytics	3	3	0	0	0	3
5	UEE2H25	Application of Machine Learning and Deep Learning to Power System Problems	3	3	0	0	0	3
6	UEE2H26	Artificial Intelligence Application in Power Systems	3	3	0	0	0	3
7	UEE2H27	Introduction To Autonomous Mobile Robots	3	3	0	0	0	3
8	UEE2H28	Fundamentals of Deep Learning	3	3	0	0	0	3
9	UEE2H29	Foundations of Human Computer Interaction	3	3	0	0	0	3
10	UEE2H30	Fundamentals of Image Processing and Analysis	3	3	0	0	0	3

DETAILED SYLLABI

Semester I

Course Code	Course Title	L	Т	Р	С
UEN2176	TECHNICAL ENGLISH	2	0	2	3
Objectives:			E		
• To enhance of	competence in reading comprehension for Science and Tech	nolo	gy.		
• To improve t	he writing proficiency specific to proposals, reports, and let	tters.			
	peaking skills for technical presentations, GDs and public s				
• To strengthe	n the listening skills of the students to enable them to lister	n and	l con	npreh	nend
lectures and	talks.			-	
• To strengthe	n the grammatical competency.				
Unit I B	SASICS OF COMMUNICATION			ç)
Language deve	lopment: Subject verb Agreement, Tenses(simple), Conjun	ctior	ns, N	umer	rical
	adjective				
Vocabulary dev	velopment: Root words–Prefixes & Suffixes, Standard abbr	evia	tions	5,	
	mprehension of short technical texts-skimming and scannin				
-	scribing an object, the process of an event/experiment and o	-	s, Pa	ragra	aph
-	riting		,	U	1
	tening for taking notes and seeking clarifications (classroom	m leo	cture	s/	
6	ted talks etc)				
Speaking: Self	f-introduction and introducing others/short conversation	s in	for	mal	and
~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~	informal contexts				
Unit II N	AKING PRESENTATIONS			ç)
Language deve	lopment: The pronouns-antecedent agreement, Tenses-con-	tinuc	ous, l	ſſ	
	conditionals, Adverbs		,		
•	velopment: Collocations and fixed expressions, Avoidance		<u> </u>		
0	Comprehension of longer texts – (Interpretative and Critica	ıl lev	els c	of	
	meaning), Writing definitions (single contenes and outended). Europi		ار مر		
-	Writing definitions (single sentence and extended), Expositive Persuasive Essays,	lory	and		
	Listening Comprehension Tasks,				
	Making technical presentations				
	ISTENING TO SPEAK			ç)
Language deve	lopment: Prepositions, Tenses-perfect, Articles, Embedded	sen	tence	es,	
Vocabulary dev	velopment: Compound words, Formal and informal vocabu	lary,			
Reading: Read	ing reviews, advertisements, SOPs for higher studies	•			
_	ing instruction and recommendations, formal and informal	lette	rs/ e	mails	3,
-	ng SOPs				
	ening to longer technical talks and discussion				
	ionstrating working mechanisms				
	READING FOR SPEAKING			ç)
	elopment: Reported speech, Active and Passive voices, F	rami	ng '	Wh'	and
6	'Yes' or 'No' questions,		0	-	~
L	······································				

Vocabulary	development: Technical vocabulary, Verbal analogies,	
•		
Reading:	Reading industrial case studies, interpreting technical text and maki	ng notes
Writing:	Interpreting charts and graphs, writing blogs and vlogs	
Listening:	Listening to telephonic conversations and online interviews	
Speaking:	Participating in group discussions	
Unit V	PROFESSIONAL NEEDS	9
Language de		
-	development: Single-word substitutes, Vocabulary retention strateg	gies,
Reading:	Reading for IELTS, GER, TOEFL	
Writing:	Writing proposals and reports, writing minutes of the meeting,	
Listening:	Listening Skills for Proficiency Tests like IELTS	
Speaking:	Job Interviews (face to face and online) – basics	
	Total Periods	45
	comes: Upon successful completion of the course, students will be abl	e to
	ad and comprehend texts (technical) effectively.	
	rite proposals, reports, emails, letters, SOPs meeting professional expect	ctations.
	nprove Vocabulary (use of right collocations, idioms and phrases etc).	
	hance their grammatical competency for writing and speaking.	
	nprove their ability to listen and comprehend at deeper levels	
Text Books		
	en Sam, D., and Shoba N, A., Course in Technical English, Cambridge	2
	ersity Press, New Delhi, 2020.	
References		
	harshana, N.P., and Saveetha, C., English for Technical Commu	nication,
	nbridgeUniversity Press, New Delhi, 2016.	
2. Rama	in, Meenakshi, Sharma, and Sangeetha, Technical Communication F	rinciples
andP	actice, Oxford University Press, New Delhi, 2014.	
3. Kum	ar, Suresh, E., Engineering English, Orient Blackswan, Hyderabad, 20	15.
4. Boot	h L. Diana, Project Work, Oxford University Press, 2014.	
5. Grus	sendorf, Marion, English for Presentations, Oxford University Press, 2	.007.
6. Mea	ns, L. Thomas and Elaine Langlois, English & Communication For (Colleges,
Cen	gage Learning, USA, 2007	

COs	Pos											PSOs			
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
1	-	-	-	-	-	-	-	-	2	3	-	2			
2	-	-	-	-	-	-	-	-	2	3	-	2			
3	-	-	-	-	-	-	-	-	2	3	-	2			
4	-	-	-	-	-	-	-	-	2	3	-	2			
5	-	-	-	-	-	-	-	-	2	3	-	2			

Course	Course Title I		Т	Р	С
Code					
UMA2176	MATRICES AND CALCULUS 3		1	0	4
Objectives:					
• To red	uce quadratic form to canonical form of a matrix and identify	its	nati	ure	
• To ana	lyse the convergence of infinite series				
• To stue	dy the concept of evolute and envelope				
• To find	d the extreme values for a function of two variables				
• To con	npute area of closed surface and volume of solids using multip	le	inte	grals	
Unit I M	IATRICES			1	2
eigenvalues a Diagonalizatio	equation - Eigenvalues and Eigenvectors of a real matrix nd eigenvectors, Cayley-Hamilton Theorem – statement an on of matrices – Similarity transformation - Quadratic form - n to canonical form by orthogonal transformation – Nature of q	d Re	app educ	licati ction	ons, of a
Unit II S	EQUENCES AND SERIES			1	2
	Definition and examples, Series - Types of Convergence, Se	rie	s of	f pos	itive
-	of convergence - Comparison test, Integral test and D'Alemb			-	
Alternating se	eries – Leibnitz's test, Series of positive and negative terms	, <i>I</i>	Abso	olute	and
-					
conditional co	onvergence.				
conditional co Unit III A	Onvergence. APPLICATIONS OF DIFFERENTIAL CALCULUS			1	2
Unit III A	APPLICATIONS OF DIFFERENTIAL CALCULUS	tre	of		
Unit IIIACurvature, rad	0			curva	ture
Unit IIIACurvature, rad- Circle of	APPLICATIONS OF DIFFERENTIAL CALCULUS lius of curvature - Cartesianand parametric co-ordinates – Cen			curva	ture
Unit IIIACurvature, rad- Circle of curvature), Evolution	APPLICATIONS OF DIFFERENTIAL CALCULUS lius of curvature - Cartesianand parametric co-ordinates – Cen urvature in Cartesian form, Evolutes, Envelopes (including			curva baram	ture
Unit IIIACurvature, rad- Circle of crfamily), EvolutUnit IVFPartial derivatits properties	APPLICATIONS OF DIFFERENTIAL CALCULUS lius of curvature - Cartesianand parametric co-ordinates – Cen urvature in Cartesian form, Evolutes, Envelopes (including ite as envelope of normal.	tw – . an	Jaco	curva baram 1 obian	ture neter 2 and
Unit IIIACurvature, rad- Circle of curvature, radfamily), $EvolutionUnit IVFPartial derivations of two functions of two$	APPLICATIONS OF DIFFERENTIAL CALCULUS lius of curvature - Cartesian and parametric co-ordinates – Cen urvature in Cartesian form, Evolutes, Envelopes (including ute as envelope of normal. UNCTIONS OF SEVERAL VARIABLES ives – Total derivative – Differentiation of implicit functions – Taylor's series for functions of two variables – Maxima	tw – . an	Jaco	curva baram 1 bbian hinim	ture neter 2 and
Unit IIIACurvature, rad- Circle offamily), $E \vee U$ Unit IVFPartial derivations of twofunctions of twoUnit VNDouble integra	APPLICATIONS OF DIFFERENTIAL CALCULUS lius of curvature - Cartesianand parametric co-ordinates – Cen urvature in Cartesian form, Evolutes, Envelopes (including ite as envelope of normal. TUNCTIONS OF SEVERAL VARIABLES ives – Total derivative – Differentiation of implicit functions – Taylor's series for functions of two variables – Maxima wo variables – Lagrange's method of undetermined multipliers IULTIPLE INTEGRALS als in Cartesian and polar coordinates – Change of order of in lane curves – Change of variables in double integrals, Triple in	tw - : an iteş	Jaco Jaco d m grati gral	curva param bbian hinim 1 ion, 4 s.	ture neter 2 and a of 2 Area
Unit IIIACurvature, rad- Circle offamily), $E \vee U$ Unit IVFPartial derivations of twofunctions of twoUnit VNDouble integra	PPLICATIONS OF DIFFERENTIAL CALCULUS lius of curvature - Cartesianand parametric co-ordinates – Cen urvature in Cartesian form, Evolutes, Envelopes (including ite as envelope of normal. UNCTIONS OF SEVERAL VARIABLES tives – Total derivative – Differentiation of implicit functions – Taylor's series for functions of two variables – Maxima wo variables – Lagrange's method of undetermined multipliers JULTIPLE INTEGRALS als in Cartesian and polar coordinates – Change of order of in	tw - : an iteş	Jaco Jaco d m grati gral	curva param bbian hinim 1 ion, 4 s.	ture neter 2 and a of 2
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- 1. Grewal B.S, Higher Engineering Mathematics, Khanna Publishers, 44th Edition, 2018.
- 2. Erwin Kreyszig, Advanced Engineering Mathematics, John Wiley & Sons, Inc., 10th Edition, 2016.

References:

- 1. Bali N. P and Manish Goyal, "A Text book of Engineering Mathematics", Ninth Edition, Laxmi Publications Pvt Ltd., 2016.
- 2. James Stewart, Calculus: Early Transcendental, Cengage Learning, New Delhi, 7th Edition, 2013.
- 3. Dass, H.K., and Er. Rajnish Verma," Higher Engineering Mathematics", S. Chand Private Ltd., 2011.
- 4. Srimanta Pal and Subodh C. Bhunia, Engineering Mathematics, Oxford University Press, 2015.

COs	Pos												PSOs	
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1	3	2												
2	3	2												
3	3	2												
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5	3	2												
6	3	2										1		

Course	Course Title	L	Т	P	C				
Code									
UPH2176	ENGINEERING PHYSICS	3	0	0	3				
Objectives:									
Compre	nend and identify different crystal structures and their imperfe	ectio	ns.						
• Explain	the elastic and thermal properties of materials and understand	their	sigi	nifica	nce.				
 Develop 	an understanding of quantum mechanical phenomena and the	eir a	ppli	catio	ns.				
Provide	an overview of the characteristics of sound, architectural	acou	stics	s and	l the				
producti	on, detection and applications of ultrasound.								
• Explain	the origin of laser action, production of laser, fibre optics and	their	app	licati	ons.				
Unit I	CRYSTAL PHYSICS				9				

Single crystalline, polycrystalline and amorphous materials– single crystals - Lattice – Unit cell – Bravais lattice – Lattice planes – Miller indices – d spacing in cubic lattice – Calculation of number of atoms per unit cell – Atomic radius – Coordination number – Packing factor for SC, BCC, FCC and HCP structures – Diamond and graphite structures (qualitative treatment) - Crystal Imperfections – Point, line (Edge and Screw dislocations – Burger vectors) Surface (stacking faults) and Volume defects.

Unit II	PROPERTIES OF MATTER AND THERMAL PHYSICS 9
Properties	of matter: Elasticity- Hooke's law - Relationship between three moduli of
elasticity- s	stress -strain diagram- Poisson's ratio -Factors affecting elasticity- Torsional
stress & de	formations - Twisting couple - Torsion pendulum - theory and experiment-
bending of	beams-bending moment- cantilever: theory and experiment-uniform and non-
uniform ber	nding: theory and experiment-I-shaped girders.
Thermal P	hysics: Modes of heat transfer – thermal conduction, convection and radiation –
Newton's la	aw of cooling - thermal conductivity- Lee's disc method for bad conductor –
Radial heat	flow – Rubber tube method – conduction through compound media (series and
parallel) – H	Formation of ice on ponds.
Unit III	ACOUSTICS AND ULTRASONICS 9
Acoustics:	Classification and characteristics of Sound - decibel - Weber-Fechner law -
Sabine's for	rmula - derivation using growth and decay method —factors affecting acoustics
	s and their remedies - Methods of determination of Absorption Coefficient.
-	: Production of ultrasonics by Magnetostriction and piezoelectric methods –
	ating -Non Destructive Testing – pulse echo system through transmission and
-	nodes - A, B and C – scan displays.
Unit IV	QUANTUM PHYSICS 9
	radiation – Planck's theory (derivation) – Deduction of Wien's displacement law
•	gh – Jeans' Law from Planck's theory – Compton Effect. Theory and
-	al verification – Properties of Matter waves – wave particle duality -
-	r's wave equation – Time independent and time dependent equations – Physical
-	e of wave function – Particle in a one dimensional box and extension to three
-	1 box – Degeneracy of electron energy states - Scanning electron microscope -
	on electron microscope.
Unit V	PHOTONICS AND FIBRE OPTICS 9
	Spontaneous and stimulated emission- Population inversion -Einstein's A and B
	–Conditions for Laser action - Types of lasers – Nd: YAG, & CO2 lasers-Basics
	ers-Industrial and Medical Applications. Fibre optics: Principle and propagation
	ptical fibres – Numerical aperture and Acceptance angle - Types of optical fibres
-	efractive index, mode) –Losses in fibers - attenuation, dispersion, bending - Fibre
	mmunication system (Block diagram) - Active and passive fibre sensors
-	d displacement.
pressure and	Total Periods 45
Course Ou	tcomes: Upon successful completion of the course, students will be able to
	ze crystal structures and the influence of imperfections on their properties.
-	onstrate and explain the general concepts of elastic and thermal properties of
mater	
	in quantum mechanical theories to correlate with experimental results and their
-	cations to material diagnostics.
	ze the applications of acoustics and ultrasonics to engineering and medical
discip	
uiscip	

CO5: Elucidate the principle and working of lasers and optical fibers, and their applications in the field of industry, medicine and telecommunication.

Text Books:

- 1. Gaur, R.K., and Gupta, S.L., Engineering Physics, Dhanpat Rai Publishers, 2012.
- 2. Serway, R.A., & Jewett, J.W., Physics for Scientists and Engineers, Cengage Learning, 2010.

References:

- 1. Halliday, D., Resnick, R. & Walker, J. Principles of Physics, Wiley, 2015.
- 2. Tipler, P.A. & Mosca, G. Physics for Scientists and Engineers with Modern Physics, WH Freeman, 2007.
- 3. Avadhanulu, M. N., Kshirsagar, P. G, A text book of Engineering Physics, S. Chand & Co. Ltd., Ninth Revised Edition, 2012.

COs	POs												PSOs		
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3	3	2		1	1		2			2					
4	3	2		1	1		2			2					
5	3	2		1	1		2			2					

Course Code	Course Title	L	Т	Р	C
UCY2176	ENGINEERING CHEMISTRY	3	0	0	3

Objectives:

• To impart knowledge to the students on the basic concepts of chemistry and properties of materials for various engineering applications

9

9

Unit I ATOMIC AND MOLECULAR NANO CHEMISTRY

Atoms- Atomic orbitals, Molecules- Molecular orbitals. Nanoparticles and its uniqueness. Distinction between molecules, nanoparticles and bulk materials. Classification of nanoparticles. Size dependent Properties-Thermal, Optical, Chemical, Electronic and Mechanical. Synthesis of nanomaterials - bottom-up and top-down approaches-Techniques-Colloidal, hydrothermal, electrodeposition, chemical vapour deposition, laser ablation. Objectives of surface modification of nanoparticles.Synthesis and applications - Carbon Nano Tubes (CNT) - Gold nanoparticle

Unit II ELECTROCHEMISTRY

Conductivity of electrolytes - factors influencing conductivity- Conductometric titration and its applications -estimation of strong acid, estimation of mixture of strong and weak acids and estimation of BaCl₂. Electrochemical cell-redox reaction-origin of electrode potential, Types of electrodes, Measurement of electrode potential and emf of the electrochemical cell -reference electrode- saturated calomel electrode and Ag/AgCl electrode - Ion selective electrode-glass electrode measurement of pH –Potentiometric titrations- estimation of ferrous ion and estimation of strong acid. Problems based on all the above concepts.

Unit III	CORROSION AND ITS CONTROL	9
Corrosion-	Definition-Classification of corrosion-Chemical corrosion – Pilling –	Bedworth
rule – elect	rochemical corrosion – different types – galvanic corrosion – differentia	l aeration
corrosion -	- factors influencing corrosion - corrosion control - selection of m	aterials -
sacrificial a	anode and impressed current cathodic methods – corrosion inhibitors – J	protective
coatings -	paints - constituents and functions - metallic coatings - electroplating	(Au) and
electroless	(Ni) plating	
Unit IV	PHASE EQUILIBRIA	9
Phase Rule	- Definition and explanation of terms involved with suitable examples	- Phase -
	ts – Degrees of Freedom –Applications and limitations of Phase R	
	system - H ₂ O Two component systems – Construction of phase dis	
	nalysis (or) Cooling curves - Condensed Phase Rule - Simple eutectic	
	em – System with congruent melting point: Zn-Mg – System with ind	•
melting po		-
Unit V	SYNTHESIS AND APPLICATIONS OF INDUSTRIAL	9
	POLYMERS	
Polymers a	nd Polymerization: definition, classification - types of polymerization	: additior
•	sation – mechanism of addition polymerization (cationic, anionic, free ra	
	on polymerization)-Properties: Glass Transition temperature, Average N	
coordinatic	······································	
	l its determination by viscosity method. Polymer composites (fibre r	einforced
weight and	l its determination by viscosity method. Polymer composites (fibre r	
weight and plastics)-pr	reparation, properties and application of engineering plastics Epo	
weight and plastics)-pr	reparation, properties and application of engineering plastics Epo ns, Nylon 6:6, Polycarbonate, PS, PVC and PET	xy resin
weight and plastics)-pr	reparation, properties and application of engineering plastics Epo	
weight and plastics)-pr Polyuretha	reparation, properties and application of engineering plastics Epo ns, Nylon 6:6, Polycarbonate, PS, PVC and PET Total Periods	xy resin 45
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weight and plastics)-pr Polyuretha Course Ou demonstrat CO1: The CO2: The CO3: The their CO4: Cons CO5: The s	reparation, properties and application of engineering plastics Epons, Nylon 6:6, Polycarbonate, PS, PVC and PET Total Periods Itcomes: Upon successful completion of the course, students will be able understanding on: Unique properties of nano-particles and their applications principles of electrochemistry and its application for quantitative analys various types of corrosion under normal to severe corrosive environm control measures truction of phase diagram and its application to analyse simple eutectic synthesis, properties and applications of important industrial polymers	xy resin 45 le to sis nents and
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weight and plastics)-pr Polyuretha Course Ou demonstrat CO1: The CO2: The CO3: The their CO4: Cons CO5: The S CO5: The S CO5: The S	reparation, properties and application of engineering plastics Epo ns, Nylon 6:6, Polycarbonate, PS, PVC and PET Total Periods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiods Interiod	xy resin 45 le to iss nents and systems ng chnology

COs	POs													Os
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	3	2	1											
2	3	2	1											
3	3	2	1											
4	3	2	1											
5	3	2	1											

	Course Title	L	Т	Р	С							
Code												
UGE2176 PROBLEM SOI	LVING AND PROGRAMMING IN	3	0	0	3							
	PYTHON											
Objectives:												
• To learn algorithmic probl	em solving techniques.											
• To learn the fundamentals	of python programming.											
• To compose programs in I	Python using conditions, iterations and de	econ	npos	e a								
problem into functions			-									
• To construct programs in I	Python sequenced data type.											
• To develop python progra	ms using advanced constructs like diction	narie	es an	d file	es							
Unit I ALGORITHMIC P	ROBLEM SOLVING			Ģ)							
Logical and Algorithmic Thinki	ng: Logical Thinking – Algorithmic Th	nink	ing;	Prob	lem							
	Defining the Problem – Devising											
	g blocks: Basic Algorithmic Constructs (p	oseu	do co	ode, f	flow							
chart, programming language) - H												
Unit II DATA, EXPRESSI	ON, STATEMENT, CONDITIONAL			Ģ)							
Data and types: int, float, bc	olean, string, list; variables, expression	ions	, sta	ateme	ents,							
e 1	dence of operators; comments; in-bu			ules	and							
functions: Conditional: boolean y	values and operators, conditional (if), alt	erna	4									
	1	CIIIU	uive	(if-e								
case analysis (if-elif-else).			uive		lse)							
case analysis (if-elif-else).Unit IIIITERATION, FUN	CTION, STRINGS			ļ	lse),)							
case analysis (if-elif-else).Unit IIIITERATION, FUNIteration: while, for, break, contin	CTION, STRINGS ue, pass; Functions: function definition, f	unct	tion	g call, f	lse)) flow							
case analysis (if-elif-else).Unit IIIITERATION, FUNIteration: while, for, break, contin of execution, parameters and arg	CTION, STRINGS ue, pass; Functions: function definition, f uments, return values, local and global	unct scop	tion o	g call, f	lse) J flow							
case analysis (if-elif-else).Unit IIIITERATION, FUNIteration: while, for, break, contin of execution, parameters and arg Strings: string slices, immutability	CTION, STRINGS ue, pass; Functions: function definition, f	unct scop	tion o	call, f	lse)) flow ion;							
case analysis (if-elif-else).Unit IIIITERATION, FUNIteration: while, for, break, contin of execution, parameters and arg Strings: string slices, immutabilityUnit IVLISTS, TUPLES	CTION, STRINGS ue, pass; Functions: function definition, f uments, return values, local and global y, string functions and methods, string m	unct scoj odul	ion o pe, r le.	call, f ecurs	lse)) flow sion							
case analysis (if-elif-else).Unit IIIITERATION, FUNIteration: while, for, break, contine of execution, parameters and arg Strings: strip slices, immutabilityUnit IVLISTS, TUPLESLists: list operations, list slices, list	CTION, STRINGS ue, pass; Functions: function definition, f uments, return values, local and global y, string functions and methods, string m st methods, list loop, mutability, aliasing,	unct scop odul	ion o pe, r le. ning	call, f ecurs	lse) flow flow flow flow flow flow							
case analysis (if-elif-else).Unit IIIITERATION, FUNIteration: while, for, break, contine of execution, parameters and arg Strings: strip slices, immutabilityUnit IVLISTS, TUPLESLists: list operations, list slices, list	CTION, STRINGS ue, pass; Functions: function definition, f uments, return values, local and global y, string functions and methods, string m	unct scop odul	ion o pe, r le. ning	call, f ecurs	lse) flow flow flow flow flow flow							
case analysis (if-elif-else).Unit IIIITERATION, FUNIteration: while, for, break, contine of execution, parameters and arg Strings: strip slices, immutabilityUnit IVLISTS, TUPLESLists: list operations, list slices, list	CTION, STRINGS ue, pass; Functions: function definition, f uments, return values, local and global y, string functions and methods, string m st methods, list loop, mutability, aliasing,	unct scop odul	ion o pe, r le. ning	call, f ecurs	lse)) flow flow ion;) , list							
case analysis (if-elif-else).Unit IIIITERATION, FUNIteration: while, for, break, contin of execution, parameters and arg Strings: string slices, immutabilityUnit IVLISTS, TUPLESLists: list operations, list slices, list parameters, nested lists, list comp	CTION, STRINGS ue, pass; Functions: function definition, f uments, return values, local and global y, string functions and methods, string m st methods, list loop, mutability, aliasing, rehension; Tuples: tuple assignment, tupl	unct scop odul	ion o pe, r le. ning	call, f ecurs	lse), flow ion; , list ilue,							
case analysis (if-elif-else).Unit IIIITERATION, FUNIteration: while, for, break, contine of execution, parameters and arg Strings: string slices, immutabilityUnit IVLISTS, TUPLESLists: list operations, list slices, list parameters, nested lists, list comp tuple operations.Unit VDICTIONARIES, HDictionaries: operations and meth	CTION, STRINGS ue, pass; Functions: function definition, f uments, return values, local and global y, string functions and methods, string m st methods, list loop, mutability, aliasing, rehension; Tuples: tuple assignment, tupl	funct scop odul , clo le as	ion ope, r be, r le. ning retu	call, f ecurs lists urn va	lse), flow ion; , list , list nries							

Course Outcomes: Upon successful completion of the course, students will be able to									
CO1: Solve programming problems and express solutions in pseudo code.									
CO2: Develop simple programs using basic constructs.									
CO3: Construct programs using conditions and iterations decompose a problem into									
functions.									
CO4: Make use of strings, lists, tuples and dictionaries data structures.									

CO5: Perform Input/Output Operations using files.

Text Books:

- 1. Karl Beecher, ``Computational Thinking A beginner's Guide to Problem Solving and Programming", British Computer Society (BCS), 2017.
- 2. Allen B. Downey, ``Think Python: How to Think Like a Computer Scientist", 2nd edition, Green Tea Press, Shroff/O'Reilly Publishers, 2015 (http://greenteapress.com/wp/think-python/)

References:

- John V Guttag, ``Introduction to Computation and Programming Using Python", 3rd edition, MIT Press, 2021.
- 2. Ashok NamdevKamthane, Amit Ashok Kamthane, ``Programming and Problem Solving with Python", McGraw Hill Education (India) Private Limited, 2018.
- Robert Sedgewick, Kevin Wayne, Robert Dondero, ``Introduction to Programming in Python: An Inter-disciplinary Approach", Pearson India Education Services Pvt. Ltd., 2016.
- 4. Timothy A. Budd, ``Exploring Python", Mc-Graw Hill Education (India) Private Ltd., 2015.
- 5. Kenneth A. Lambert, ``Fundamentals of Python: First Programs'', 2nd Edition, CENGAGE Learning, 2018.

COs		POs											PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	
1	2	1	0	0											
2	2	2	0	0											
3	2	3	2	1											
4	2	3	2	1											
5	2	2	2	1											

Course	Course Title	L	Т	Р	С						
Code											
UGE2177	UGE2177 ENGINEERING GRAPHICS										
Objectives:											
• To dev	velop the graphic skills for communication of concepts, idea	s and	d des	sign c	of						
engine	engineering products.										
• To exp	pose them to existing national standards related to technical	draw	vings	•							

	Concepts and Conventions (Not for Examinations)	
Importance	of graphics in engineering applications – Use of drafting instruments –	BIS
conventions	and specifications - Size, layout and folding of drawing sheets - Lette	ring and
dimensionin	Ig	
Unit I	PLANE CURVES AND FREEHAND SKETCHING	10
	metrical constructions, Curves used in engineering practices: C	
	n of ellipse, parabola and hyperbola by eccentricity method – Dra	0
-	d normal to the above curves. Visualization concepts and Free Hand shares are principles. Representation of Three Dimensional chiests. I event	-
	n principles –Representation of Three-Dimensional objects – Layout of etching of multiple views from pictorial views of objects.	of views-
Unit II	PROJECTION OF POINTS, LINES AND PLANE SURFACE	15
	c projection principles - Principal planes - First angle projection - L	
	pjection of points. Projection of straight lines (only First angle pro-	•
	both the principal planes - Determination of true lengths and true incline	
	e method and traces. Projection of planes (polygonal and circular	-
-	both the principal planes by rotating object method.	,
Unit III	PROJECTION OF SOLIDS	15
Projection o	f simple solids like prisms, pyramids, cylinder, cone and truncated sol	ids when
	inclined to one of the principal planes by rotating object method.	
Unit IV	SECTION OF SOLIDS AND DEVELOPMENT OF SURFACES	20
Sectioning of	of above solids in simple vertical position when the cutting plane is in	clined to
-	the principal planes and perpendicular to the other – obtaining true	
section. Dev	velopment of lateral surfaces of truncated solids (simple position only)	– Prisms,
pyramids, c	ylinders and cones.	
Unit V	ISOMETRIC AND PERSPECTIVE PROJECTION	15
Principles o	f isometric projection - isometric scale - Isometric projections of simple	ole solids
and truncate	ed solids - Prisms, pyramids, cylinders, cones- combination of two soli	d objects
in simple ve	ertical positions. Perspective projection of simple solids- Prisms, pyrat	mids and
cylinders by	visual ray method.	
	Total Periods	75
	tcomes: Upon successful completion of the course, students will be abl	
	Plane curves and perform Free hand sketching of three - dimensional of	bjects
	the Orthographic projections of points, lines and plane surfaces.	
	the Projections of solids.	
	the Projections of sectioned solids and Development of surfaces.	
	the Isometric and Perspective projections of solids.	
Text Books		
	jan, K.V., A Textbook of Engineering Graphics, Dhanalakshmi Pu	ıblishers,
	ai, 33rd Edition, 2020. [ISBN:9788190414089]	
-	opal, K. and Prabhu Raja, V., Engineering Graphics, New Age Internat d, 15th Edition, 2018. [ISBN :9789386649249]	tional (P)
References	5:	

- 1. Bhatt, N.D., Engineering Drawing, Charotar Publishing House, 53rd Edition, 2014. [ISBN: 9789380358963]
- 2. Basant Agarwal, and Agarwal, C.M., Engineering Drawing, McGraw Hill, 3rd Edition, 2019. [ISBN: 9789353167448]
- 3. Gopalakrishna, K.R., Engineering Drawing (Vol. I & II Combined), Subhas Publications, 27th Edition, 2017. [ISBN: 9789383214235]
- 4. Luzzader J Warren, and Jon M Duff, Fundamentals of Engineering Drawing with an introduction to Interactive Computer Graphics for Design and Production, Pearson Education, 11th Edition, 2005. [ISBN :9789332549982]

Publication of Bureau of Indian Standards

1. IS 10711 – 2001: Technical products Documentation – Size and lay out of drawing sheets.

2. IS 9609 (Parts 0 & 1) – 2001: Technical products Documentation – Lettering.

3. IS 10714 (Part 20) – 2001 & SP 46 – 2003: Lines for technical drawings.

4. IS 11669 – 1986 & SP 46 – 2003: Dimensioning of Technical Drawings.

5. 15021 (Parts 1 to 4) – 2001: Technical drawings – Projection Methods.

COs	POs													PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3	
1	3	2	2	-	-	2	-	-	-	3	-	-				
2	3	2	2	-	-	2	-	-	-	3	-	-				
3	3	2	2	-	-	2	-	-	-	3	-	-				
4	3	2	2	-	-	2		-	-	3	-	-				
5	3	2	2	-	-	2	-	-	-	3	-	-				

Course Code	Course Title	L	Т	Р	C
UGE2197	PROGRAMMING IN PYTHON LAB	0	0	3	1.5
Objectives					

Objectives:

- To write, test, and debug simple Python programs.
- To apply conditions and loops to solve problems using python.
- To implement programs using functions
- To write programs using different data types such as strings, lists tuples and dictionaries
- To perform read and write operations into the files.

List of Experiments:

- 1. Use Linux shell commands, use Python in interactive mode, and an editor
- 2. Write simple programs (area of a geometric shape, simple interest, solve quadratic equation, net salary).
- 3. Write programs using conditional statements (leap year, maximum of 2 numbers,

maximum of 3 numbers, simple calculator, grade of the total mark).

- 4. Develop programs using loops and nested loops (gcd, prime number, integer division, sum of digits of an integer, multiplication table, sum of a series, print patterns, square root using Newton's method).
- 5. Develop programs using functions (sine and cosine series, Pythagorean triplets).
- 6. Develop programs using recursion (efficient power of a number, factorial, Fibonacci number).
- 7. Develop programs using strings (palindrome, finding substring) without using inbuilt functions.
- 8. Develop programs using lists and tuples (linear search, binary search, selection sort, insertion sort, quicksort).
- 9. Develop programs using nested lists (matrix manipulations).
- 10. Develop simple programs using dictionaries (frequency histogram, nested dictionary).
- 11. Develop programs using Files (read and write files).
- 12. Develop programs to perform any task by reading arguments from command line.
- 13. Implement a simple application using appropriate datatypes and files

Total Periods: 45

Course Outcomes: Upon successful completion of the course, students will be able to

CO1: Write, test, and debug simple Python programs

CO2: Build Python programs with conditionals and loops

CO3: Solve a problem using functions in python programming

CO4: Construct python programs using compound data like lists, tuples, and dictionaries

CO5: Build a simple application in teams using files and appropriate datatypes by applying the best programming practices

References:

1.Karl Beecher, ``Computational Thinking – A beginner's Guide to Problem Solving and Programming'', British Computer Society (BCS), 2017.

2.Allen B. Downey, ``Think Python: How to Think Like a Computer Scientist", 2nd edition, Green Tea Press, Shroff/O'Reilly Publishers, 2015

(http://greenteapress.com/wp/think-python/)

COs	POs													s
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	2	2	0	0	-	-	-	1	-	-	-	-		
2	3	3	0	1	-	-	-	1	-	-	-	-		
3	3	3	0	1	-	-	-	1	-	-	-	-		
4	3	3	0	1	-	-	-	1	-	-	-	-		
5	3	3	0	2	-	-	-	1	3	2	-	-		

Course	Course Title	L	Т	Р	С
Code					
UGS2197	PHYSICS AND CHEMISTRY LABORATORY	0	0	3	1.5

A. PHYSICS LABORATORY

COURSE OBJECTIVE:

The objective of this course is to enable the students to

• Obtain basic Knowledge about physics concepts applied in optics, thermal physics and properties of matter.

LIST OF EXPERIMENTS

(A minimum of 5 experiments to be performed from the given list)

- 1. Determination of the Young's modulus of the material of the given beam by Non-uniform bending method.
- 2. Determination of the rigidity modulus of the material of the given wire using torsion pendulum.
- 3. Determination of the wavelength of the mercury spectra using Spectrometer and grating.
- 4. Determination of the dispersive power of a prism using Spectrometer.
- 5. Determination of the grating element/wavelength, and particle size/ wavelength using a laser.
- 6. Determination of the Numerical and the acceptance angle of an optical fiber.
- 7. Determination of the thickness of a thin wire using interference fringes.
- 8. Determination of the coefficient of viscosity of the given liquid using Poiseuille's method.
- 9. Determination of the band gap energy of a semiconductor.
- 10. Determination of the coefficient of thermal conductivity of the given bad conductor using Lee's disc.

COURSE OUTCOMES

Upon successful completion of the course, students will be able to CO1: Apply principles of elasticity, optics, viscosity, thermal and band gap determination for engineering applications

CO-PO/PSO MAPPING

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3			2	1										

B. <u>CHEMISTRY LABORATORY</u>

COURSE OBJECTIVE:

The objective of this course is to enable the student to impart hands on training for all the possible concepts learned in Engineering Chemistry Course

LIST OF EXPERIMENTS

(A minimum of 6 experiments to be performed from the given list)

- 1. Estimation of ferrous ion by potentiometric titration
- 2. Estimation of strong acid using pH meter.
- 3. Estimation of strong acid by conductometric titration
- 4. Estimation of mixture of strong and weak acids using conductometer
- 5. Estimation of BaCl₂ by conductometric titration
- 6. Determination of degree of polymerization of a water-soluble polymer by Viscosity method
- 7. Determination of equivalent conductance of a strong electrolyte at infinite dilution
- 8. Determination of weak acid using weak base by conductometric titration.
- 9. Determination of rate of corrosion by weight loss method

TOTAL PERIODS: 45

TEXT BOOK

1. Manual Prepared by Faculty of Chemistry and Physics Department, SSNCE

REFERENCES

1. Practical Physical Chemistry, B. Viswanath and P.S.Raghavan, ViVa Books VT.Ltd, New Delhi, 2012.

COURSE OUTCOMES

- Upon successful completion of the course, students will be able to
- CO1: Analyse ions like Fe2+, Fe3+, H+ using different instruments
- CO2: Determine the Molecular weight and Degree of Polymerisation using viscometer

CO-PO/PSO MAPPING

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3												1		2
CO2	3												1		2

Semester II

Course Code	Course Title	L	Т	Р	C
Coue	COMPLEX FUNCTIONS AND LAPLACE				
UMA2276	TRANSFORMS	3	1	0	4
Objectives:	TRAUST OR WIS				L
-	ing C-R equations in the construction of Analytic Functions.				
	the methods of Complex Integration, finding Taylor's and		irent	's Se	ories
• study expans				. 5 50	/105
-	the Laplace Transforms and inverse transforms for standard f	unct	ions		
	Differential Equations using different techniques.	unet	10113	•	
	te Line, Surface and Volume integrals.				
	NALYTIC FUNCTIONS			1	2
	ctions – necessary and sufficient conditions, Cauchy-Riem	ann	0011		
•	polar form (with proof) – Properties - harmonic functions		-		
	ion, conformal mapping - some standard transformations	-v	v = 1	z + c	, <i>CZ</i> ,
$\frac{1}{z}$, z^2 , bilinear	transformation.				
Unit II C	COMPLEX INTEGRATION			1	2
Line integral	- Cauchy's integral theorem - Cauchy's integral formu	ıla,	Tayl	or's	and
Laurent's seri	es, Singularities - Residues - Residue theorem - Applie	catio	on o	f res	idue
theorem for ev	valuation of real integrals - Use of circular contour and sen	nicir	cula	r con	tour
(except the po	les on the real axis).				
Unit III L	APLACE TRANSFORMS			1	2
Definition, pr	roperties, existence conditions - Transforms of elemen	tary	fur	ction	ıs —
Transform of	unit step function and unit impulse function, shifting theorem	ns, T	Frans	sform	is of
derivatives an	nd integrals, Initial and final value theorems, Periodic f	unct	ions	, Inv	erse
transforms – C	Convolution theorem.				
Unit IV C	ORDINARY DIFFERENTIAL EQUATIONS			1	2
Solution of se	cond and higher order linear differential equation with con	istar	t co	effici	ents
$(f(x) = e^{mx})$	$sinmx, cosmx, x^n, f(x)e^{mx}, f(x)sinmx)$, Method of	v	aria	tion	of
	multaneous linear equations with constant coefficients of fi	rst c	order	, Sol	ving
linear second	order ordinary differential equations with constant coefficie	nts ı	ising	g Lap	lace
transforms.			-	-	
Unit V V	VECTOR CALCULUS			1	2
	directional derivative – Divergence and curl – Vector identi	ities	– Irı	otati	onal
	l vector fields, Line integral over a plane curve, Surface int				
	e, Volume integral, Green's, Gauss divergence and Sto	U			
	nd application in evaluating line, surface and volume integra				
	Total F		ods	6	0
Course Outco	omes: Upon successful completion of the course, students w	ill b	e abl	e to	

CO1: Solve problems in Analytic functions and construction of analytic functions using C-
R equations.

CO2: Solve problems using integration techniques, find Taylor's and Laurent's Series expansions.

CO3: Obtain the Laplace Transforms and inverse transforms of standard functions.

CO4: Solve Differential Equations using different techniques.

CO5: Evaluate Line, Surface and Volume integrals.

CO6: application of Complex integration, Laplace transforms, Ordinary differential equations, and vector calculus in engineering problems

Text Books:

- 1. Grewal, B.S., Higher Engineering Mathematics, 44th Edition, Khanna Publishers, 2018.
- 2. Erwin Kreyszig, Advanced Engineering Mathematics, 10th Edition, John Wiley & Sons, Inc., 2016.

- 1. Bali, N.P., Goyal, M., Watkins, C., Advanced Engineering Mathematics, Laxmi Publications Pvt. Limited, 2007.
- 2. Boyce, W.E., and DiPrima, R.C., Elementary Differential Equations and Boundary Value Problems, 11th Edition, Global Edition, Wiley, 2017.
- 3. George B. Thomas Jr., Maurice D. Weir, Joel R. Hass, Thomas' Calculus: Early Transcendental, 13th Edition, Pearson Education, 2014.
- 4. O'Neil. P. V., Advanced Engineering Mathematics, 7th Edition, Cengage Learning India Pvt., Ltd, New Delhi, 2012.
- 5. Howard Anton, Irl C. Bivens, Stephen Davis, Calculus Early Transcendentals, 11th Edition, Global Edition, John Wiley & Sons, Inc., 2017.
- 6. Srimanta Pal and Subodh C. Bhunia, Engineering Mathematics, Oxford University Press, 2015.
- 7. Srivastava, A.C., and Srivastava, P.K., Engineering Mathematics Volume I and II, PHI learning Pvt. Ltd, 2011.

COs								Pos					PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	
1	3	2													
2	3	2													
3	3	2													
4	3	2													
5	3	2													
6	3	2												1	

CodeImage: CodeUEE2276BASIC ELECTRICAL AND ELECTRONICS ENGINEERING300Objectives:•To learn the basic concepts of electric circuits.•To know the operation of various electrical machines.•To study the concepts of utilization of electrical power.•To comprehend the working principle of electronic devices and its application	3
 To learn the basic concepts of electric circuits. To know the operation of various electrical machines. To study the concepts of utilization of electrical power. To comprehend the working principle of electronic devices and its application 	
 To learn the basic concepts of electric circuits. To know the operation of various electrical machines. To study the concepts of utilization of electrical power. To comprehend the working principle of electronic devices and its application 	
 To know the operation of various electrical machines. To study the concepts of utilization of electrical power. To comprehend the working principle of electronic devices and its application 	
 To study the concepts of utilization of electrical power. To comprehend the working principle of electronic devices and its application 	
• To comprehend the working principle of electronic devices and its application	
	18.
• To grasp the working principle of various sensors and transducers.	
Unit I ELECTRICAL CIRCUITS	9
DC Circuits: Ohm's Law- Kirchhoff's laws - Mesh current and Node voltage m	ethods
(Analysis with only independent source). Network theorems - Superposition the Thevenins theorem and Norton theorem. AC circuit: Waveforms and RMS value, I diagram, Power, Power factor. Three phase supply – Star connection, Delta connec Balanced Loads - Power in three-phase systems.	Phasor
Unit II ELECTRICAL MACHINES	9
Construction, Principle of Operation, Basic Equations and Applications - DC Gene DC Motors, Single Phase Transformer, Single phase Induction Motor, Three phase Ind Motor, Three phase Alternator, Stepper and BLDC motors. Unit III UTILIZATION OF ELECTRICAL POWER Renewable energy sources- wind and Solar panels. Illumination by lamps- Sodium V	luction 9 Yapour,
Mercury vapour, Fluorescent tube. Batteries-NiCd, Pb Acid and Li ion Charge and Disc Characteristics. Protection- Earthing, Fuses. Energy Tariff calculation for domestic lo	U
Unit IV ELECTRONIC DEVICES AND APPLICATIONS	9
Operation of PN junction diodes, VI characteristics, Zener diode, BJT- CB, Cl configurations, input and output characteristics, MOSFET. Half wave and full wave recapacitive filters, zener voltage regulator, Operational amplifiers, Ideal Op characteristics, Inverting and Non-inverting amplifier.	ctifier,
Unit V SENSORS AND TRANSDUCERS	9
Sensors: Capacitive and resistive sensors, magnetic sensors, Hall effect sensors, resistive sensors, viscosity, optical sensors, Ultrasonic sensors, Nuclear and microsen Transducers: Classification of transducers, strain gauges, RTD, thermocouples, electric, LVDT and Thermo electric transducers	isors.
Total Periods	45
	<i>-</i> Ј
Course Outcomes: Upon successful completion of the course, students will be able t	0
CO1: Analyze DC and AC circuits.	
CO2: Explain the operating principle of AC and DC machines.	
CO3: Describe the utilization of electric power.	

CO4: Describe the working principle of electronic devices and its applications

CO5: Describe the working principle of sensors and transducers.

Text Books:

- Kothari DP and I.J Nagrath, "Basic Electrical and Electronics Engineering", McGraw Hill Education, 2014
- 2. Alan S. Moris, Principles of Measurements and Instruments, Prentice Hall of India Pvt. Ltd., New Delhi,1999.
- 3. S.Salivahanan, R.Rengaraj and G.R.Venkatakrishnan, Basic Electrical, Electronics and Measurement Engineering, McGrawHill, 2017.

References:

- 1. S.B. Lal Seksena and Kaustuv Dasgupta, Fundaments of Electrical Engineering, Cambridge, 2016.
- 2. M.S. Sukhija and T.K. Nagsarkar, Basic Electrical and Electronic Engineering, Oxford, 2016.
- 3. S.K.Sahdev, Basic of Electrical Engineering, Pearson, 2015.
- 4. Edward Hughes, John Hiley, Keith Brown and Ian McKenzie Smith "Electrical And Electronic Technology" Pearson Education Ltd, 10 th Edition, 2008
- 5. H.Cotton, "Electrical Technology" 7th Edition, CBS; 2005

COs													PSOs		
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Course Code	Course Title	L	Т	Р	EL	C
UEE2201	ELECTRICAL CIRCUITS AND SYSTEMS - FUNDAMENTALS AND PRACTICES	3	0	3	3	5.5

Objectives:

- To introduce the elements of electric circuits and perform analysis using governing laws
- To impart knowledge on solving electric circuits using network reduction methods and theorems

• To introduce the phenomenon of resonance in electric circuits and to introduce coupled circuits.

• To impart knowledge on transient response of circuits and two port networks.

• To introduce the concept of Phasor diagrams and perform analysis of three phase circuits

Unit I	BASIC CIRCUIT ANALYSIS	12+6
Theory - I	Resistive, Inductive and Capacitive elements - Ohm's Law Resistor	s in series and
parallel cir	cuits - Kirchoffs laws - Mesh current and node voltage - methods of	analysis- A.C
circuits – l	Phasors - Average and RMS value - Phasor Diagram - Power, Pow	wer Factor and
Energy.		
Practice -	Simulation of electrical circuit using Kirchhoff's voltage and curre	ent laws using
MATLAB	/ Simulink	
Studio -En	ergy auditing of department building and cost analysis in implementir	ng solar power
Design and	l analysis of series and parallel circuits with residential lamp loads.	
Unit II	NETWORK REDUCTION & THEOREMS FOR DC & AC	12+6
	CIRCUITS	
Theory - N	Network reduction: voltage and current division, source transformati	ion – star delta
·	. Thevenin and Norton Theorems – Superposition Theorem – Ma	
	eorem – Reciprocity Theorem – Millman's theorem.	Ĩ
	Verification of Thevenin's theorem, Norton's theorem, Maximum	power transfe
	uperposition theorem by Simulation of electrical circuits using MATL	
	Iaximum Power Point Tracking using solar panel-Impedance matchi	
		0 0
amplifter.		
Unit III Theory - Bandwidth	RESONANCE AND COUPLED CIRCUITS Series and parallel resonance – their frequency response – Qual - Self and mutual inductance – Coefficient of coupling – Tuned ci	-
Bandwidth tuned circu Practice - MATLAB	Series and parallel resonance – their frequency response – Qual - Self and mutual inductance – Coefficient of coupling – Tuned ci its. Simulation of series resonance circuit-Simulation of parallel resonan / Simulink.	lity factor and rcuits – Single
Unit III Theory - Bandwidth tuned circu Practice - MATLAB Studio - A	Series and parallel resonance – their frequency response – Qual - Self and mutual inductance – Coefficient of coupling – Tuned ci its. Simulation of series resonance circuit-Simulation of parallel resonan / Simulink. nalysis of tuned radio receiver circuit.	lity factor and rcuits – Single t circuits using
Unit III Theory - Bandwidth tuned circu Practice - MATLAB	 Series and parallel resonance – their frequency response – Qual Self and mutual inductance – Coefficient of coupling – Tuned ci Simulation of series resonance circuit-Simulation of parallel resonan / Simulink. nalysis of tuned radio receiver circuit. TRANSIENT RESPONSE ANALYSIS AND TWO PORT 	lity factor and rcuits – Single
Unit III Theory - Bandwidth tuned circu Practice - MATLAB Studio - A Unit IV	Series and parallel resonance – their frequency response – Qual - Self and mutual inductance – Coefficient of coupling – Tuned ci its. Simulation of series resonance circuit-Simulation of parallel resonan / Simulink. nalysis of tuned radio receiver circuit. TRANSIENT RESPONSE ANALYSIS AND TWO PORT NETWORKS	lity factor and rcuits – Single t circuits using 12+6
Unit III Theory - Bandwidth tuned circu Practice - MATLAB Studio - A Unit IV Theory - T	Series and parallel resonance – their frequency response – Qual - Self and mutual inductance – Coefficient of coupling – Tuned ci its. Simulation of series resonance circuit-Simulation of parallel resonan / Simulink. nalysis of tuned radio receiver circuit. TRANSIENT RESPONSE ANALYSIS AND TWO PORT NETWORKS Transient response of RL, RC and RLC Circuits using Laplace transform	lity factor and rcuits – Single t circuits using 12+6 m for DC inpu
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Unit III Theory - Bandwidth tuned circu Practice - MATLAB Studio - A Unit IV Theory - T and A.C. parameters	Series and parallel resonance – their frequency response – Qual - Self and mutual inductance – Coefficient of coupling – Tuned ci its. Simulation of series resonance circuit-Simulation of parallel resonan / Simulink. nalysis of tuned radio receiver circuit. TRANSIENT RESPONSE ANALYSIS AND TWO PORT NETWORKS Transient response of RL, RC and RLC Circuits using Laplace transform sinusoidal input-Characterization of two port networks in terms of	lity factor and rcuits – Single t circuits using 12+6 m for DC inpu of Z,Y and F
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Unit III Theory - Bandwidth tuned circu Practice - MATLAB Studio - A Unit IV Theory - T and A.C. parameters Practice -	Series and parallel resonance – their frequency response – Qual - Self and mutual inductance – Coefficient of coupling – Tuned ci its. Simulation of series resonance circuit-Simulation of parallel resonan / Simulink. nalysis of tuned radio receiver circuit. TRANSIENT RESPONSE ANALYSIS AND TWO PORT NETWORKS Transient response of RL, RC and RLC Circuits using Laplace transform sinusoidal input-Characterization of two port networks in terms of	lity factor and rcuits – Single t circuits using 12+6 m for DC inpu of Z,Y and F
Unit III Theory - Bandwidth tuned circu Practice - MATLAB Studio - A Unit IV Theory - T and A.C. parameters Practice - Studio - D Unit V	Series and parallel resonance – their frequency response – Qual - Self and mutual inductance – Coefficient of coupling – Tuned ci its. Simulation of series resonance circuit-Simulation of parallel resonan / Simulink. nalysis of tuned radio receiver circuit. TRANSIENT RESPONSE ANALYSIS AND TWO PORT NETWORKS 'ransient response of RL, RC and RLC Circuits using Laplace transform sinusoidal input-Characterization of two port networks in terms of Simulation of R-C electric circuit transients using MATLAB / Simuli etermination of h-parameters for Common Emitter amplifier. THREE PHASE CIRCUITS	lity factor and rcuits – Single t circuits using 12+6 m for DC inpu of Z,Y and F ink 12+6
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Unit III Theory - Bandwidth tuned circu Practice - MATLAB Studio - A Unit IV Theory - T and A.C. parameters Practice - Studio - D Unit V Theory - A balanced & three phase Practice - S	Series and parallel resonance – their frequency response – Qual - Self and mutual inductance – Coefficient of coupling – Tuned ci its. Simulation of series resonance circuit-Simulation of parallel resonan / Simulink. nalysis of tuned radio receiver circuit. TRANSIENT RESPONSE ANALYSIS AND TWO PORT NETWORKS Transient response of RL, RC and RLC Circuits using Laplace transform sinusoidal input-Characterization of two port networks in terms of . Simulation of R-C electric circuit transients using MATLAB / Simulitietermination of h-parameters for Common Emitter amplifier. THREE PHASE CIRCUITS analysis of three phase 3-wire and 4-wire circuits with star and delta context of three phase balanced and unbalanced star, delta network	lity factor and rcuits – Single t circuits using 12+6 m for DC inpu of Z,Y and H ink 12+6 onnected loads neasurement in

Course Outcomes: Upon successful completion of the course, students will be able to

CO1: Understand the concepts of circuit analysis, network reduction methods and network
theorems.
CO2: Demonstrate the application of series, parallel resonance and coupled circuits.
CO3: Analyze the transient response of electric circuit and characteristics of two port
networks.
CO4: Analyze three phase circuits and various methods of power measurement.
CO5: Use modern simulation tools for electric circuit analysis.
CO6: Design and develop electric circuits for practical applications.
Text Books:
1. William H. Hayt Jr, Jack E. Kemmerly, and Steven M. Durbin, Engineering Circuits Analysis, McGraw Hill publishers, New Delhi, 2013.
2. Charles K. Alexander, Mathew N.O. Sadiku, Fundamentals of Electric Circuits, Second Edition, McGraw Hill, 2013.
References:
1. Allan H. Robbins, Wilhelm C. Miller, Circuit Analysis Theory and Practice, Cengage Learning India, 2013.
2. Chakrabarti, A, Circuits Theory (Analysis and synthesis), Dhanpath Rai & Sons, New Delhi, 1999.
3. Jegatheesan, R., Analysis of Electric Circuits, McGraw Hill, 2015.
4. Joseph A. Edminister, Mahmood Nahri, Electric circuits, Schaum's series, McGraw- Hill, New Delhi, 2010.
5. M E Van Valkenburg, Network Analysis, Prentice-Hall of India Pvt. Ltd, New Delhi, 2015.
6. Mahadevan, K., Chitra, C., Electric Circuits Analysis, Prentice-Hall of India Pvt. Ltd., New Delhi, 2015.
 Richard C. Dorf, and James A. Svoboda, Introduction to Electric Circuits, 7th Edition, John Wiley & Sons, Inc. 2015.
8. Salivahanan, S., Pravin Kumar, S, Circuit Theory, Vikas Publishing House, 2014.
9. https://www.falstad.com/circuit/

COs]	POs					PSOs		
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6	3	3	3	3	3		3		3	3	3	3	3		

	ENVIRONMENTAL SCIENCE				l
Objectives: The students	EIT INOT THE SCIENCE	3	0	0	0
The students		5	U	U	U
	of Engineering undergoing this Course would develop a				
• Dotto	r understanding of human relationships, perceptions and polic	ries	towa	rds tl	he
environment	i understanding of numun relationships, perceptions and point	105	10 11 4	145 1	
	s on design and technology for improving environmental qual	litv			
	ENVIRONMENT, ECOSYSTEMSANDBIODIVERSITY	•		()
	cope and importance of environment– concept, structure and		incti	-	
	energy flow- food chains, food webs and ecological pyrar				
succession	energy now rood enams, rood webs and ecological pyra	mus	U	0102	,icui
	to biodiversity definition and types- values of biodiversity-	Ind	ia ac	a m	ega.
	on – hot-spots of biodiversity – threats to biodiversity-endang				U
-	India -conservation of biodiversity: In-situ and ex-situ				
biodiversity.	india -conservation of biodiversity. In-situ and ex-situ	COI		ation	01
	NATURAL RESOURCES)
				-	
	xploitation of natural resources: Forest, Water, Mineral, Food,				
	on over exploitation of natural resources -Role of an individu	al in	con	serva	tion
	ources- Equitable use of resources for sustainable life styles.				
Unit III	CURRENTENVIRONMENTALISSUES			9)
Environment	al issues- causes, effects and control measures of Pollution	of (a	ı) Ai	r (Sn	nog,
	mate change and global warming, ozone layer depletion) (b)				-
	watershed management and waste water treatment) (c) S				
-	, wasteland reclamation) (d)Electronic waste.				
	xplosion, Resettlement and rehabilitation of people and Disas	ter r	nana	geme	ent
	ENGINEERING INTERVENTIONS TO REDUCE			<u> </u>	
	ENVIRONMENTAL STRESSES				
Role of info	rmation technology in environment- Remote Sensing- satel	lites	and	sens	ors-
	l Information Systems (GIS)-Applications. Environment data				
	en chemistry-Principles - Green buildings-Advantages of gre			-	
•	buildings-Electric and Hybrid Electric Vehicles (HEV)			U	
	ENVIRONMENTALREGULATIONS			()
Assessment– (Prevention a	al Ethics for sustainable development- Human rights- Environment- Ecomark-role of NGO- Central and state pollution control of Pollution) act 1981– Water (Prevention and contidlife protection act 1972 – Forest conservation act 1980- The 2010	ntrol ntrol	boa of F	ards- Pollut	Air ion)
	Total I	Perid	bds	4	5

Course Outcomes: Upon successful completion of the course, students will be able to

CO1: The structure and functions of the ecosystems and diversity among life forms within an ecosystem

CO2: The importance of various natural resources and its sustainable use

CO3: The various environmental issues such as pollution, population explosion etc and suggest remedial measures.

CO4: The role of engineering techniques to minimize environmental stress

CO5: The role of various environmental machineries and to ensure proper environmental regulation

Text Books:

- 1. Anubha Kaushik and C. P. Kaushik, Environmental Science and Engineering, New Age International Publishers, 14thEdition, 2014.
- 2. Benny Joseph, 'Environmental Science and Engineering', Tata McGraw-Hill, New Delhi,2006

References:

1. Gilbert M.Masters, 'Introduction to Environmental Engineering and Science', 2nd edition, Pearson Education, 2004.

2. G. Tyler Miller and Scott E. Spoolman, "Environmental Science", Cengage Learning India PVT, LTD, Delhi, 2014

COs								POs	5				PSOs		
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1	3	-	1												
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4	3	2	1												
5	3	-	-												

Course Code	Course Title	L	Т	Р	C
UME2251	ENGINEERING MECHANICS FOR ELECTRICAL ENGINEERS	3	0	0	3
Objectives:					
• To develo	op capacity to predict the effect of force and motion in the c	cours	se of	carry	ying
out the design fur	nctions of engineering				
Unit I	STATICS OF PARTICLES (only vector approach)			ç)
Introduction – U	nits and Dimensions – Laws of Mechanics – Lami's theore	em, F	Paral	lelog	ram
and triangular L	aw of forces - Vectorial representation of forces - Vec	tor o	oper	ation	s of
forces -additions	, subtraction, dot product, cross product - Coplanar For	ces -	- rec	ctang	ular
components - Eq	uilibrium of a particle – Forces in space – Equilibrium of a	a par	ticle	in spa	ace-
Equivalent system	ms of forces – Principle of transmissibility.				

Unit II	EQUILIBRIUM OF RIGID BODIES (only vector approach)	9
Free body diag	ram – Types of supports –Action and reaction forces – stable equil	ibrium –
Moments and	Couples – Moment of a force about a point and about an axis – V	Vectorial
representation	of moments and couples - Scalar components of a moment - Va	rignon's
theorem - Sin	gle equivalent force -Equilibrium of Rigid bodies in two dimen	nsions –
Equilibrium of	Rigid bodies in three dimensions	
Unit III	PROPERTIES OF SURFACES AND SOLIDS	9
Centroids and c	centre of mass – Centroids of lines and areas - Rectangular, circular, tr	riangular
areas by integra	ation – T section, I section, - Angle section, Hollow section by using	standard
formula -Theo	orems of Pappus - Area moments of inertia of plane areas - Rec	tangular,
circular, triang	ular areas by integration – T section, I section, Angle section, Hollow	v section
	rd formula – Parallel axis theorem and perpendicular axis theorem – I	-
moments of ine	ertia of plane areas - Principal axes of inertia-Mass moment of inert	ia –mass
	ertia for prismatic, cylindrical and spherical solids from first pri	nciple –
Relation to area	a moments ofinertia.	
Unit IV	DYNAMICS OF PARTICLES	9
1	, Velocity and acceleration, their relationship – Relative motion – Cu	
	on's laws of motion - Work Energy Equation- Impulse and Mom	entum –
Impact of elast		
Unit V	FRICTION AND RIGID BODY DYNAMICS (only vector	9
	approach)	
	Laws of sliding friction – equilibrium analysis of simple systems wit	-
-	e friction – ladder friction - Rolling resistance -Translation and Ro	
	Velocity and acceleration – General Plane motion of simple rigid boo	lies such
as cylinder, dis	c/wheel and sphere	
	Total Periods	45
	mes: Upon successful completion of the course, students will be able	
	the vectoral and scalar representation of forces and moments (BL: I	.3)
	the rigid body in equilibrium (BL: L3)	
	the properties of surfaces and solids (BL: L3)	
	e dynamic forces exerted in rigid body (BL: L3)	
	he the friction and the effects by the laws of friction (BL: L3)	
Text Books:		<u>).</u>
	and Johnston Jr. E.R., Vector Mechanics for Engineers (In SI Units	<u></u>
Delhi, 20	nd Dynamics, 8th Edition, Tata McGraw-Hill Publishing Company, 2	INEW
	rali, Engineering Mechanics, Oxford University Press, 2010	
References:	ti S.S. and Daiachekaranna K.C. Engineering Machanics North	
	ti S.S. and Rajashekarappa K.G., Engineering Mechanics, New Age	
	onal (P) Limited Publishers, 1998.	
	, R.C and Ashok Gupta, Engineering Mechanics: Statics and Dynam	ncs,
LITH Edit	ion, Pearson Education, 2010.	

- 3. Irving H. Shames, and Krishna Mohana Rao, G., Engineering Mechanics Statics and Dynamics, 4th Edition, Pearson Education 2006.
- 4. Meriam, J.L., and Kraige, L.G., Engineering Mechanics- Statics Volume 1, Dynamics- Volume 2, Third Edition, John Wiley & Sons,1993.
- 5. Rajasekaran, S, and Sankarasubramanian, G., Engineering Mechanics Statics and Dynamics, 3rd Edition, Vikas Publishing House Pvt. Ltd., 2005.

COs								POs	5				PSOs		
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Course Code	Course Title	L	Τ	Р	С
UGE2297	DESIGN THINKING AND ENGINEERING PRACTICES LAB	0	0	3	1.5

Objectives:

- To provide exposure to the students with hands on experience on various basic engineering practices in Civil, Mechanical, Electrical and Electronics Engineering
- To train the students to dismantle, understand the functional / aesthetic aspects of the product, prepare the part functional model, and to assemble the different engineering components

List of Experiments:

GROUP A (CIVIL & MECHANICAL ENGINEERING PRACTICE)

I - CIVIL ENGINEERING PRACTICE

Buildings:

Study of plumbing and carpentry components of residential and industrial buildings - Safety aspects.

Plumbing Works:

- (a) Study of pipeline joints, its location and functions: valves, taps, couplings, unions, reducers, and elbows in household fittings.
- (b) Preparation of plumbing line sketches for water supply and sewage works.
- (c) Hands-on-exercise:
 - Basic pipe connections Mixed pipe material connection Pipe connections with different joining components.
 - Plumbing with basic connections for washing basin and sink

Carpentry using Power Tools only:

- (a) Study of the joints in roofs, doors, windows and furniture.
- (b) Hands-on-exercise: Wood work, joints by sawing, planning and cutting.
 - Fabrication of different models of pencil box and pen stand.
 - Fabrication of wooden wall shelf
- (c) Demonstration of wood working machinery

II - MECHANICAL ENGINEERING PRACTICE

Basic Machining:

(a) Drilling Practice (holes of various diameters - steel sheet metal, wood, hylam/plywood sheet)

Sheet Metal Work

- (a) Forming & Bending
- (b) Different type of joints.
 - Fabrication of mobile phone metal stand
 - Fabrication of electrical control panel box

Design thinking practices

To dismantle, understand the functional / aesthetic aspects of the product, prepare the part functional model, and to assemble the following components.

• Pedestal Fan head swing mechanism - Reserve mechanism (Two wheeler) - Hot Glue gun - Paper clips - Flush tank container mechanism - Hand pump – washer Mechanism

GROUP B (ELECTRICAL & ELECTRONICS ENGINEERING PRACTICE)

- 1. Residential house wiring, staircase wiring and tube light wiring with single phase AC two wire system.
- 2. Energy measurement with RLC Load.
- 3. Earth resistance measurement.
- 4. Measurement of AC parameters using CRO and half wave and Full wave rectifier.
- 5. Study of logic gates AND, OR, EX-OR & NOT.
- 6. Soldering practice Components Devices and Circuits Using PCB.

Design thinking practices

- 1. Assemble a single phase 3 wire circuit for connecting household appliances and explain through schematic diagram
- 2. Measure the energy consumed by the household appliances and verify it theoretically
- 3. Analyze the fault occurring in electrical appliances
- 4. Design, assemble and test a cell phone charger
- 5. Design, assemble and test a relay logic to control electrical appliances.
- 6. Design, assemble and test a dc power supply using PCB

Total Periods:45

Course Outcomes: Upon successful completion of the course, students will be able to

CO1: Draw pipeline plan; lay and connect various pipe fittings used in common household plumbing work; Saw; plan; make joints in wood materials used in common household woodwork (K2)

CO2: Practice machining to make holes on different materials; fabricate sheet metal components (K2)

CO3: Dismantle, understand the functional / aesthetic aspects of the product, prepare the part functional model of various components (K2)

CO4: Construct domestic electrical circuits and verify their output parameters (K3)

CO5: Construct electronics circuits and verify their output (K3)

- 1. Willis H. Wagner, Howard "Bud" Smith, and Mark W. Huth Modern Carpentry, 12th Edition, 2015
- 2. P.C.Sharma, Production Technology (Manufacturing Process): Manufacturing Process, S.Chand publisher, 2006
- 3. Robert W. Messler, Reverse Engineering: Mechanisms, Structures, Systems & Materials, McGraw-Hill Education, 2014
- 4. David W Rongey, A Complete Guide to Home Electrical Wiring, 2013
- 5. K.Jeyachandran, S.Natarajan & S, Balasubramanian, "A Primer on Engineering Practices Laboratory", Anuradha Publications, (2007).

COs]	POs					
	1	2	3	4	5	6	7	8	9	10	11	12
1	3	2		1					2	1		1
2	3	2		1					2	1		1
3	3	2		1					2	1		1
4	3	3	3	3					3	1		1
5	3	3	3	3					3	1		1

Semester	-	III
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Course	Course Title	L	Т	P	C						
Code											
UMA2376	TRANSFORM TECHNIQUES AND PARTIAL	3	1	0	4						
	DIFFERENTIAL EQUATIONS	5	I	U	-						
Objectives:											
• Find l	Fourier series expansion of periodic functions										
Solve	the problems in partial differential equations.										
 Apply 	the concept of Fourier series in solving initial and boundary	y val	ue p	roble	ms.						
• Find l	Fourier transform of various functions.										
• Evalu	ate difference equations using Z- transform technique.										
Unit I	FOURIER SERIES			1	2						
Dirichlet's co	nditions – Fourier series – Odd and even functions – Half ran	ge si	ne a	nd co	sine						
series – RMS	value - Parseval's identity – Harmonic analysis.										
Unit II	PARTIAL DIFFERENTIAL EQUATIONS			1	2						
	partial differential equations - First order PDE's - standard	• •		-							
	standard types - Lagrange's linear equation, Higher order	r PD	E's	– Li	near						
-	s partial differential equations with constant coefficients			n	2						
	APPLICATIONS OF PARTIAL DIFFERENTIAL										
	EQUATIONS										
	n of PDE – Method of separation of variables - Solutions o										
-	on, Solutions to Heat equations - One dimensional heat	equ	atio	n – '	Two						
	steady state heat equation (no insulated edges).										
	FOURIER TRANSFORMS				2						
	Fourier integral theorem – Fourier transform pair – Fouri										
	Properties – Transform of simple functions, Transform	01	derr	vative	es –						
	theorem – Parseval's identity.			1	2						
	Z - TRANSFORMS AND DIFFERENCE EQUATIONS s - Elementary properties – Bilateral Z-transforms (definition)	nor	1)		2						
	t impulse function, Convolution theorem - Inverse Z - transf		•		-						
	volution theorem and residues), Discrete time systems										
	olution of difference equations using Z- transform.		uL	men	chee						
Lquations by	Total	Peri	ods	6	0						
	1 our		Jub	0	U						
Course Outo	comes: Upon successful completion of the course, students v	vill b	e ab	le to							
	Fourier series expansion of periodic functions.										
	he problems in partial differential equations.										
	solve initial and boundary value problems using Fourier ser	ies t	echn	iques	5.						
CO3: Able to	solve miliai and boandary value problems asing routier ser										
	Fourier transform of various functions			1							
CO4: Obtain	Fourier transform of various functions			1							
CO4: Obtain CO5: Evaluat		trans	forn		1						

Te	xt Books:
1.	Grewal. B.S., "Higher Engineering Mathematics", 44th Edition, Khanna Publishers,
	Delhi, 2018.
2.	Veerarajan. T., "Transforms and Partial Differential Equations", Tata McGraw Hill
	Education Pvt. Ltd., Second reprint, New Delhi, 2012.
3.	Narayanan.S., ManicavachagomPillay.T.K and Ramanaiah. G, "Advanced Mathematics
	for Engineering Students" Vol. II & III, S. Visvanathan Publishers Pvt Ltd. 1998.
Re	ferences:
1.	Bali.N.P and Manish Goyal, "A Textbook of Engineering Mathematics", 9th Edition,
	Laxmi Publications Pvt Ltd, 2016.
2.	Ramana.B.V., "Higher Engineering Mathematics", Tata Mc-Graw Hill Publishing
	Company Limited, New Delhi, 2008.
3.	Erwin Kreyszig, Advanced Engineering Mathematics, John Wiley & Sons, Inc., 10th
	Edition, 2016.
4.	Ray Wylie. C and Barrett. L.C, "Advanced Engineering Mathematics", Sixth Edition,
	Tata McGraw Hill Education Pvt Ltd, New Delhi, 2012.
5.	Datta.K.B., "Mathematical Methods of Science and Engineering", Cengage Learning
	India Pvt Ltd, Delhi, 2013.

COs		POs												
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	3	2												
2	3	2												
3	3	2												
4	3	2												
5	3	2												
6	3	2										1		

Course Code	Course Title	L	Т	Р	C
UHS2376	Universal Human Values 2: Understanding Harmony	2	0	2	3

Objectives:

- 1. To help students distinguish between values and skills, and understand the need, basic guidelines, content and process of value education.
- 2. To help students initiate a process of dialog within themselves to know what they 'really want to be' in their life and profession
- 3. To help students understand the meaning of happiness and prosperity for a human being.
- 4. To facilitate the students to understand harmony at all the levels of human living, and live accordingly.
- 5. To facilitate the students in applying the understanding of harmony in existence in their profession and lead an ethical life Course

Unit I	INTRODUCTION TO VALUE EDUCATION	9
importance	and process, Continuous Happiness and Prosperity - A look at basic	c Human
-	s, Right understanding, Relationship and Physical Facilities - the ts, Understanding Happiness and Prosperity - A critical appraisal of the transformation of tran	
	Aethod to fulfill the above human aspirations - understanding and	
	various levels.	U
Unit II	HARMONY IN THE HUMAN BEING	9
Understand Body as a characterist the Body: S	ing human being as a co-existence of the sentient 'I' and the material ing the needs of Self ('I') and 'Body' - Sukh and Suvidha, Understant in instrument of 'I' (I being the doer, seer and enjoyer), Understant ics and activities of 'I' and harmony in 'I', Understanding the harmony anyam and Swasthya; correct appraisal of Physical needs, meaning of P rograms to ensure Sanyam and Swasthya	nding the nding the of I with
Unit III	HARMONY IN THE FAMILY AND SOCIETY	9
	hip, Difference between intention and competence, Understanding Res aluation, Difference between respect and differentiation; the other salie	-
Visualizing	hip, Understanding the harmony in the society - comprehensive Huma a universal harmonious order in society- Undivided Society, Universative to world family!	an Goals,
Visualizing	hip, Understanding the harmony in the society - comprehensive Huma a universal harmonious order in society- Undivided Society, Universa	an Goals,
Visualizing from family Unit IV Understand fulfillment existence of	hip, Understanding the harmony in the society - comprehensive Huma a universal harmonious order in society- Undivided Society, Universa to world family!	an Goals, al Order - 9 ad mutual ce as Co-
Visualizing from family Unit IV Understand fulfillment existence of	hip, Understanding the harmony in the society - comprehensive Huma a universal harmonious order in society- Undivided Society, Universa to world family! HARMONY IN THE NATURE AND EXISTENCE ing the harmony in the Nature, Interconnectedness, self-regulation an among the four orders of nature- recyclability, Understanding Existence f mutually interacting units in all-pervasive space, Holistic perception of	an Goals, al Order - 9 ad mutual ce as Co-
Visualizing from family Unit IV Understand fulfillment existence of at all levels Unit V Natural acc Humanistic Competence characterist systems and to Univers responsible	hip, Understanding the harmony in the society - comprehensive Huma a universal harmonious order in society- Undivided Society, Universate to world family! HARMONY IN THE NATURE AND EXISTENCE ing the harmony in the Nature, Interconnectedness, self-regulation an among the four orders of nature- recyclability, Understanding Existence f mutually interacting units in all-pervasive space, Holistic perception of of existence. IMPLICATIONS OF THE ABOVE HOLISTIC UNDERSTANDING OF HARMONY ON PROFESSIONAL	an Goals, al Order - 9 d mutual ce as Co- harmony 9 Basis for 1 Order, cope and roduction esent state plogically

Course Outcomes: Upon successful completion of the course, students will be able to

CO1: Understand the significance of value education, happiness, and prosperity (K2)

CO2: Understand the significance of harmony in self and body (K2)

CO3. Understand the value of harmony in human relationships (K2)

CO4: Understand the harmony in nature and existence and work out their mutually fulfilling participation in the nature. (K2)

CO5: Distinguish between ethical and unethical practices and start working out the strategy to actualize a harmonious environment wherever they work (K4)

Text Books:

1. R R Gaur, R Sangal, G P Bagaria, 2009, A Foundation Course in Human Values and Professional Ethics, Excel Books, New Delhi, 2nd Revised Edition, 2019.

- 1. Jeevan Vidya: EkParichaya, A Nagaraj, Jeevan Vidya Prakashan, Amarkantak, 1999.
- 2. Human Values, A.N. Tripathi, New Age Intl. Publishers, New Delhi, 2004.
- 3. The Story of Stuff (Book).
- 4. The Story of My Experiments with Truth by Mohandas Karamchand Gandhi
- 5. Small is Beautiful E. F Schumacher.
- 6. Slow is Beautiful Cecile Andrews
- 7. Economy of Permanence J C Kumarappa
- 8. Bharat Mein Angreji Raj PanditSunderlal
- 9. Rediscovering India by Dharampal
- 10. Hind Swaraj or Indian Home Rule by Mohandas K. Gandhi
- 11. India Wins Freedom Maulana Abdul Kalam Azad
- 12. Vivekananda Romain Rolland (English)
- 13. Gandhi Romain Rolland (English)

COs		POs													
	1	2	3	4	5	6	7	8	9	10	11	12			
1						2		3	3	2		3			
2						2		3	3	2		3			
3						2		3	3	2		3			
4						2		3	3	2		3			
5						2		3	3	2		3			

Course	Course Title	L	Т	Р	С						
Code	Code										
UEC2376	SIGNALS AND SYSTEMS	3	0	0	3						
Objectives:											
• To under	rstand the basic properties of signal & systems.										
• To know	the methods of characterization of LTI systems in time do	main	l.								
To analy	ze continuous time signals and systems in the Fourier and I	Lapla	ace d	lomai	in.						

Unit I	CLASSIFICATION OF SIGNALS AND SVOTEMS	Λ
	CLASSIFICATION OF SIGNALS AND SYSTEMS	9 Declard
	-Time signals (CT), Discrete-Time signals (DT) - Step, Ramp, Pulse,	
	ponentials, Sinc, Impulse, Exponential, Classification of CT and DT	
-	d aperiodic signals, Energy and Power signals, Random signals- Continu	
	te-time sinusoids and its properties – Operations on signals-Deper	
-	t Variables- CT systems and DT systems - Linear & Nonlinear, Time-	
	ant, Causal & Non-causal, Static and Dynamic and Stable & Unstable	
Unit II	ANALYSIS OF CONTINUOUS TIME SIGNALS	9
	ies analysis (Exponential only)- Properties of Fourier series -Time	-
	shifting and Parseval's Theorem in Fourier series, Gibb's phenomenon	
	and its properties - Linearity, Time shift, Time scaling, Frequency shift	•
	ion in time and frequency, Convolution, Multiplication and Parseval's	
	Laplace transform- Pole-Zero diagram in s-domain, Region of Cor	ivergence
	perties of ROC- Inverse Laplace transform.	0
Unit III	LINEAR TIME-INVARIANT CONTINUOUS TIME SYSTEMS	9
Differential	equation, Representing CT system using differential equations – Appl	ication of
Laplace trai	nsform to RL, RC and RLC circuits- Impulse response- Causality and	Stability
-	n integral- Properties of convolution integral (Statement only)- Transfe	-
	stems-Analysis of CT systems using Fourier and Laplace the	
•	tion of system –Cascade and Parallel.	
Unit IV	ANALYSIS OF DISCRETE TIME SIGNALS	9
Sampling o	f CT signals, Frequency domain representation of sampling, Reconstru	ction of a
1 0	d signals from its samples- Z-transform, Pole – Zero diagram in z	
		L-uomam.
properties c	of Z-transform -Linearity, Time shift, Time scaling, Time Reversal, F	
	of Z-transform -Linearity, Time shift, Time scaling, Time Reversal, Follotion, and Correlation, Inverse Z-transform- Partial fraction method.	Frequency
shift, Convo	olution, and Correlation, Inverse Z-transform- Partial fraction method.	Frequency Discrete-
shift, Convo Time Fouri		Frequency Discrete-
shift, Convo Time Fourio theorem.	olution, and Correlation, Inverse Z-transform- Partial fraction method. er Transform (DTFT) and Inverse DTFT- Properties- Periodicity and H	Frequency Discrete
shift, Convo Time Fourio theorem. Unit V	olution, and Correlation, Inverse Z-transform- Partial fraction method. er Transform (DTFT) and Inverse DTFT- Properties- Periodicity and H LINEAR TIME INVARIANT - DISCRETE TIME SYSTEMS	Frequency Discrete Parseval's
shift, Convo Time Fourio theorem. Unit V Difference of	olution, and Correlation, Inverse Z-transform- Partial fraction method. er Transform (DTFT) and Inverse DTFT- Properties- Periodicity and H LINEAR TIME INVARIANT - DISCRETE TIME SYSTEMS equations, Impulse response, Convolution sum, Z-transform and DTFT	Frequency Discrete- Parseval's 9 `Analysis
shift, Convo Time Fourio theorem. Unit V Difference of Recursiv	olution, and Correlation, Inverse Z-transform- Partial fraction method. er Transform (DTFT) and Inverse DTFT- Properties- Periodicity and H LINEAR TIME INVARIANT - DISCRETE TIME SYSTEMS equations, Impulse response, Convolution sum, Z-transform and DTFT re & Non-recursive systems. Block diagram representation, Direct Fo	Frequency Discrete- Parseval's 9 Analysis prm-I and
shift, Convo Time Fourio theorem. Unit V Difference of of Recursiv Direct Form	olution, and Correlation, Inverse Z-transform- Partial fraction method. er Transform (DTFT) and Inverse DTFT- Properties- Periodicity and H LINEAR TIME INVARIANT - DISCRETE TIME SYSTEMS equations, Impulse response, Convolution sum, Z-transform and DTFT	Frequency Discrete- Parseval's 9 Analysis prm-I and
shift, Convo Time Fourio theorem. Unit V Difference of of Recursiv Direct Form	olution, and Correlation, Inverse Z-transform- Partial fraction method. er Transform (DTFT) and Inverse DTFT- Properties- Periodicity and H LINEAR TIME INVARIANT - DISCRETE TIME SYSTEMS equations, Impulse response, Convolution sum, Z-transform and DTFT re & Non-recursive systems. Block diagram representation, Direct For n-II - Cascade and Parallel forms, Interconnection of DT systems – Cas	Frequency Discrete- Parseval's 9 Analysis prm-I and
shift, Convo Time Fourio theorem. Unit V Difference of Recursiv	olution, and Correlation, Inverse Z-transform- Partial fraction method. er Transform (DTFT) and Inverse DTFT- Properties- Periodicity and H LINEAR TIME INVARIANT - DISCRETE TIME SYSTEMS equations, Impulse response, Convolution sum, Z-transform and DTFT re & Non-recursive systems. Block diagram representation, Direct Fo	Frequency Discrete- Parseval's 9 `Analysis orm-I and scade and
shift, Convo Time Fourio theorem. Unit V Difference of of Recursiv Direct Form Parallel	olution, and Correlation, Inverse Z-transform- Partial fraction method. er Transform (DTFT) and Inverse DTFT- Properties- Periodicity and H LINEAR TIME INVARIANT - DISCRETE TIME SYSTEMS equations, Impulse response, Convolution sum, Z-transform and DTFT re & Non-recursive systems. Block diagram representation, Direct For n-II - Cascade and Parallel forms, Interconnection of DT systems – Cas	Frequency Discrete Parseval's 9 YAnalysis prm-I and scade and 45
shift, Convo Time Fourio theorem. Unit V Difference of Recursiv Direct Form Parallel Course Ou	olution, and Correlation, Inverse Z-transform- Partial fraction method. er Transform (DTFT) and Inverse DTFT- Properties- Periodicity and H LINEAR TIME INVARIANT - DISCRETE TIME SYSTEMS equations, Impulse response, Convolution sum, Z-transform and DTFT re & Non-recursive systems. Block diagram representation, Direct Fo n-II - Cascade and Parallel forms, Interconnection of DT systems – Cas Total Periods	Frequency Discrete- Parseval's 9 Y Analysis prm-I and scade and 45
shift, Convo Time Fourio theorem. Unit V Difference of of Recursiv Direct Form Parallel Course Ou CO1: Analy CO2: Apply	olution, and Correlation, Inverse Z-transform- Partial fraction method. er Transform (DTFT) and Inverse DTFT- Properties- Periodicity and H LINEAR TIME INVARIANT - DISCRETE TIME SYSTEMS equations, Impulse response, Convolution sum, Z-transform and DTFT re & Non-recursive systems. Block diagram representation, Direct Fo n-II - Cascade and Parallel forms, Interconnection of DT systems – Cas Total Periods tcomes: Upon successful completion of the course, students will be ab yze the properties of signals & systems. y Fourier series, Laplace transform, Fourier transform, Z-transform and	Frequency Discrete Parseval's 9 Analysis orm-I and scade and 45 le to
shift, Convo Time Fourie theorem. Unit V Difference of of Recursiv Direct Form Parallel Course Ou CO1: Analy CO2: Apply in signal ar	olution, and Correlation, Inverse Z-transform- Partial fraction method. er Transform (DTFT) and Inverse DTFT- Properties- Periodicity and H LINEAR TIME INVARIANT - DISCRETE TIME SYSTEMS equations, Impulse response, Convolution sum, Z-transform and DTFT re & Non-recursive systems. Block diagram representation, Direct Fo n-II - Cascade and Parallel forms, Interconnection of DT systems – Cas Total Periods teomes: Upon successful completion of the course, students will be ab yze the properties of signals & systems. y Fourier series, Laplace transform, Fourier transform, Z-transform and nalysis.	Frequency Discrete Parseval's 9 Analysis orm-I and scade and 45 le to 1 DTFT
shift, Convo Time Fourie theorem. Unit V Difference of of Recursiv Direct Form Parallel Course Ou CO1: Analy CO2: Apply in signal ar	olution, and Correlation, Inverse Z-transform- Partial fraction method. er Transform (DTFT) and Inverse DTFT- Properties- Periodicity and H LINEAR TIME INVARIANT - DISCRETE TIME SYSTEMS equations, Impulse response, Convolution sum, Z-transform and DTFT re & Non-recursive systems. Block diagram representation, Direct Fo n-II - Cascade and Parallel forms, Interconnection of DT systems – Cas Total Periods tcomes: Upon successful completion of the course, students will be ab yze the properties of signals & systems. y Fourier series, Laplace transform, Fourier transform, Z-transform and	Frequency Discrete Parseval's 9 Analysis orm-I and scade and 45 le to 1 DTFT
shift, Convo Time Fourio theorem. Unit V Difference of of Recursiv Direct Form Parallel Course Ou CO1: Analy CO2: Apply in signal ar CO3: Analy	olution, and Correlation, Inverse Z-transform- Partial fraction method. er Transform (DTFT) and Inverse DTFT- Properties- Periodicity and H LINEAR TIME INVARIANT - DISCRETE TIME SYSTEMS equations, Impulse response, Convolution sum, Z-transform and DTFT re & Non-recursive systems. Block diagram representation, Direct Fo n-II - Cascade and Parallel forms, Interconnection of DT systems – Cas Total Periods teomes: Upon successful completion of the course, students will be ab yze the properties of signals & systems. y Fourier series, Laplace transform, Fourier transform, Z-transform and nalysis.	Frequency Discrete Parseval's 9 Analysis orm-I and scade and 45 le to 1 DTFT

1. Oppenheim A.V, Wilsky S and Nawab S.H, Signals and Systems, Prentice-Hall International, Second Edition, 2011 (Unit I-V)

References:

- 1. Lathi B.P, Principles of Linear Systems and Signals, Oxford, Second Edition, 2009.
- 2. Zeimer R.E, Tranter W.H and Fannin R.D, Signals & Systems-Continuous and Discrete, Prentice-Hall, Fourth Edition, 1998.
- 3. OktayAlkin, Signals and Systems: A MATLAB® Integrated Approach, CRC Press,
- 4. First Edition, 2017.
- 5. Roberts M.J, Signals & Systems Analysis using Transform Methods & MATLAB, Tata-McGraw Hill, First Edition, 2003.
- 6. Luis Chaparro and Aydin Akan, Signals and Systems using MATLAB, Elsevier, Third Edition,2018.

COs	POs											PSOs			
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
1	3	3		2	3				2			2	3	3	2
2	3	3		2	3				2			2	3	3	2
3	3	3	2	3	3	2	1		2			2	2	3	2
4	3	3	2	3	3	2	1		2			2	3	3	2

Course Code	Course Title	L	T	Р	C
UEE2301	ELECTROMAGNETIC THEORY	2	1	0	3

Objectives:

- To understand the basic mathematical concepts related to electromagnetic vector fields
- To study the concepts of Electrostatic fields, electrical potential, energy density and their applications.
- To study the concepts of Magneto static fields, magnetic flux density, vector potential and its applications.
- To apply concepts related to electrostatics, magnetostatics and electrodynamics in obtaining Maxwell's equations
- To understand Electromagnetic wave propagation and characterize the parameters

Unit I	VECTOR ANALYSIS	9						
Sources and effects of electromagnetic fields - Coordinate Systems - Differential Elements								
of Length, S	Surface and Volume - Vector fields –Gradient of a scalar field - Diverg	ence of a						
vector field	- Curl of a vector filed - Gauss's Divergence Theorem - Stoke's Theorem	em.						
Unit II	STATIC ELECTRIC FIELDS	9						

Coulomb's Law – Electric field intensity – Field due to discrete and continuous charges – Gauss's law and applications-Electric potential – Electric field and equipotential plots, Uniform and Non-Uniform field, Utilization factor – Electric field in free space, conductors,

dielectrics - Dielectric polarization – Dielectric strength - Electric field in multiple d	ielectrice
– Boundary conditions, Poisson's and Laplace's equations, Capacitance, Energy	
	density,
Applications. Unit III STATIC MAGNETIC FIELDS	9
Lorentz force, magnetic field intensity (H) – Biot–Savart's Law - Ampere's Circu	
H due to straight conductors, circular loop, infinite sheet of current, Magnetic flux	
(B) - B in free space, conductor, magnetic materials – Magnetization, Magnetic	•
multiple media –Boundary conditions, scalar and vector potential, Poisson's I	
Magnetic force, Torque, Inductance, Energy density, Applications.	squaron,
Unit IV ELECTRODYNAMIC FIELDS	9
Faraday's law – Transformer and motional EMF –Displacement current - M	
equations (differential and integral form) – Relation between field theory and circu	
-Electromagnetic boundary conditions - Applications of electrodynamic fields	int theory
Unit V ELECTROMAGNETIC WAVES	9
Electromagnetic wave equations – Wave parameters: velocity, intrinsic im	
propagation constant – Waves in free space, lossy and lossless dielectrics, conduct	-
depth – Poynting vector.	JOIS SKIII
Total Periods	45
Course Outcomes: Upon successful completion of the course, students will be abl	e to
CO1: Apply the basic mathematical concepts related to electromagnetic vector field	
CO2: Examine the concepts of electrostatic fields, electrical potential, energy dens	
their applications.	5
CO3: Infer the concepts of magneto static fields, magnetic flux density, vector pote	ential
and its applications.	
CO4: Perform analysis using concepts related to electrostatics, magnetostatics and	
electrodynamics in obtaining Maxwell's equations	
CO5: Understand electromagnetic wave propagation and characterize the parameter	ers
Text Books:	
1. Mathew N. O. Sadiku and S.V. Kulkarni, 'Principles of Electromagnet	tics', 6th
Edition, Oxford University Press Inc. Asian edition, 2015.	
2. William H. Hayt and John A. Buck, 'Engineering Electromagnetics', McG	raw Hill
Special Indian edition, 2014.	
3. Salivahanan S and Karthie S, 'Electromagnetic Field Theory", 2nd Edition,	,
McGrawHill, 2018	
References:	
1. V.V.Sarwate, 'Electromagnetic fields and waves', First Edition, Newage Pu	ublishers,
1993.	
2. J.P.Tewari, 'Engineering Electromagnetics - Theory, Problems and Appl	ications',
Second Edition, Khanna Publishers.	
3. Joseph. A.Edminister, 'Schaum's Outline of Electromagnetics, Third	Edition

3. Joseph. A.Edminister, 'Schaum's Outline of Electromagnetics, Third Edition (Schaum's Outline Series), McGraw Hill, 2010.

- 4. S.P.Ghosh, Lipika Datta, 'Electromagnetic Field Theory', First Edition, McGraw Hill Education(India) Private Limited, 2012.
- 5. K A Gangadhar, 'Electromagnetic Field Theory', Khanna Publishers; Eighth Reprint : 2015.
- 6. Kraus and Fleish, 'Electromagnetics with Applications', McGraw Hill International Editions, Fifth Edition, 2010.

COs	POs											PS	Os	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	3	2										1	3	
2	3	2	1						1	1		1	3	
3	3	2	1						1	1		1	3	
4	3	2	1						1	1		1	3	
5	3	2	1						1	1		1	3	

Course	Course Title	L	Τ	Р	C
Code					
UEE2302					_
	DATA STRUCTURES FOR ELECTRICAL	3	0	0	3
	ENGINEERING				
Objectives:					
• To u	nderstand Object Oriented Programming concepts				
• Top	erform polymorphism and file handling in C++				
• To e	xplore linear data structures.				
• To e	xplore non-linear data structures.				
• To a	pply the concepts of oops and data structures to electrical eng	inee	ring		
Unit I	INTRODUCTION TO OBJECT ORIENTED			9	9
	PROGRAMMING				
Object orien	nted programming concepts: classes - objects - object relat	ions	– m	embe	ers -
abstraction	- encapsulation - inheritance – polymorphism. Introduction to	C++	cla	iss- s	tatic
& dynamic	objects - constructors - destructors- static and constant memb	ers -	this	point	ter –
inline - nam	e space.				
Unit II	OVERLOADING – POLYMORPHISM – FILES			Ģ)
Operator ov	verloading - friend functions - Inheritance - function pointe	rs -c	lass	poin	ters-
-	tions- static and runtime polymorphism - type conversions- te			-	
	rary. Exception and File handling.	1			
Unit III	LINEAR DATA STRUCTURES – LIST, STACKS & QU	JEU	ES	()
Abstract D	ata Types (ADTs), Linked List - Types, Implementation	& a	ppli	catio	ns -
Polynomial	manipulations. Stack - Operations & Applications - Eval	luati	ng a	rithn	netic
	. Queue – Operations - Types: Circular Queue - Priority Qu		-		

Applic	rations of Queues.	
Unit I		9
Tree A	DT, Binary Tree – search, Threaded Binary Trees- AVL Trees – B-Tree -	B+ Tree -
Heap	- Applications of trees & heap. Graphs: Representation - Types - Bro	eadth-first
travers	al - Depth-first traversal – Topological Sort – Bi-connectivity – Cut verte	x – Euler
circuit	s – Applications of graphs.	
Unit V	ALGORITHMS & APPLICATIONS OF OOPS & DATA	9
	STRUCTURES TO ELECTRICAL ENGINEERING	
Search	ing- Linear Search - Binary Search. Sorting - Bubble sort - Selection sort -	Insertion
sort –	Shell sort - Radix sort. Applications - Solutions to simple DC/AC Circ	uits using
Graph	s. Solutions to simple Digital Circuits – Full Adder, four-bit full adder usi	ng OOPs.
Solutio	ons to simple power system problems.	
	Total Periods	45
		1
Cours	e Outcomes: Upon successful completion of the course, students will be ab	ole to
CO1.	Describe the need for object-oriented programming.	
CO2.	Apply the concepts of polymorphism, inheritance, exception, and file hand	lling in
	programming.	
CO3.	Illustrate the implementation of linear data structures using list, stacks, and	d queues.
CO4.		
CO5.	Illustrate various sorting and search algorithms for data handling	
CO6. Text H	Emulate electric circuits using OOPS and data structures.	
		7
	B. Trivedi, "Programming with ANSI C++", Oxford University Press, 200	
2.	Cay S. Horstman, Gary Cornell, "Core JAVA volume 1", Eighth Edition,	Pearson
	Education, 2008.	
3.	Mark Allen Weiss, "Data Structures and Algorithm Analysis in C", 2nd Ed	dition,
	Pearson Education,1997.	
4.	Reema Thareja, "Data Structures Using C", Second Edition, Oxford Unive	ersity
	Press, 2011	
Refere	ences:	
1.	ISRD Group, "Introduction to Object-oriented Programming and C++", Ta	ata
	McGraw-Hill Publishing Company Ltd., 2007.	
2.	S. B. Lippman, Josee Lajoie, Barbara E. Moo, "C++ Premier", Fourth Edi	tion,
	Pearson Education, 2005	
3.	D. S. Malik, "C++ Programming: From Problem Analysis to Program Des	ign",
	Third Edition, Thomson Course Technology, 2007.	
4.	Thomas H. Cormen, Charles E. Leiserson, Ronald L.Rivest, Clifford Stein	•
	"Introduction to Algorithms", Second Edition, Mcgraw Hill, 2002.	
5.	Ellis Horowitz, Sartaj Sahni, Susan Anderson-Freed, "Fundamentals of Da	ita
	Structures in C", Second Edition, University Press, 2008	

COs													PSOs	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	3		2		3								3	
2	3		2	1	3								3	
3	3		2	1	3								3	
4	3		2	1	3								3	
5	3		2	3	3								3	

Course	Course TitleLT												
Code													
UEE2303	ELECTRONIC DEVICES AND	3	0	0	3								
	CIRCUITS	3	U	U	3								
Objectives:													
• Unde	rstand the structure of basic electronic devices.												
• Fami	liarize the operation and characteristics of transistor like BJT	and	MO	SFEI	Г.								
• Explo	ore the design and analysis of amplifiers and understand the f	requ	ency										
respo	nse of amplifiers.												
• Learn	the required functionality of positive and negative feedback	amp	olifie	rs.									
Unit I	DIODE AND IT'S APPLICATIONS			9									
PN junction	diode - Structure, Operation, VI characteristics, models; A	pplic	catio	ns - I	Half								
wave rectif	ier, Full wave rectifier, impact of filters; Zener diod	le –	Br	eakd	own								
characteristic	es, Voltage regulation; Varactor diode, Light emitting diode	(LE	ED),	Scho	ttky								
diode – Oper	ation and Applications.												
Unit II	TRANSISTORS AND THYRISTORS			9									
Transistors:	BJT, UJT, FET, MOSFET – Structure, Operation, Input-outp	out cl	narac	cteris	tics;								
Biasing met	hods of BJT, FET & MOSFET; Thyristors: Structure, C)pera	ation	and	VI								
characteristic	CS												
Unit III	SMALL SIGNAL AND LARGE SIGNAL AMPLIFIERS)		9									
BJT-Config	urations, Small signal analysis using hybrid model – Analysis	of C	CE ar	nplif	ïers,								
Frequency re	esponse; MOSFET – Configurations, Small signal models, A	naly	sis o	f CS	and								
Source follo	wer amplifiers; Power amplifiers - Class A, Class B, Class	AB,	Cla	ss C	and								
Class D amp	lifiers (Qualitative analysis only).												
Unit IV	MULTISTAGE AND DIFFERENTIAL AMPLIFIERS			9									
Introduction	to Multistage amplifiers, Different coupling methods and	d the	eir f	reque	ency								
-	arlington connection; Differential Amplifier - Common			-									
	mode analysis, CMRR, frequency response; Single tuned	and	douł	ole tu	ined								
<u> </u>	Operation and frequency response.												
Unit V	FEEDBACK AMPLIFIERS AND OSCILLATORS			9									

Feedback amplifiers - Types, Stability, Distortion; Negative feedback: Voltage/current, series/shunt feedback amplifiers; Positive feedback: Barkhausencriterion, Operation and analysis of RC phase shift, Wienbridge, Hartely, Colpitts and crystal oscillators; Non-sinusoidal oscillators: Astable, Monostable & bistable Multivibrators.

Total Periods 45

Course Outcomes: Upon successful completion of the course, students will be able to

CO1: Describe the operation, characteristics and applications of diodes

CO2: Describe the operation, characteristics and applications of transistors

CO3: Design and analyze BJT and MOSFET amplifiers through frequency response

CO4: Design and analyze multistage and differential amplifiers through frequency response

CO5: Design feedback circuits for amplifier and describe various oscillators and its stability

Text Books:

1. Electronic Devices- Floyd T.L, 9th Edition, Pearson Education, 2012.

- 2. Electronic Devices and Circuits S.Salivahanan, N.Suresh Kumar, Mcgraw Hill Education, New Delhi, Fourth Ed, 2016.
- 3. Electronic Devices and Circuits David A. Bell, 7th Ed, Oxford, 2008

- 1. Electronic devices and circuits Allen Mottershead, Goodyear Publishing company, 1973.
- 2. Electronic Devices and Circuits B. P. Singh, Rekha Singh, Pearson, Second Ed, 2013.
- 3. Electronic Devices and Circuits Anil K. Maini, VarshaAgarwal, First Ed, Wiley India Pvt. Ltd, 2009.
- 4. Millman's Electronic Devices and Circuits J. Millman, C.C.Halkias and Satyabratajit, Second Ed,1998, TMH.
- 5. Electronic Devices and Circuits Mohammad Rashid, Cengage Learing, 2013

COs					POs									s
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	3			2									1	3
2	3												1	3
3	3	2	3	3	2							1	1	3
4	3			2									1	3
5	3			2	1								1	3

Course	Course Title	L	Τ	Р	С
Code					
UEE2311	ELECTRONICS LAB	0	0	3	1.5
Objectives:					1
• To ena	ble the students to understand the behavior of semiconducto	or de	vice	base	d on
experi	nentation.				
List of Experi	ments:				
1. Study of Cl	RO for frequency and phase measurements				
2. Characterist	ics of Semiconductor diode and Zener diode				
3. Characterist	ics of a NPN Transistor under common emitter, common co	ollec	tor a	nd	
common base	configurations				
4. Characterist	ics of JFET and draw the equivalent circuit				
5. Characterist	ics of UJT and generation of saw tooth waveforms				
6. Design and	Frequency response characteristics of a Common Emitter and	mpli	fier		
7. Characterist	ics of photo diode & photo transistor, Study of light activate	ed re	elay o	circu	it
8. Design and	testing of RC phase shift and LC oscillators				
9. Single Phas	e half-wave and full wave rectifiers with inductive and ca	paci	tive	filter	s10.
Differential an	plifiers using FET				
11. Realization	n of passive filters				
		Tota	al Pe	riod	s:45
Course Outco	mes: Upon successful completion of the course, students w	vill b	e abl	e to	
CO1: Characte	rize PN diode, zener diode, BJT, FET , UJT, photo diode an	d ph	oto ti	ransi	stor.
CO2 C1	rize rectifiers, passive filters, CE amplifiers and differentia	l am	plifie	ers.	
CO2: Characte	rize oscillators and realize filters.				
	fize oscillators and realize inters.				
	anze oscillators and realize filters.				
CO3: Characte References:	Devices- Floyd T.L, 9th Edition, Pearson Education, 2012.				
CO3: Character References: 1. Electronic		cgra	w Hi	11	
CO3: CharacterReferences:1. Electronic2. Electronic	Devices- Floyd T.L, 9th Edition, Pearson Education, 2012.	cgra	w Hi	11	

COs		POs												
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	2	2	1	3				1	3	1		1	2	3
2	2	2	1	3				1	3	1		1	2	3
3	2	2	1	3				1	3	1		1	2	3

Course	Course Title	L	Т	Р	С			
Code								
UEE2312	OBJECT ORIENTED PROGRAMMING AND							
	DATA STRUCTURES LABORATORY FOR	0 0 3 1						
	ELECTRICAL ENGINEERING							
Objectives:								
 Object 	orient programming & Inheritance							
Polyme	orphism & File handling							
• Linear	& non-linear data structures.							
Search	ing & Sorting.							
Solution	ons to electrical engineering problems							
List of Experi	ments:							
1. Simple	classes for understanding objects (Both static and dynamic	obje	cts),	men	nber			
	ns, constructors & destructors.							
	s with both Static and Constant members							
-	le time Polymorphism – Operator and Function Overloading							
	ne Polymorphism – Inheritance, Virtual Functions and Temp	blates	5					
	undling – Sequential and Random on, Insertion, Deletion and Traversal in Linked List – Sir	olv	Doi	ıhlv	and			
Circula		1 <u>6</u> 1y,		lory	and			
	nentation of Queues – Arrays and Liked List							
-	nentation of Stacks – Arrays and Linked List							
-	on, Deletion and search in a binary search tree.							
-	nent Bubble Sort Quick sort and Heap sort							
	ation of graphs for solving DC/AC Circuits							
12. Applic	ation of OOPS for solutions to digital circuits.	—						
		Tota	-		s:45			
	mes: Upon successful completion of the course, students w							
	software skills for real time programming using the concep							
	and and apply the concepts of Inheritance, Exception and Fi	le ha	ndliı	ıg.				
	and and apply the concepts of Linear Data structures							
CO4: Underst	and and apply the concepts Non Linear Data structures							
CO5:Apply th	e concepts of oops and data structures to Electrical Engineer	ring.						
References:								
1. ISRD Gro	up, "Introduction to Object-oriented Programming and C++"	', Ta	ta M	cGr	aw-			
Hill Publis								
	hing Company Ltd., 2007.							
2. S. B. Lipp	hing Company Ltd., 2007. nan, Josee Lajoie, Barbara E. Moo, "C++ Premier", Fourth	Edit	ion,	Pear	son			
2. S. B. Lipp Education	man, Josee Lajoie, Barbara E. Moo, "C++ Premier", Fourth	Edit	ion,	Pear	son			
Education	man, Josee Lajoie, Barbara E. Moo, "C++ Premier", Fourth							
Education, 3. D. S. Mali	nan, Josee Lajoie, Barbara E. Moo, "C++ Premier", Fourth 2005 k, "C++ Programming: From Problem Analysis to Program							
Education, 3. D. S. Mali Edition, T	man, Josee Lajoie, Barbara E. Moo, "C++ Premier", Fourth 2005 k, "C++ Programming: From Problem Analysis to Program nomson Course Technology, 2007.	Desi	gn",					
Education, 3. D. S. Mali Edition, T 4. Thomas H	 man, Josee Lajoie, Barbara E. Moo, "C++ Premier", Fourth 2005 k, "C++ Programming: From Problem Analysis to Program nomson Course Technology, 2007. Cormen, Charles E. Leiserson, Ronald L.Rivest, Clifford S 	Desi	gn",					
Education, 3. D. S. Mali Edition, T 4. Thomas H "Introduct	man, Josee Lajoie, Barbara E. Moo, "C++ Premier", Fourth 2005 k, "C++ Programming: From Problem Analysis to Program nomson Course Technology, 2007.	Desi stein,	gn",	Thi	rd			

COs								POs					PSOs	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	3		2		3								3	
2	3		2	1	3								3	
3	3		2	1	3								3	
4	3		2	1	3								3	
5	3		2	3	3								3	

Semester – IV

Course	Course Title	L	Т	Р	С					
Code										
UMA2452	PROBABILITY AND STATISTICS FOR	2	1	0	3					
	ELECTRICAL ENGINEERING	2	1	0	3					
Objectives	The objective of this course is to enable the student to									
• Identi	fy the standard distributions and apply them in solving proble	ms.								
• Solve	problems in joint probabilities and to find correlation between	n the	m.							
• Perfo	m hypothesis testing using normal, t, F, chi square distributio	n								
• Evalu	ate the tests of significance in analysis of variance.									
Calculate the various statistical quality control measurements										
Unit I RANDOM VARIABLES										
Random V	Random Variables - Discrete and continuous random variables - Moments - I									
generating f	unctions - Binomial, Poisson, Uniform, Exponential, Normal	distr	ibuti	ons						
Unit II	TWO-DIMENSIONAL RANDOM VARIABLES			Ģ	9					
Joint distrib	utions - Marginal and Conditional distributions - Covariance	- Co	orrela	ation	and					
Linear regre	ssion									
Unit III	TESTS OF SIGNIFICANCE			ç	9					
Sampling di	stributions - small and large sample test - Test based on Norma	l and	lt dis	stribu	ition					
(Single and	difference of mean) - χ^2 -Test for goodness of fit, Independen	ce o	f attr	ibute	s-F					
test for vari	nnce.									
Unit IV	DESIGN OF EXPERIMENTS			ç	9					
One way an	d two-way classifications, Completely randomized design, R	land	omiz	ed b	lock					
design, Lati	n square design									
Unit V	STATISTICAL QUALITY CONTROL			Ģ	9					
Control cha	rts for measurements (\overline{X} and R charts) - Control charts for attri	ibute	es (p,	c an	d np					
charts) - To	erance limits - Acceptance sampling									
	Total I	Perio	ods	4	5					
Course Ou	comes: Upon successful completion of the course, students w	vill b	e abl	e to						
CO1: Identi	fy standard distributions and apply them.									
CO2: solve problems in two dimensional random variables and find the correlation										

between them.

CO3: Identify and apply the suitable testing of hypothesis under normal, t, F and chi square distribution

CO4: Solve problems in analysis of variance.

CO5: Analyze quality control by applying control chart methods.

CO6: Application of Design of Experiments in engineering problems

Text Books:

- 1. Milton, J. S. and Arnold, J.C., Introduction to Probability and Statistics, Tata McGraw-Hill, New Delhi, 4th Edition, 2014.
- 2. Johnson, R.A. and Gupta, C.B., Miller and Freund's Probability and Statistics for Engineers, Pearson Education, Asia, 9th Edition, 2016.

- 1. Devore, J.L., Probability and Statistics for Engineering and the Sciences, Thomson Brooks/Cole, International Student Edition, New Delhi, 8th Edition, 2012.
- 2. Walpole, R.E., Myers, R.H., Myers, S.L. and Ye, K., Probability and Statistics for Engineers and Scientists, Pearson Education, Asia, 9th Edition, 2012.
- 3. Ross, S.M., Introduction to Probability and Statistics for Engineers and Scientists, Elsevier, New Delhi, 5th Edition, 2014.
- 4. Spiegel, M.R., Schiller, J. and Srinivasan, R.A., Schaum's Outline of Theory and Problems of Probability and Statistics, Tata McGraw Hill, New Delhi, 3rd Edition, 2017.
- 5. Gupta, S.C and Kapoor, V.K., Fundamentals of Mathematical Statistics, Sultan and Chand Company, New Delhi, 12th Edition, 2020.

COs		POs												
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	3	2												
2	3	2												
3	3	2												
4	3	2		1										
5	3	2												
6	3	2										1		

Course Title	L	Τ	Р	С							
INDIAN CONSTITUTION	3	0	0	0							
ch history and philosophy of Indian constitution.											
• To summarize powers and functions of Indian government.											
• To explain structure and functions of local administration.											
ſ	INDIAN CONSTITUTION ch history and philosophy of Indian constitution. nmarize powers and functions of Indian government.	INDIAN CONSTITUTION 3 ch history and philosophy of Indian constitution. and functions of Indian government.	INDIAN CONSTITUTION30ch history and philosophy of Indian constitution.nmarize powers and functions of Indian government.	INDIAN CONSTITUTION300							

• To c	lemonstrate the organization and working of the Judiciary.	
• To a	liscuss financial power and emergency provisions.	
Unit I	INTRODUCTION	9
	background – Government of India act – Indian councils act – Makin -Philosophy of the Indian constitution – Preamble.	ng of the
Unit II	GOVERNMENT OF THE UNION	9
	Functions of President and Prime Minister - Council of Ministers – Prenis council - Legislature structure and functions of LokSabha and Ra	
Unit III	GOVERNMENTS OF THE STATES AND LOCAL GOVERNMENT	9
legislature.l	executive: General structure – Governor – Council of ministers Local government - Panchayat –Municipality– Power author ties municipalities.	
Unit IV	THE JUDICATURE	9
-	on and Composition of Judiciary – Constitution – Appointment - Quality d functions of the supreme court– High courts – Control over subordina	
Unit V	THE FEDERAL SYSTEM	9
	n of financial powers: Need, principles-Underlaying distribution of tax r n of legislative power – Interstate relation - Emergency provisions.	evenues-
	Total Periods	45
	tcomes: Upon successful completion of the course, students will be abl	e to
	rstand history and philosophy of Indian constitution.	
	ze powers and functions of Indian government.	
-	ire awareness on structure and functions of local administration. nce knowledge about organization and composition of judiciary.	
	bre the distribution of financial powers and emergency provisions.	
Text Books		
	u D.D, "Introduction to Indian Constitution", Prentice Hall of India, Ne	w Delhi,
-	ta D.C, "Indian Government and Politics", Vikas Publishing House, Ne hi, 2010.	ew
References		
-	e M.V, "Introduction to the Constitution of India", lishing House, New Delhi, 2011.	Vikas
2. Kas	hyap S, "Our Constitution", National Book Trust, New Delhi, 2010.	
3. The	Constitution of India, 1950 (Bare Act), Government Publication.	
4. Jain	M P, Indian Constitution Law, 7thEdition., Lexis Nexis, 2014.	
	i S N, Ambedkar B R framing of Indian Constitution, 1stEdition, 2015.	

COs	POs										PSOs			
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1						2		2	2	2		2		
2						2		2	2	2		2		
3						2		2	2	2		2		
4						2		2	2	2		2		
5						2		2	2	2		2		

Course	Course Title	L	Τ	Р	С
Code					
UEE2401	ELECTRICAL MACHINES-I	3	0	0	3
Objectives:					
To kno	ow about the principles of electromechanical energy conver-	sion	in si	ingly	and
multip	ly excited systems.				
To stu	dy the construction, working principles and characteristics	of l	DC g	gener	ator
and D	C motor				
• To und	lerstand the starting process, speed control methods and test	s of	DC	moto	rs.
• To re	alize the constructional details, principle of operation	n, p	oredi	ction	of
perform	mance, testing methods of single phase transformer				
To kno	ow about three phase transformer connections and instrument	t tra	nsfo	rmer	s.
Unit I N	AGNETIC CIRCUITS			9)
Basic magnet	ic circuit analysis - Magnetization characteristics (BH cur	ves)	– B	H lo	op -
hysteresis and	d eddy-current losses. Magnetically induced EMF and for	orce	– E	nerg	y in
	em - field energy and mechanical force – electromagnetic en	ergy	v con	versi	on -
singly and dou	ably excited magnetic field systems.				
	DC GENERATOR			-)
	l features of DC machines - lap and wave windings - princi				
-	n – types of DC generators – commutation - Armature reac			-	
	ation - external and internal or total characteristics - Para	allel	ope	ratio	n of
Generators.					
	DC MOTOR)
	peration, types of DC motors – Torque and speed of DC moto				
	haracteristics - Starting, speed control and braking of DC				
-	notors - Losses in DC machines, Efficiency- Swinburne's and	l Ho	pkin	son's	test
	nagnet DC motors (PMDC) and its applications.				
	TRANSFORMER)
	ciple-Construction, Core-type and Shell type transformers-				
-	n, performance of transformer on no load and loaded con				
diagrams - Ec	quivalent circuit - open circuit and short circuit test - Vo	ltage	e reg	gulati	on -

ope	ation of single-phase transformer.	
Un	V TRANSFORMER: THREE PHASE	9
Th	e phase transformer connections – Open Delta Connection- Scott connections.	. Three
pha	e to single phase conversion- parallel operation of three phase transformers. Inst	trumen
Tra	sformers – Current Transformer, Potential Transformer	
	Total Periods	45
	·	
Co	rse Outcomes: Upon successful completion of the course, students will be able	to
CC	: Apply the principles of electromechanical energy conversion in singly and m	nultiply
exc	ted systems.	
CC	: Describe the construction, working principle and characteristics of DC general	tor
CC	: Illustrate various speed control methods, necessity of starters and performance	9
ass	ssment of DC motor.	
CC	: Analyze the performance of single phase transformers	
CC	: Describe the principle of various three phase transformer and instrument	
trai	formers	
CC	: Design and evaluate the suitability of DC machines and transformers for the g	jiven
app	ication.	
Te	Books:	
1.	Nagrath, I.J. and Kothari.D.P., Electric Machines', McGraw-Hill Education, 200)4
2.	Fitzgerald. A.E., Charles Kingsely Jr, Stephen D.Umans, 'Electric Machinery', S	Sixth
	dition, McGraw Hill Books Company, 2003.	
Re	rences:	
1.	Stephen J. Chapman, 'Electric Machinery Fundamentals'4th edition, McGraw H	lill
	Education Pvt. Ltd, 2010.	
2.	Theodore Wildi, "Electrical Machines, Drives, and Power Systems", Pearson	
	Education., (5th Edition), 2002.	
3.	B.L.Theraja and A.K.Theraja, 'A Textbook of Electrical Technology Vol II AC	and
	DC Machines.	
4.	3.R. Gupta,'Fundamental of Electric Machines' New age International Publishe	ers,3rd
	Edition ,Reprint 2015.	
5.	S.K. Bhattacharya, 'Electrical Machines' McGraw - Hill Education, New Delhi,	3rd
	Edition, 2009.	
		C
6.	P.C. Sen'Principles of Electric Machines and Power Electronics' John Wiley &	Sons;

7. K. Murugesh Kumar, 'Electric Machines', Vikas publishing house Pvt Ltd, 2002.

COs													PSOs	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	3	2	1	2						1		1	1	3
2	3	2	1	2						1		1	1	3
3	3	2	1	2						1		1	1	3
4	3	2	1	2						1		1	1	3
5	3	2	1	2						1		1	1	3

Course	Course Title	L	Т	Р	С
Code					
UEE2402	ANALOG ELECTRONIC CIRCUITS	3	0	0	3
Objectives:					
• To fa	miliarize the signal analysis using Op-amp based circuits.				
• To u	nderstand the applications of Op-amp.				
• To s	tudy the functional blocks and applications of special ICs	like	Tim	ers, 1	PLL
circu	its, regulator circuits.				
	now the IC fabrication procedure.				
Unit I	IC FABRICATION			9	
including pa	tion, fundamental of monolithic IC technology – basic silicon ackaging, Fabrication of typical circuit, Fabrication of res ETs, Thin and Thick film technology.				
Unit II	CHARACTERISTICS OF OPAMP			9	
characteristi rate, Differe	block diagram of op-amp IC741, Ideal op-amp chacs, AC characteristics, frequency compensation and stability ential amplifier, Basic applications of op-amp – Inverting a voltage follower.	of	op-a	mp, s	slew
Unit III	APPLICATIONS OF OPAMP			9	
Instrumentat second order Clippers, Cl	fferentiator & Integrator, Voltage to Current and Current to V cion amplifier, Log and Antilog Amplifiers. Characteristics of cactive Butterworth filters. Comparators, Multivibrators, Wav ampers, Peak detector, Sample & Hold circuit. DAC (R- 2R la ted resistor) and ADC (Flash, Successive approximation, Dua fications.	f filt efor adde	ers, m ge r, In	First enerativerte	and tors, d R-
Unit IV	SPECIAL ICs			9	
	lock, characteristics, modes & applications of 555 Timer IC, scillator IC, 565-phase lock loop IC, Analog multiplier ICs.	566	volta	ıge	
Unit V	APPLICATION ICs			9	
regulators L	egulators – Fixed voltage regulators LM78XX & LM79XX - M317 & IC723, Concept of Switching regulator- Schematic di M 380 power amplifier- ICL 8038 function generator IC.				
	Total I	Perio	ods	45	

Course Outcomes: Upon successful completion of the course, students will be able to	
CO1. Describe the IC fabrication steps and their integrated sequence to fabricate Silicor	n
devices and ICs.	
CO2. Describe the Characteristics of Op-amps.	
CO3. Design the Op-amp circuits for basic applications with feedback using passive components and diodes.	
CO4. Design the Op-amp circuits for reasonably complex applications such as	
multivibrators, filters and oscillators.	
CO5. Illustrate the internal functional blocks and the applications of special ICs like	
Timers, PLL, Regulator, Analog Multiplier, etc.	
Text Books:	
1. D. Roy Choudhury, Shail B. Jain, 'Linear Integrated Circuits', II edition, New Age,	
2003.	
2. Ramakant A. Gayakward, 'Op-amps and Linear Integrated Circuits', IV edition,	
Pearson Education, 2003 / PHI, 2000	
References:	
1. S. Salivahanan and V. S. Kanchana Bhaaskaran, "Linear Integrated Circuits" McGra	W
Hill Edition, New Delhi, 2 nd edition, 2018.	
2. David A. Bell, 'Op-amp & Linear ICs', Oxford, 2013.	
3. Fiore,"Opamps& Linear Integrated Circuits Concepts & Applications", Cengage, 201	10.
4. Floyd ,Buchla,"Fundamentals of Analog Circuits, Pearson, 2013.	
5. Jacob Millman, Christos C.Halkias, 'Integrated Electronics - Analog and Digital	
circuits system', Tata McGraw Hill, 2003.	
6. Robert F. Coughlin, Fredrick F. Driscoll, 'Op-amp and Linear ICs', PHI Learning, 6th	h

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6. Robert F. Coughlin, Fredrick F. Driscoll, 'Op-amp and Linear ICs', PHI Learning, 6th edition, 2012.

COs					POs							PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	3											1	1	3
2	3												1	3
3	3		2	1								1	1	3
4	3	1	3	1	2							1	1	3
5	3												1	3

Course	Course Title	L	Τ	Р	C
Code					
UEE2476	CONTROL SYSTEMS ENGINEERING	3	0	0	3
Objectives:					
• To exp	lain the importance of transfer function in modelling physic	al sy	ysten	ns	
• To ana	lyse any system with respect to time domain and frequency	dom	nain		
• To exp	lain the stability of the system				

I	cifications and to improve the stability of the system.	Δ
Unit I	SYSTEMS AND THEIR REPRESENTATION	9
	ents in control systems – Open and closed loop systems – Electrical a	
	and thermal systems – Transfer function – Synchros – AC and DC ser	vomotors
	agram reduction techniques – Signal flow graphs	
Unit II	TIME RESPONSE	9
-	onse – Time domain specifications – Types of test input – I and II ord	-
	Error coefficients – Generalized error series – Steady state error – R	
	n- Effects of P, PI, PID modes of feedback control –Time response	analysis ·
-	ation using MATLAB	
Unit III	FREQUENCY RESPONSE	9
	response – Bode plot – Polar plot – Nyquist plot- Constant M - N circles	
	ermination of closed loop response from open loop response - Correlation	
	domain and time domain specifications- Implementation using MATLA	AB
Unit IV	STABILITY AND COMPENSATOR DESIGN	9
	stics equation - Routh Hurwitz criterion - Performance criteria - Lag	
-	tworks - Effect of Lag, lead and lag-lead compensation on frequency	-
analysis -	Design of compensator network using Bode plot Implementation	on using
MATLAB		
Unit V	STATE VARIABLE ANALYSIS	9
-	state variables – State models for linear and time invariant Systems – S	
state and o	utput equation in controllable canonical form - Concepts of controlla	bility and
observabili	ty – Implementation using MATLAB	
	Total Periods	45
Course Oi	Itcomes: Upon successful completion of the course, students will be ab	le to
	ve transfer function for a given physical system (K3)	
	yse a system in both time domain and frequency domain (K3)	
	rmine the stability of a given system (K3)	
	gn and analyse a compensator for a given system specification (K4)	
	gn a controller to improve the stability of a given system (K3)	
Text Book		
	ahanan, R.Rengaraj, and G.R.Venkatakrishnan, "Control systems Engin	neering".
	n India Education, 2015.	, , ,
	th, I.J. and Gopal, M., "Control Systems Engineering", New Age Intern	national
-	ers, 2017.	
	in C. Kuo, "Automatic Control Systems", Wiley, 2014.	
Reference		
	iko Ogata, "Modern Control Engineering", Pearson India Education, 20)15
	C.Dorf and Bishop, R.H., "Modern Control Systems", Pearson India	
2. Richard	$\mathbf{V} = \mathbf{D} \mathbf{O} \mathbf{U} = \mathbf{M} \mathbf{O} \mathbf{O} \mathbf{U} = \mathbf{V} \mathbf{O} \mathbf{O} \mathbf{U} \mathbf{O} \mathbf{U} = \mathbf{O} \mathbf{U} \mathbf{U} \mathbf{O} \mathbf{U} \mathbf{U} \mathbf{U} \mathbf{U} \mathbf{U} \mathbf{U} \mathbf{U} U$	

- 3. John J.D., Azzo Constantine, H. and HoupisSttuart, N Sheldon, "Linear Control System Analysis and Design with MATLAB", CRC Taylor& Francis Reprint 2009.
- 4. RamesC.Panda and T. Thyagarajan, "An Introduction to Process Modelling Identification and Control of Engineers", Narosa Publishing House, 2017.
- 5. M.Gopal, "Control System: Principle and design", McGraw Hill Education, 2012.
- 6. NPTEL Video Lecture Notes on "Control Engineering "by Prof. S. D. Agashe, IIT Bombay.

COs								POs					PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	
1	3				1								3	2	
2	3	3		2									3	2	
3	3	3		2									3	2	
4	3	3		2									3	2	
5	3	3	3	2	3								3	2	

Course	Course Title	L	Т	Р	С
Code					
UEE2403	GENERATION TRANSMISSION AND	4	0	0	4
	DISTRIBUTION	4	0	0	4
Objectives:					
• To in	ntroduce various electric power generation principle along wi	th co	mpu	tatio	n of
elect	ric power tariff.				
• To d	etermine the various electrical parameter and to compute electrical	ctrica	ıl		
	ormance of overhead transmission line				
• To e	xplain the role of insulators in OHTL and underground cable	s.			
	tudy about DC and AC distribution systems along with variou		chnic	ues f	or
	age and power factor improvement.			L	
Unit I	GENERATION PRINCIPLES			1	2
Hydro-elect	ric power plants - Thermal power plants - Nuclear power p	lants	- R	enew	able
Power Plant	– Operation – Selection of Site - Power tariff types				
Unit II	TRANSMISSION LINE PARAMETER			1	2
Structure of	electric power system - Types of AC and DC distributors - El	HVA	C an	d HV	/DC
	- Resistance, Inductance and Capacitance calculations – Sing				
phase lines -	- double circuit lines – effect of earth on transmission line ca	paci	tance	- coi	rona
& proximity	v effect				
Unit III	PERFORMANCE OF TRANSMISSION LINE			1	2
Modeling of	f Transmission Line - short, medium and long transmission	lines	s - R	egula	tion
and efficien	ncy – ABCD constants - Power flow through a transmis	ssion	line	- SI	urge

Unit IV	MECHANICAL DESIGN OF TRANSMISSION LINE AND	12
	CABLES	12
Mechan	ical design of transmission line – sag and tension calculations for different	t weather
	ns, Tower spotting, Types of towers Insulators, Voltage distribution in su	
	rs – string efficiency – improving string efficiency - testing of i	-
	ound cables – Types of cables – insulation resistance – dielectric stress – g	
-	capacitance grading - intersheath grading.	U
Unit V	DISTRIBUTION SYSTEMS	12
	aspects – DC distribution systems - concentrated and distributed loads - r	adial and
	in systems – A.C. distribution – Single-phase and three phase	
	Total Periods	60
Course	Outcomes: Upon successful completion of the course, students will be abl	le to
	Understand the principles of power generation and various power tariff.	
	Determine the various transmission line parameters.	
	nalyze the performance of overhead transmission line.	
	ompute the voltage distribution, string efficiency, and dielectric stress for C	OHTL
and Cat		
CO5: A	nalyze the performance of DC and AC distribution systems	
	valuate and Summarize the concepts of transmission and distribution for a s	specific
real tim	e problem.	
Text Bo		
1. 1	Leonard L. Grigsby, "Electric Power Generation, Transmission, and Distrib	oution",
(CRC Press; 1st edition, 2007.	
	Wadhwa, C.L., 'Generation Distribution and Utilization of Electrical Energ	gy', New
2.	Age International Publishers, 3rd Edition, 2010.	
	rge international i ubilshers, sid Edition, 2010.	
	S.N. Singh, 'Electric Power Generation, Transmission and Distribution', Pre	entice
3.		entice
3.	S.N. Singh, 'Electric Power Generation, Transmission and Distribution', Pre Hall of India, Second edition 2008.	entice
3. Referen	S.N. Singh, 'Electric Power Generation, Transmission and Distribution', Pre Hall of India, Second edition 2008.	entice
3. Referen 1.	S.N. Singh, 'Electric Power Generation, Transmission and Distribution', Pre- Hall of India, Second edition 2008.	entice
3. Referen 1.	S.N. Singh, 'Electric Power Generation, Transmission and Distribution', Pre Hall of India, Second edition 2008. Ices: S. Sivanagaraju and S. Sathyanarayana, 'Electric Power Transmission and	
3	S.N. Singh, 'Electric Power Generation, Transmission and Distribution', Pre- Hall of India, Second edition 2008. Inces: S. Sivanagaraju and S. Sathyanarayana, 'Electric Power Transmission and Distribution', Pearson, 2009.	3
3. Referen 1. 2. 3. 3.	 S.N. Singh, 'Electric Power Generation, Transmission and Distribution', Pre-Hall of India, Second edition 2008. S. Sivanagaraju and S. Sathyanarayana, 'Electric Power Transmission and Distribution', Pearson, 2009. V.K. Mehta and Rohit Mehta, ' Principles of Power System', S. Chand, 201 	3
3. Referen 1. 2. 3. 4	 S.N. Singh, 'Electric Power Generation, Transmission and Distribution', Pre-Hall of India, Second edition 2008. S. Sivanagaraju and S. Sathyanarayana, 'Electric Power Transmission and Distribution', Pearson, 2009. V.K. Mehta and Rohit Mehta, 'Principles of Power System', S. Chand, 201 C L Wadhwa, "Electrical Power Systems", New Age Internationals; First E 	3 Edition

COs								Pos					PSC) s
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1	3	3		1	3			1						
2	3	3	2	1	3			1						
3	3	3	2	1	3			1					1	
4	3	3	2	1	3			1						
5	3	3		1	3			1						

Course	Course Title	L	Т	Р	С
Code					
UEE2411	ELECTRICAL MACHINES LAB-I	0	0	3	1.5
Objectives:					
To obt	ain practical knowledge in the characteristics of DC genera	tors			
• To gain	n practical knowledge in the characteristics DC motors				
• To acq	uire practical knowledge in the characteristics of transform	ers			

List of Experiments:

- 1. Open circuit and load characteristics of DC shunt generator
- 2. Load characteristics of DC compound generator
- 3. Load characteristics of DC series generator
- 4. Load characteristics of DC shunt and compound motor
- 5. Load characteristics of DC series motor
- 6. Swinburne's test and speed control of DC shunt motor
- 7. Hopkinson's test
- 8. Load test on single phase transformer
- 9. Load test on three phase transformer
- 10. Open circuit and short circuit tests on single phase transformer
- 11. Sumpner's test
- 12. Separation of no-load losses in single phase transformer

Total Periods:45

Course Outcomes: Upon successful completion of the course, students will be able to
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- CO1: Characterize DC shunt, series and compound generators through measurements and interpretation.
- CO2: Characterize DC shunt, series and compound motors through measurements and interpretation.
- CO3: Characterize single phase and three phase transformers through measurements and interpretation.
- CO4: Characterize DC motors and transformers under no-load condition

References:

- 1. Nagrath, I.J. and Kothari.D.P., Electric Machines', McGraw-Hill Education, 2004
- 2. Fitzgerald. A.E., Charles Kingsely Jr, Stephen D.Umans, 'Electric Machinery', Sixth edition, McGraw Hill Books Company, 2003.
- 3. Stephen J. Chapman, 'Electric Machinery Fundamentals'4th edition, McGraw Hill Education Pvt. Ltd, 2010.
- 4. Theodore Wildi, "Electrical Machines, Drives, and Power Systems", Pearson Education., (5th Edition), 2002.
- 5. B.L.Theraja and A.K.Theraja, 'A Textbook of Electrical Technology Vol II AC and DC Machines.
- 6. B.R. Gupta, 'Fundamental of Electric Machines' New age International Publishers, 3rd Edition ,Reprint 2015.
- 7. S.K. Bhattacharya, 'Electrical Machines' McGraw Hill Education, New Delhi, 3rd Edition, 2009.
- 8. P.C. Sen'Principles of Electric Machines and Power Electronics' John Wiley & Sons; 3rd Edition 2013.
- 9. K. Murugesh Kumar, 'Electric Machines', Vikas publishing house Pvt Ltd, 2002.

COs								POS					PSC	Os
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	2	2	1	3				1	3	1			2	3
2	2	2	1	3				1	3	1			2	3
3	2	2	1	3				1	3	1			2	3

Course	Course Title	L	Т	Р	С
Code					
UEE2412	ANALOG ELECTRONIC CIRCUITS LAB	0	0	3	1.5
Objectives:					
• To	o design and test the applications of Op-amps.				
• To	b learn the basic modes of IC555 ICs.				
• To	b design and test additional applications of analog ICs using	softv	vare		
List of Exper	iments:				
1. Measurer	nent of input bias current, input offset current and input offset	et vo	ltage	e of (Dp-
Amp IC.					
2. Measurer	nent of slew rate of µA741 IC				
-	f basic Op-amp applications using IC741: inverting and non- s, & voltage follower	-inve	erting	5	
-					

- 4. Testing of Adder, Subtractor and comparator circuits using Op-amp
- 5. Testing of Integrator and Differentiator circuits using Op-amp.
- 6. Timer NE/SE555applications: Astable, Monostable Operations.

- 7. Study of DC Characteristics of two different Op-amp packages using simulation software.
- 8. Study the frequency response of Op-amp IC.
- 9. Comparative study of differential amplifier and Instrumentation amplifier using Op-Amps.
- 10. Study of waveform generators using Op-amp: Sine, Triangular & Square.
- 11. Study of VCO & PLL.

Total Periods: 45

Course Outcomes: Upon successful completion of the course, students will be able to

CO1: Characterize IC741 Op-Amp and realize various applications

CO2: Realize astable and monostable multivibrators using IC555 timer

CO3: Use the software simulators like PSpice for analysis of analog ICs.

References:

- 1. D. Roy Choudhury, Shail B. Jain, 'Linear Integrated Circuits', II edition, New Age, 2003.
- 2. Ramakant A. Gayakward, 'Op-amps and Linear Integrated Circuits', IV edition, Pearson Education, 2003 / PHI, 2000

COs								POs					PSO	8
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	3		3						2				1	
2	3		2						2				2	1
3	3	2	3	2	2				2			1	2	1

SEMESTER V

Course	Course Title	L	Т	Р	С				
Code									
UEE2501	POWER ELECTRONICS	3	0	0	3				
Objectives:									
• To understand the characteristics of power semiconductor devices									
• To understand the operation of AC-DC, DC-DC, DC-AC and AC-AC power									
converters									
Unit IPOWER SEMI-CONDUCTOR DEVICES9									
Study of sw	itching devices - SCR, TRIAC, GTO, BJT, MOSFET, IGBT	and	IGC	T, S	tatic				
characterist	cs - SCR, MOSFET and IGBT, Introduction to Silicon carba	ide (SiC)	devi	ices,				
Triggering a	Triggering and commutation circuit for SCR, Introduction to Driver and snubber circuits.								
Unit IIPHASE-CONTROLLED CONVERTERS9									
2-pulse, 3-pulse and 6-pulse converters- performance parameters -Effect of source									
inductance - Firing Schemes for converter-Dual converters, Applications-light dimmer,									
Excitation system, Solar PV systems.									
Unit IIIDC TO DC CONVERTERS9									

Unit IV INVERTERS	9
Single phase and three phase voltage source inverters (both120 mode and 1	
Voltage & harmonic controlPWM techniques: Multiple PWM, Sinusoidal PWI	
harmonic elimination – Introduction to space vector modulation –Single-pha	ise Currei
source inverter, Applications-Induction heating, UPS.	
Unit V AC TO AC CONVERTERS	9
Single phase and Three phase AC voltage controllers-Control strategy- Po	
Control –Multistage sequence control -single phase and three phase cyclo c	onverters
Introduction to Matrix converters, Applications –welding.	
Total Period	s 45
Course Outcomes: Upon successful completion of the course, students will be a	able to
CO1: Describe the characteristics of power semiconductor devices	
CO2: Analyse the operation and performance of phase-controlled rectifiers	
CO3: Examine the operation and control of DC – DC converters	
CO4: Discuss the operation and switching strategies of $DC - AC$ and $AC - AC$	converters
CO5: Select an appropriate power converter and illustrate its characteristics for s	specific
applications	
Text Books:	
1. M.H. Rashid, 'Power Electronics: Circuits, Devices and Applications', Pearson	'n
Education, Third Edition, New Delhi, 2004.	
2.P.S.Bimbra "Power Electronics" Khanna Publishers, third Edition, 2003.	
References:	
1. Ashfaq Ahmed 'Power Electronics for Technology', Pearson Education, India 2003.	n reprint,
 Joseph Vithayathil,' Power Electronics, Principles and Applications', McGrav Series, 6th Edition, 2013. 	v Hill
3. Philip T. Krein, "Elements of Power Electronics" Oxford University Press, 20 Edition.	04
4. L. Umanand, "Power Electronics Essentials and Applications", Wiley, 2010.	
5.Ned Mohan Tore. M. Undel and, William. P. Robbins, 'Power Electronics:	Converter
Applications and Design', John Wiley and sons, third edition, 2003.	
6.S.Rama Reddy, 'Fundamentals of Power Electronics', Narosa Publications, 20	14.
-	
7. M.D. Singh and K.B. Khanchandani, "Power Electronics," Mc Graw Hill Indi	a, 2013.

COs								POs					PSO	s
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	1		1	1	1									2
2	3		2	2	2								1	3
3	3		2	2	2								2	3
4	3		2	2	2								1	2
5	3		2	2	2									2

Course	Course Title	L	Τ	Р	С			
Code					I			
UEE2502	ELECTRICAL MACHINES II	3	0	0	3			
Objectives:								
• To int	roduce various types of AC Electrical Machines and fraction	al K	W n	notor	S			
	miliarize the construction and performance of synchronour ronous motor.	is ge	enera	ators	and			
-	idy the construction, working principle and performance of	f sin	gle a	and f	hree			
	induction machines.	. 5111	5.0 .		mee			
1	derstand the starting and speed control of three-phase inducti	ion r	noto	rs.				
	idy the construction, principle of operation and performance				KW			
motor								
Unit I	FUNDAMENTALS OF AC MACHINES			Ģ)			
Types of AC	Machines: Synchronous machines and Induction machines	- C(omp	onent	s of			
rotating AC n	nachines - stator, rotor and armature windings - Generated EM	/IF o	f AC	wind	ding			
- Distribution	a factor - Chording factor - MMF of distributed windings -	Mag	gneti	c fiel	d in			
rotating mach	ninery - Concept of rotating flux - Relationship between ele	ectri	cal f	reque	ency			
and the speed	of rotating magnetic field.							
Unit II	SYNCHRONOUS GENERATORS			ç)			
Basic princip	le - types- salient and cylindrical pole rotor, equivalent circu	it - E	EMF	equa	tion			
armature read	ction - alternator on load - synchronous reactance - voltage r	egul	latio	n - E	MF,			
	nd A.S.A methods - power developed by a synchronous ge			-				
angle charact	eristics - Synchronizing and parallel operation – Synchronizin	g tor	rque	- Cha	inge			
of excitation and mechanical input - Two reaction theory.								
	SYNCHRONOUS MOTOR			9	-			
-	peration - Equivalent circuit - Power and Torque equation -	-		-				
	ed V curves - Method of Starting - Current loci for const		-		÷ .			
	itation and constant power developed - Hunting - natu	ral	frequ	uency	/ of			
	damper windings- synchronous condenser.							
	INDUCTION MOTOR			9				
Principle of o	operation - Types - Squirrel cage rotor - slip ring rotor - s	lip -	cog	ging	and			

crawling- Equivalent circuit – Torque-Slip characteristics - Condition for maximum torque – Losses and efficiency - parameter determination from no-load and blocked rotor tests -Circle Diagram Starting and speed control-Braking Methods-Induction generator.

Unit V SINGLE PHASE INDUCTION AND SPECIAL MOTORS

Double revolving field theory – Equivalent circuit – Starting methods of single-phase induction motors – Constructional features and Working principle: Capacitor-start capacitor run Induction motor- Shaded pole induction motor - Repulsion motor - AC series motor - Universal motor - Reluctance motor - Hysteresis motor.

Total Periods 45

9

Course Outcomes: Upon successful completion of the course, students will be able to

CO1: Explain the fundamentals of AC machines and the basic principles of emf, mmf generation in the machine windings.

CO2: Acquire knowledge on the constructional features, working and performance evaluation methods of synchronous machines

CO3: Describe the construction, principle and analyze performance characteristics of three phase induction motors.

CO4: Explain the constructional features of single-phase induction motors and other fractional KW motors.

CO5: Evaluate the performance of synchronous and induction machines to assess suitability for domestic and industrial applications.

Text Books:

1.Nagrath, I.J. and Kothari.D.P., Electric Machines', McGraw-Hill Education, 2004

2. Fitzgerald. A.E., Charles Kingsely Jr, Stephen D.Umans, 'Electric Machinery', Sixth edition, McGraw Hill Books Company, 2003.

References:

- 1. Stephen J. Chapman, 'Electric Machinery Fundamentals'4th edition, McGraw Hill Education Pvt. Ltd, 2010.
- 2. Theodore Wildi, "Electrical Machines, Drives, and Power Systems", Pearson Education., (5th Edition), 2002.
- 3.B.L.Theraja and A.K.Theraja, 'A Textbook of Electrical Technology Vol II AC and DC Machines
- 4. S.K. Bhattacharya, 'Electrical Machines' McGraw Hill Education, New Delhi, 3rd Edition, 2009
- 5. B.R. Gupta ,'Fundamental of Electric Machines' New age International Publishers,3rd Edition ,Reprint 2015
- P.C. Sen'Principles of Electric Machines and Power Electronics' John Wiley & Sons; 3rd Edition 2013

7. K. Murugesh Kumar, 'Electric Machines', Vikas publishing house Pvt Ltd, 2002.

COs								POs					PSO	s
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	3	2	1									1	1	3
2	3	2	1	2								1	1	3
3	3	2	1	2								1	1	3
4	3	2	1	2								1	1	3
5	3	2	1	2	1		1		1	1		1	1	3

Course	Course Title	L	Т	Р	С
Code					
UEE2503	ELECTRICAL MEASUREMENTS AND	3	0	0	3
	INSTRUMENTATION SYSTEMS				
Objectives:					
To impart k	nowledge on the following Topics				
• Basi	c functional elements of instrumentation				
• Fund	lamentals of electrical and electronic instruments				
• Com	parison between various measurement techniques				
• Vari	ous storage and display devices				
• Vari	ous transducers and the data acquisition systems				
Unit I	INTRODUCTION			Ģ)
Functional	elements of an instrument – Static and dynamic characteri	stics	s – 1	Error	s in
measuremen	t - Statistical evaluation of measurement data - Standards	and	d cal	librat	ion-
Principle an	d types of analog and digital voltmeters, ammeters.				
				1	
Unit II	ELECTRICAL AND ELECTRONIC INSTRUMENTS			Ç)
Principle an	d types of multi meters – Single and three phase watt meters a	ind e	energ	gy me	eters
- Magnetic	measurements - Determination of B-H curve and measureme	ents	of ir	on lo	ss –
Instrument t	ransformers - Instruments for measurement of frequency and	phas	se		
Unit III	COMPARATIVE METHODS OF MEASUREMENTS			Ģ)
D.C and A.	C potentiometers, D.C (Wheat stone, Kelvin and Kelvin Doub	ole b	ridge	e) &	A.C
bridges (Ma	xwell, Anderson and Schering bridges), transformer ratio bridg	jes, s	elf-t	oalan	cing
bridges. Int	erference& screening – Multiple earth and earth loops -	Elec	tros	tatic	and

U	terreneede sereening	1
electromag	netic Interference – Grou	nding techniques.
U		6 1
Unit IV	STORAGE AND DISI	PLAY DEVICES

9

Magnetic disk and tape recorders, Graphic recorder, Oscillographic recorder, digital plotters and printers, Cathode ray oscilloscope (CRO), CRT display, digital CRO, LED, LCD & Dot

matrix dis	play – Data Loggers.	
Unit V	TRANSDUCERS AND DATA ACQUISITION SYSTEMS	9
Classifica	tion of transducers - Selection of transducers - Resistive, capacitive & i	nductive
Transduce	ers - Piezoelectric, Hall effect, optical and digital transducers - Element	s of data
acquisitio	n system – Smart sensors-Thermal Imagers.	
	Total Periods	45
<u> </u>		
	Putcomes: Upon successful completion of the course, students will be able	
-	lain the basic functional elements of any electrical and electronic instrum	lent
	npare various principles and techniques involved in measurement	
	strate the concept of different storage and display devices	
	nonstrate the knowledge about various transducers and data acquisition s	ystems
	ntify an appropriate instrument for a particular application	
Text Boo		
	K. Sawhney, 'A Course in Electrical & Electronic Measurem	nents &
	strumentation', DhanpatRai and Co, 2010.	
	B. Gupta, 'A Course in Electronic and Electrical Measurements', S. K. K.	ataria&
	ns, Delhi, 2013.	
	ebelin E.O. and Manik D.N., Measurement Systems - Applications and	Design,
	ecial Indian Edition, McGraw Hill Education Pvt. Ltd., 2007.	
	Salivahanan, R. Rengaraj, G. R. Venkatakrishnan, " Measureme	ents and
	strumentation" McGraw Hill, 2018.	
Reference		
	alsi, 'Electronic Instrumentation', McGraw Hill, III Edition 2010.	
2. D.V.S.	Murthy, 'Transducers and Instrumentation', Prentice Hall of India Pvt Lt	d, 2015.
3. David I	Bell, 'Electronic Instrumentation & Measurements', Oxford University	
Press	,2013.	
4. Martin	Reissland, 'Electrical Measurements', New Age International (P) Ltd., D	elhi,
2001.		
	. Morris, Principles of Measurements and Instrumentation, 2nd Edition, H	Prentice
Hall	of India, 2003.	

	POs PSOs										s			
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COs														
1	3												3	
2	3	2		2									3	
3	3			2									3	
4	3			2									3	
5	3		3	3		2						3	3	2

Course	Course Title	L	Т	EL	Р	C
Code						
UEE2504	DIGITAL LOGIC SYSTEM DESIGN AND	3	0	3	1	4.5
01:	PRACTICES					
Objectives:	dy Boolean functions and combinational circuits.					
	sign various synchronous circuits.					
	roduce asynchronous sequential circuits and PLDs.					
	roduce algorithmic state machine and data paths.					
	roduce design of control unit and small processor					
	DIGITAL PRINCIPLES & COMBINATIONAL LOGI	С			9+3	
Introduction Practice – Demultiplexe Design and te	Combinational Circuits, Fundamentals of Microp o FPGA & VHDL. Design and testing of Multi-input and Multibit-input r using VHDL. sting of Adders, Subractors, Comparators, Encoders & Dec	- C	Gates rs us	s, Mu ing VI	ltiple HDL	exer,
Studio - Desi	gn and Implement 16-bit Arithmetic and logic Unit using V	'HD	L in	FPGA	L	
Unit II	SYNCHRONOUS SEQUENTIAL LOGIC CIRCUITS				9+3	
Synchronous	ops-Concept of State: Table, Diagram, Reduction & A Sequential circuits using Mealy & Moore Models esign and testing of Flip-Flops, Shift Registers, Free running VHDL	U			U	
	ign and Implement 16-bit Program Counter Unit using VH	DL i	n FP	GA		
	ASYNCHRONOUS SEQUENTIAL LOGIC CIRCUITS				9+3	
Transition tal of Asynchro Programmabl	le – Primitive flow table – Implication Table - Race conditi nous Sequential Logic Circuits – Realization of Flip e Logic Devices: PROM, PLA, PAL & CPLD	on – flop	os. I	ntrodu	Ana action	n to
Practice - De VHDL	sign of Asynchronous Sequential Circuits – Ripple counter	r, mo	odulo	o cour	iter u	ising
Studio - Desi	gn of a Real-Time PWM signal Generation with counter us	ing V	/HD	L in F	PGA	ι.
Unit IV	ALGORITHMIC STATE MACHINE & DATA PATHS)			9+3	
PLAs & PRC	- ASM Transition & Excitation Tables- ASM Realization MS. Synchronous Sequential Circuit Design using ASM C	hart-	Dat	a path	s: Siı	nple
-	eration, Multiple Arithmetic OperationsDesign of Dedica SE, Counting 1-to-n, Summation n down to 1 and factorial			Paths	– Sii	npie

Studio - Design and Implement a Digital logic circuit for measuring speed using Encoder using VHDL in FPGA.

Unit V	DESIGN OF CONTROL UNIT & DEDICATED	9+3
	MICROPROCESSORS	

Deriving control words for Data Paths-Design of control unit- Simple IF THEN ELSE, Counting 1-to-n, Summation n down to 1. Generating status signals. Standalone controllers. Design of Dedicated Microprocessor - Largest numbers, Summation of Unsigned numbers & Greatest common devisor.

Practices – VHDL Design of Dedicated Data paths & Control units for IF THEN ELSE, Counting, Summation procedures.

Studio- Design and Implement an Instruction Decoder using VHDL in FPGA.

Course Outcomes: Upon successful completion of the course, students will be able to

CO1: Understand the digital principles and design of combinational logic circuit using VHDL.

CO2: Analysis and design of synchronous sequential logic circuits.

CO3: Analysis and design of Asynchronous Sequential Circuits.

CO4: Understanding the concept of ASM and Data paths for Synchronous Sequential Circuit design.

CO5: Design of customized microprocessor.

Text Books:

1.Donald D Givone, 'Digital Principals and Design', Tata McGraw-Hill, 2009.

- 2. Enoch O. Hwang, 'Digital Logic and Microprocessor Design with VHDL', Thomson-Indian Edition, 2007.
- 3. Noman Nisam& Shimon Schocken, "Elements of Computing Systems- Building a Modern computer from first principles ", MIT Press Cambridge: London; 2005.

References:

1. Alan B.Marcovitz., "Introduction to Logic and Computer Design", Tata McGraw-Hill, 2009.

2.M.Morris Mano & Charles R.Kime, "Logic and Computer Design Fundamentals", Pearson, 2014.

3. Albert Paul Malvino& Jerald A Brown, "Digital computer Electronics", Glencoe McGraw-Hill., 1999

Cos			POs												PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12		1	2		
1	3	1	3	3	3				2	1	2	1		2	1		
2	3	3	3	3	3				2	1	2	1		2	1		
3	3	3	3	3	3					1		1			1		
4	3		3	3	3					1		1			1		
5	3		3	3	3	1	1	1	3	1	3	1		3	1		
Co	ourse		Course Title										Т	P	C		

Code					
UEE2511	ELECTRICAL MACHINES LAB – II	0	0	3	1.5
Objectives:				1	1
• To exp	ose the students to the operation of synchronous machine	es a	nd i	nduc	ction
-	and give them experimental skill.				
List of Experi					
-	ation of voltage regulation of three phase alternator by EMF	F. M	MF	and	ZPF
method		,			
2. Determinati	on of voltage regulation of three phase salient pole alternator	r by	slip	test	
	on of negative and zero sequence impedance of three phase	•	-		
	three phase alternator				
	on of V and inverted V curves of three phase synchronous m	iotoi			
	three phase squirrel cage induction motor				
	blocked rotor test on three phase squirrel cage induction mo	otor			
	single phase induction motor				
	blocked rotor test on single phase induction motor				
	rol of three phase slip ring induction motor using rotor resista	ance	and	vari	able
frequency met					
	of no-load losses of three phase induction motor				
1	Total Perio	ods:4	45		
Course Outco	mes: Upon successful completion of the course, students wi	ll be	abl	e to	
	te and practice the experimental procedures and measurement				n
	ion of regulation of alternators				
	, analyze, interpret and describe the characteristics of synchr	rono	us m	iotoi	•
	, analyze, interpret and describe the characteristics of induct				
	and analyze the characteristics of induction motors used in				
applications.	······································				
References:					
	rald, Charles Kingsley, Stephen. D. Umans, 'Electric Mach	iner	v'. N	Ac C	braw
e	g Company Ltd, 2003.	•	, ,		
1 4	Toro, 'Basic Electric Machines' Pearson India Education, 2	016	•		
	Chapman, 'Electric Machinery Fundamentals'4th edition			raw	Hill
Education Pvt.					
4. D.P. Kothar	i and I.J. Nagrath, 'Electric Machines', McGraw Hill Publish	hing			
Company Ltd,	2002.	Ũ			
	nra, 'Electrical Machinery', Khanna Publishers, 2003.				
	opadhyay, Electrical Machines Theory and Practice, PHI Le	earni	ng F	VT	
LTD., New De			-		
7. B.R.Gupta,	'Fundamental of Electric Machines' New age International I	Publ	ishe	rs,3r	d
Edition, Reprin	nt 2015.				
8. Murugesh K	Cumar, 'Electric Machines', Vikas Publishing House Pvt. Ltd	1, 20	02.		
9. Alexander S	. Langsdorf, 'Theory of Alternating-Current Machinery', M	cGra	aw F	Hill	
Dublications ?	001				

Publications, 2001.

COs	POs											PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	3	3	1	3				1	3	1		1	2	3
2	3	3	1	3				1	3	1		1	2	3
3	3	3	1	3				1	3	1		1	2	3
4	3	3	1	3	1			1	3	1		1	2	3

Course	Course Title	L	Τ	P	С
Code					
UEE2512	CONTROL AND INSTRUMENTATION	0	0	4	2
	LABORATORY				
Objectives:					

- To implement a controller to a system and to study the response of the system
- To get hands on various sensors and instruments to measure basic electrical parameters.

List of Experiments:

CONTROLSYSTEMS:

- 1. P, PI and PID controllers (CO1)
- 2. Stability Analysis (CO1)
- 3. Modeling of Systems Machines, Sensors and Transducers (CO2)
- 4. Design of Lag, Lead and Lag-Lead Compensators (CO2)
- 5. Position Control Systems (CO2)
- 6. Synchro-Transmitter- Receiver and Characteristics (CO2)
- 7. Simulation of Control Systems by Mathematical development tools. (CO1)

INSTRUMENTATION:

- 8. Bridge Networks –AC and DC Bridges (CO4)
- 9. Dynamics of Sensors/Transducers (CO5)
 - a. Temperature transducer
 - b. Pressure transducer
 - c. Displacement transducer
 - d. Strain gauge
 - e. Flow meter
- 10. Power and Energy Measurement (CO2)
- 11. Signal Conditioning (CO3)
 - a. Instrumentation Amplifier
 - b. Analog Digital and Digital –Analog converters (ADC and DACs)
- 12. Process Simulation (CO2)

Total Periods:60

Course Outcomes: Upon successful completion of the course, students will be able to CO1: Implement the control system concept to electrical engineering problems

CO2: Illustrate the characteristics of different converters, compensators and other instruments

CO3: Design a signal conditioning circuit and implement a bridge network and transducer concept for a particular engineering problem.

References:

- 1. S.Salivahanan, R.Rengaraj, and G.R.Venkatakrishnan, "Control systems Engineering", Pearson India Education, 2015.
- 2. Nagarath, I.J. and Gopal, M., "Control Systems Engineering", New Age International Publishers, 2017.
- 3. Benjamin C. Kuo, "Automatic Control Systems", Wiley, 2014.
- 4. A.K. Sawhney, 'A Course in Electrical & Electronic Measurements & Instrumentation', DhanpatRai and Co, 2010.
- 5. J. B. Gupta, 'A Course in Electronic and Electrical Measurements', S. K. Kataria&Sons, Delhi, 2013.
- 6. Doebelin E.O. and Manik D.N., Measurement Systems Applications and Design, Special Indian Edition, McGraw Hill Education Pvt. Ltd., 2007.
- 7. S. Salivahanan, R. Rengaraj, G. R. Venkatakrishnan, "Measurements and Instrumentation" McGraw Hill, 2018.

COs	Pos												PSOs	5
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	1	2		2	2	2	3					2	3	3
2	1	2		3	2								3	3
3	1	2	2	3	2		3					2	3	3

SEMESTER VI

Course	Course Title	L	Τ	Р	EL	С
Code						
UEE2601	MICROPROCESSORS AND	3	0	1	3	4.5
	MICROCONTROLLERS - FUNDAMENTALS					
	AND PRACTICES					
Objectives:					•	
• To in	npart knowledge on Architecture of 8085 & 8086 and prog	ramı	ning	g in 8	086	
• To st	udy the interfacing of coprocessors with 8086					
• To in	npart knowledge on Architecture of $\mu C 8051$ and program	ning	in µ	C 80	51	
• To in	npart knowledge on ARM CORTEX M3 PROCESSOR					
• To st	udy simple programming in STM32XX MICROCONTRO	LLE	R			
Unit I	MICROPROCESSOR ARCHITECTURE &				9+3	
	INSTRUCTION SET					
	8085 and 8086, 8086: Addressing Modes - Instruction S Programming.	Set –	Tin	ning	diagra	.m –
Practice – I	Programming with 8086 – Arithmetic and logic operation	s – N	Matri	ix op	eratio	ns –

Floating point operation – Code conversions – Searching and Sorting- Data Transfer - Counter and Time Delay.

Studio – Programming 8086 using interrupts for counting and timing applications.

Interfacing 8086 with: Peripheral programmable interface 8255 & Programmable interrupt timer 8253, Programmable interrupt controller 8259, Keyboard and Display Interface 8279, monitor, Direct Memory access controller 8257.Interfacing ADC and DAC.

Practice – 8253 Timer Modes - Matrix Keyboard & 7 Segment display Interfacing - Interrupt Handling with 8259, Temperature measurement, Generation of Different types of Signals with frequencies.

Studio – Speed control of DC motor using 8086 Microprocessor.

Unit III	MICROCONTROLLERS ARCHITECTURE& INSTRUCTION SET	9+3
Architectur	e 8051 – Pin details- Timing Diagram - Memory – Parallel Ports - C	ounters/Timers
– Interrupts	- Serial port. Addressing modes, Instruction set of 8051.	

Practice - Basic Assembly Language Programming and Embedded C Programming – Arithmetic operations – Code conversions – Sorting – Look up tables – subroutines – Timer and serial port programming.

Studio - Design of a Real-Time PWM signal Generation with counter using Embedded C in 8051

Unit IV	STM32XX - ARM CORTEX M3 PROCESSOR	9+3

Cortex M3 Processor and Features – Core Peripherals – Memory Model –Bit Banding – Vector Table –NVIC Controller -Instruction set- STM32XX: General Purpose I/O (GPIO), Timer – Capture Compare unit

9+3

Practices – Programming in Embed C: GPIO, Timer - Capture & Compare Units. **Studio**- Sine PWM Signal generation for 3 Phase Inverter.

Unit V STM32XX MICROCONTROLLER

STM32XX - Watchdog –Interrupts – On chip ADC / DAC – DMA – I2C- CAN-Ethernet. **Practices:** Interrupts – ADC – DMA

Studio- ADC Multi Channel Data acquisition using DMA.

Total Periods60Course Outcomes: Upon successful completion of the course, students will be able to

CO1: Understand the architecture and instruction set of 8085 and 8086

CO2: Interface 8086 with its coprocessors and peripheral devices.

CO3: Understand the architecture and instruction set of 8051.

CO4: Understand the architecture and instruction set of STM32.

CO5: Interface STM32 with peripheral devices.

Text Books:

1. Douglas V. Hall, 'Microprocessors and interfacing programming and hardware', Tata McGraw-Hill, 2004.

2. K Uma Rao & Andhe Pallavi, "The 8051 Microcontrollers Architecture, Programming and Applications", Pearson Publications, 2nd Edition, 2011.

- 3. PM0056 Programming manual, STM32F10xxx/20xxx/21xxx/L1xxxx Cortex®-M3 programming manual
- 4. RM0008 Reference manual, STM32F101xx, STM32F102xx, STM32F103xx, STM32F105xx and STM32F107xx advanced Arm®-based 32-bit MCUs

References:

- 1. Kenneth J. Ayala, "The 8086 Microprocessor Programming & interfacing The PC".Penram International Publishing (India)Pvt.Ltd ,1995
- 2. David Calcutt, FredCowan, Hassan Parchizadesh, "8051Microcontrollers An Application Based Introduction", Elsevier Publication, 2006.
- 3. Donald Norris, "Programming with STM 32 getting started with the Nucleo board and C/ C++ ", McGraw-Hill Education TAB 1st edition, 2018.
- 4. Muhammad Ali Mazidi, SepehrNaimi"The STM32F103 ARM Microcontroller & Embedded Systems Using Assembly & C" Naimi and Mazidi Books , 2019.

COs								Pos					PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	
1	3			3	3				2	2			3	3	
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3	3			3	3				2	2			3	3	
4	3			3	3				2	2		1	3	3	
5	3	3	3	3	3				2	2		1	3	3	

Course	Course Title	L	Т	Р	С
Code					
UEE2602	POWER SYSTEM ANALYSIS	3	0	0	3
Objectives:					
• To int	roduce application of numerical methods to various power system	yster	n pro	oblen	ns.
• To m	odel the various power system components and to explain p	er u	nit c	luant	ities
0	with the formations of various matrices used for solvin	ng p	owe	r sys	tem
proble	ems.				
 To dis 	scuss various mathematical tools available for solving power	flov	v pro	blem	l .
 To dis 	scuss symmetrical and unsymmetrical fault studies in power s	syste	em.		
To dis	scuss transient stability analysis of SMIB and application of nu	imer	ical	meth	ods.
Unit I	NUMERICAL METHODS FOR POWER SYSTEMS			ç)
Numerical sc	lution of Non-linear equations - Gauss-Seidel and Newton	Rap	hson	itera	tive
methods - N	lumerical Solution of Non-Linear Ordinary Differential E	quat	ions	- Eu	ler's
method - Eul	er's modified method - and Runge-Kutta method				
Unit II	MODELING OF POWER SYSTEM COMPONENTS			9)
Modeling of	power system components - single line diagram - impe	danc	e d	iagra	m –
reactance dia	gram – per unit quantities – change of base – bus impedance	e ar	d ad	lmitta	ance

matrix	ζ.													
Unit I		POW	ER F	LOW	ANAI	LYSIS)							9
								Gauss-	Seidel	Newt	ton-Ra	aphson	and	Fast
		nethod				-				, ,		1		
Unit I	V	FAU	LT ST	UDIE	S	<i>.</i>								9
Symm	etrica	l fault	analys	sis usir	ng anal	ysis th	rough	imped	lance	matrix	- Uns	ymmet	rical s	short
-		vsis – S	-		-	-	-	_				5		
Unit V	V	STAI	BILIT	Y STU	UDIES	5								9
Steady	y state	and tra	ansien	t stabi	lity of	Single	Mach	ine In	finite I	Bus – S	Swing	equation	on - E	Iqual
area ci	riterio	n – Sol	lution	using	Euler's	s modi	fied m	ethod	and R	unge-K	Lutta n	nethod		
										Т	'otal P	Periods	4	15
Cours	se Out	comes	s: Upo	n succ	essful	compl	etion of	of the o	course	, stude	nts wi	ll be at	ole to	
CO1:	Under	stand	the ba	sics of	fnume	erical 1	nethoo	ls to s	olve n	on-line	ar alg	gebraic	equa	tions
and no	on-line	ear ord	inary o	differe	ntial e	quatio	n.							
CO2: 1	Demo	nstrate	mode	ling of	vario	us pow	ver sys	tem co	mpon	ents, re	prese	nt them	in si	mple
diagra	ms an	d cons	truct c	comput	ationa	l matr	ices.							
CO3:	Apply	nume	rical s	olutior	n meth	ods to	comp	lex and	l non-l	linear p	ower	flow p	roble	ms.
CO4:	Analy	ze syn	nmetri	cal and	l unsy	mmetr	ical sh	ort cir	cuit fa	ults in	a pow	ver syst	em	
CO5:	Apply	v equal	area	criterio	on and	conce	ept of	numer	ical sc	olution	metho	ods to a	non-li	inear
ordina	ry dif	ferenti	al equ	ation f	or tran	sient s	stabilit	y prob	lem.					
Text I	Books	:												
1. Ha	adi Saa	adat, 'I	Power	Syster	n Ana	lysis',	Tata N	AcGra	w-Hill	Educa	tion, 2	2nd Ed	ition,	
20	02.													
2. Jo	hn .J.	Graing	ger & S	Steven	son. W	/.D., 'F	ower	Systen	n Anal	ysis', N	AcGra	w Hill	, 1st	
Ed	lition,	2003.												
			r, "Pov	ver Sy	stem S	stabilit	y and	Contro	ol", Mo	cGraw	Hill E	Education	on; 1s	st
ed	ition,	2006.												
Refer	ences													
1.									rbye, "	Power	Syste	em Ana	lysis	and
	Desi	gn", C	engag	e Lear	ning, 5	5th Edi	tion, 2	2012						
				-				-				ition, 2		
3.	СL	Wadh	wa, "I	Electri	cal Po	wer S	ystems	s", Nev	w Age	Intern	ationa	als; Fir	st Ed	ition
	2016													
4.	Gupt	ta B.R.	., 'Pow	ver sys	tem A	nalysi	s & D	esign',	S. Ch	nand ai	nd Co	mpany	Ltd.,	Re-
		e Editio	,											
5.							Systen	ns - Ai	nalysis	s, Stabi	ility &	z Prote	ction'	', 3 ^{rc}
	Editi	on Kh	anna F	Publish	ers, 19	998.								
90								DC					mar	
COs	-				-		-	POs	0	4.0		4.5	PSC	1
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	3	3		2	3			2				1		

2	3	3	1	2	3		2				
3	3	3	2	2	3		2		2	1	1
4	3	3	2	2	3		2		2	1	
5	3	3		2	3		2		2	1	

	Course Title	L	Т	P	С
Code					
UEE2603	POWER SYSTEM OPERATION AND CONTROL	3	0	0	3
Objectives:	· · ·				
• To ur	derstand system load variations along with the need for volt	age a	and f	reque	ency
regul	ation and estimate the load using forecasting techniques.				
• To ur	nderstand the functions of energy control centre and provide	con	trol s	et-po	oints
for se	cure power system operation using contingency analysis.				
Unit I	INTRODUCTION			6	5
Load charac	teristics, load curve - load factor - diversity factor, Im	nport	ance	of 1	load
forecasting -	quadratic and exponential curve fitting techniques of foreca	sting	g, nec	essit	y of
voltage and	frequency regulation, P-f and Q-V control loops, plant level	l and	l syst	em l	evel
controls.					
Unit II	REAL POWER-FREQUENCY CONTROL			1	2
Basics of spe	ed governing mechanism, speed-load characteristics, load sh	aring	g betv	veen	two
synchronous	machines in parallel, control area concept, LFC control of a s	single	e-area	a syst	tem
static and dy	namic analysis of uncontrolled and controlled cases, LFC c	ontro	ol of	two-a	area
system and	modelling, static analysis of uncontrolled case, tie line wi	ith fi	reque	ency	bias
			-	•	orac
control, state	variable model.		-	Ţ	orac
	variable model. REACTIVE POWER-VOLTAGE CONTROL		-	9	
Unit III		Regu		9)
Unit III Generation	REACTIVE POWER-VOLTAGE CONTROL	U	lator	9 (AV) /R)
Unit III Generation brushless AG	REACTIVE POWER-VOLTAGE CONTROL and absorption of reactive power, Automatic Voltage I	R loo	lator p - s	(AV tatic) /R): and
Unit III Generation brushless AG dynamic ana	REACTIVE POWER-VOLTAGE CONTROL and absorption of reactive power, Automatic Voltage H C excitation system - block diagram representation of AVR	R loo n line	lator p - s e, me	(AV tatic) /R): and
Unit III Generation brushless AC dynamic ana reactive pow	REACTIVE POWER-VOLTAGE CONTROL and absorption of reactive power, Automatic Voltage I C excitation system - block diagram representation of AVR lysis - stability compensation, voltage drop in transmission	R loo n line ransf	lator p - s e, me	(AV (AV tatic ethod er.) /R): and
Unit III Generation brushless AC dynamic ana reactive pow Unit IV	REACTIVE POWER-VOLTAGE CONTROL and absorption of reactive power, Automatic Voltage I C excitation system - block diagram representation of AVR lysis - stability compensation, voltage drop in transmission er injection - shunt and series compensation - tap changing th	R loo n line ransf	lator p - s e, me	(AV tatic ethod er. 1) /R): and s of 2
Unit III Generation brushless AG dynamic ana reactive pow Unit IV Statement of	REACTIVE POWER-VOLTAGE CONTROL and absorption of reactive power, Automatic Voltage I C excitation system - block diagram representation of AVR lysis - stability compensation, voltage drop in transmission er injection - shunt and series compensation - tap changing the UNIT COMMITMENT AND ECONOMIC DISPATCH	R loo n line ransf	lator p - s e, me forme	(AV tatic ethod er. 1 , ther) and s of 2 mal
Unit III Generation brushless AC dynamic ana reactive pow Unit IV Statement of unit constrai	REACTIVE POWER-VOLTAGE CONTROL and absorption of reactive power, Automatic Voltage I C excitation system - block diagram representation of AVR lysis - stability compensation, voltage drop in transmission er injection - shunt and series compensation - tap changing the UNIT COMMITMENT AND ECONOMIC DISPATCH Unit Commitment (UC) problem, constraints in UC: spinning	R loo n line ransf ng res iints,	lator p - s e, me forme serve UC	(AV tatic ethod er. 1 , ther solu	/R): and s of 2 mal tion
Unit III Generation brushless AC dynamic ana reactive pow Unit IV Statement of unit constrai methods: Pr	REACTIVE POWER-VOLTAGE CONTROL and absorption of reactive power, Automatic Voltage I C excitation system - block diagram representation of AVR lysis - stability compensation, voltage drop in transmission er injection - shunt and series compensation - tap changing the UNIT COMMITMENT AND ECONOMIC DISPATCH Unit Commitment (UC) problem, constraints in UC: spinnin nts, hydro constraints, fuel constraints and other constra	R loo n line ransf ng res iints, ach,	lator p - s e, me forme serve UC State	(AV tatic ethod er. 1 , ther solu emen	/R) and s of 2 main tior t of
Unit IIIGenerationbrushless ACdynamic anareactive powUnit IVStatement ofunit constraitmethods: PrEconomic D	REACTIVE POWER-VOLTAGE CONTROL and absorption of reactive power, Automatic Voltage I C excitation system - block diagram representation of AVR lysis - stability compensation, voltage drop in transmission er injection - shunt and series compensation - tap changing to UNIT COMMITMENT AND ECONOMIC DISPATCH Unit Commitment (UC) problem, constraints in UC: spinnin nts, hydro constraints, fuel constraints and other constra iority-list method - forward dynamic programming approx	R loo n line ransf ng res iints, ach, of th	lator p - s e, me forme serve UC State	(AV tatic ethod er. 1 , ther solu emen l pla	(R): and s of 2 rmal tior t of nt -
Unit IIIGenerationbrushless ACdynamic anareactive powUnit IVStatement ofunit constraitmethods: PrEconomic DincrementalED solution	REACTIVE POWER-VOLTAGE CONTROL and absorption of reactive power, Automatic Voltage I C excitation system - block diagram representation of AVR lysis - stability compensation, voltage drop in transmission er injection - shunt and series compensation - tap changing the UNIT COMMITMENT AND ECONOMIC DISPATCH Unit Commitment (UC) problem, constraints in UC: spinning nts, hydro constraints, fuel constraints and other constra- iority-list method - forward dynamic programming appro- bispatch (ED) problem - input and output characteristics of cost curve - co-ordination equations without loss and with tr by direct method and λ -iteration method, base point and pa	R loo n line ransf ng res ints, ach, of th	lator p - s e, me forme serve UC State erma	(AV tatic ethod er. 1 , ther solu emen 1 pla on los	7R): and s of 2 mal tion t of sses.
Unit IIIGenerationbrushless ACdynamic anareactive powUnit IVStatement ofunit constraitmethods: PrEconomic DincrementalED solution	REACTIVE POWER-VOLTAGE CONTROL and absorption of reactive power, Automatic Voltage I C excitation system - block diagram representation of AVR lysis - stability compensation, voltage drop in transmission er injection - shunt and series compensation - tap changing the UNIT COMMITMENT AND ECONOMIC DISPATCH Unit Commitment (UC) problem, constraints in UC: spinning nts, hydro constraints, fuel constraints and other constra- iority-list method - forward dynamic programming approx- ispatch (ED) problem - input and output characteristics of cost curve - co-ordination equations without loss and with tr by direct method and λ -iteration method, base point and pa- gration of economic dispatch control with LFC.	R loo n line ransf ng res ints, ach, of th	lator p - s e, me forme serve UC State erma	(AV tatic ethod er. 1 , ther solu emen 1 pla on los	7R): and s of 2 mal tion t of nt - sses,
Unit IIIGenerationbrushless ACdynamic anareactive powUnit IVStatement ofunit constraitmethods: PrEconomic DincrementalED solution	REACTIVE POWER-VOLTAGE CONTROL and absorption of reactive power, Automatic Voltage I C excitation system - block diagram representation of AVR lysis - stability compensation, voltage drop in transmission er injection - shunt and series compensation - tap changing the UNIT COMMITMENT AND ECONOMIC DISPATCH Unit Commitment (UC) problem, constraints in UC: spinning nts, hydro constraints, fuel constraints and other constra- iority-list method - forward dynamic programming appro- bispatch (ED) problem - input and output characteristics of cost curve - co-ordination equations without loss and with tr by direct method and λ -iteration method, base point and pa	R loo n line ransf ng res ints, ach, of th	lator p - s e, me forme serve UC State erma	(AV tatic ethod er. 1 , ther solu emen 1 pla on los	 /R): and s of 2 cmal tion t of nt - sses, ttors
Unit IIIGenerationbrushless ACdynamic anareactive powUnit IVStatement ofunit constraitmethods: PrEconomic DincrementalED solutionmethod, inteUnit V	REACTIVE POWER-VOLTAGE CONTROL and absorption of reactive power, Automatic Voltage I C excitation system - block diagram representation of AVR lysis - stability compensation, voltage drop in transmission er injection - shunt and series compensation - tap changing the UNIT COMMITMENT AND ECONOMIC DISPATCH Unit Commitment (UC) problem, constraints in UC: spinning nts, hydro constraints, fuel constraints and other constra- iority-list method - forward dynamic programming approx- ispatch (ED) problem - input and output characteristics of cost curve - co-ordination equations without loss and with tr by direct method and λ -iteration method, base point and pa- gration of economic dispatch control with LFC.	R loo n line ransf ints, ach, of th artici	lator p - s e, me forme serve UC State erma nissic patio	(AV tatic ethod er. 1 , ther solu emen l pla on los n fac	P P
Unit IIIGenerationbrushless AGdynamic anareactive powUnit IVStatement ofunit constraitmethods: PrEconomic DincrementalED solutionmethod, integUnit VPower scenacentre, PMU	REACTIVE POWER-VOLTAGE CONTROL and absorption of reactive power, Automatic Voltage H C excitation system - block diagram representation of AVR lysis - stability compensation, voltage drop in transmission er injection - shunt and series compensation - tap changing the UNIT COMMITMENT AND ECONOMIC DISPATCH Unit Commitment (UC) problem, constraints in UC: spinning nts, hydro constraints, fuel constraints and other constra- iority-list method - forward dynamic programming appro- tispatch (ED) problem - input and output characteristics of cost curve - co-ordination equations without loss and with tr by direct method and λ -iteration method, base point and pa- gration of economic dispatch control with LFC. COMPUTER CONTROL OF POWER SYSTEMS	R loo n line ransf ng res iints, ach, of th ransm artici	lator p - s e, me forme serve UC State erma nissic patio	(AV tatic ethod er. 1, ther solu emen il pla on los n fac (y cor	A constraint of the second

Total Periods	45

Course Outcomes: Upon successful completion of the course, students will be able to

CO1: Understand system load variations along with the need for voltage and frequency regulation and estimate the load using forecasting techniques.

CO2: Analyze the load frequency dynamics in power system and design power-frequency controller.

CO3: Articulate the various conventional methods of reactive power compensation and illustrate the model of automatic voltage regulator.

CO4: Compute the optimal dispatch of the generating units in a power system by solving Unit Commitment and economic dispatch problems.

CO5: Understand the functions of energy control centre and provide control set-points for secure power system operation using contingency analysis.

Text Books:

- 1.Olle. I. Elgerd, 'Electric Energy Systems theory-An introduction', Tata Mc Graw Hill Education Pvt.Ltd., NewDelhi, 34th reprint, 2010.
- 2. Allen. J. Wood and Bruce F. Wollenberg, 'Power Generation, Operation andControl', John Wiley&Sons,Inc., 2003.
- 3. B. M. Weedy, B. J. Cory, N. Jenkins, J. B. Ekanayake, G. Strbac, 'Electric Power Systems', John Wiley & Sons Ltd., New Delhi, 5th edition 2013

References:

- 1.Nagrath. I. J. and Kothari D. P., 'Modern Power System Analysis', TataMcGraw-Hill, 14th reprint, 2009.
- 2.KundurP., 'Power System Stability and Control', Tata McGraw Hill Education Pvt. Ltd., New Delhi, 10th reprint, 2010.

Cos								POs					PS	Os
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	3	3	3	1	1								3	2
2	3	3	3	3	3								3	2
3	3	3	3	3	2								3	2
4	3	3	3	3	2								3	2
5	3	3	3	3									3	2

Course	Course Title I	4	Τ	Р	С
Code			0	4	2
UEE2611	POWER ELECTRONICS AND DRIVES LAB)	0	4	2
Objectives:			<i>.</i> .		
-	vide hands on experience with power electronic converters and	te	sting	5.	
List of Experi					
	teristics of SCR and IGBT.				
	teristics of GTO & IGCT.				
U U	phase AC to DC semi-converter and fully controlled converter	•			
	ET based step down and step-up choppers.				
	based single phase PWM inverter.				
	based three phase PWM inverter.				
-	phase AC Voltage controller.				
	ed mode power converter.	1			
	o based Gate Pulse Generation for DC-DC converter & single-	ph	ase 1	nver	ter.
-	of gate drive circuit for power electronic converters.				
	er based DC drive				
	tion of PE circuits (1 Φ & 3 Φ semi converters, 1 Φ & 3 Φ full c	cor	ivert	ers,	DC
DC co	nverters, $1\Phi \& 3\Phi$ Inverters & AC voltage regulators)		1	()	
<u> </u>	Total Po				
	omes: Upon successful completion of the course, students will	be	able	to	
	erize the power devices through DC analysis.				
	and test AC-DC and AC-AC converters				
	and test chopper and inverter circuits				
	bulse generation circuits for power electronic converters				
	e the performance of power converters through simulation				
References:					
	hid, 'Power Electronics: Circuits, Devices and Applications', P	ea	rson		
	, Third Edition, New Delhi, 2004.				
	ra "Power Electronics" Khanna Publishers, third Edition, 2003.				
3. Ashfaq A reprint, 20	hmed 'Power Electronics for Technology', Pearson Education, 003.	In	dian		
-	thayathil,' Power Electronics, Principles and Applications', Mon Edition, 2013.	cG	raw	Hill	
5. Philip T.	Krein, "Elements of Power Electronics" Oxford University Pre-	ss,	200	4	
Edition.	a di Monana Electro di a Energia la cadi Angli a di a 22 Willon (0.1	0		
	nd, "Power Electronics Essentials and Applications", Wiley, 20				2.80
	an Tore. M. Undel and, William. P. Robbins, 'Power Electronic	28:	Cor	ivert	2 18,
**	ons and Design', John Wiley and sons, third edition, 2003.		201	4	
	eddy, 'Fundamentals of Power Electronics', Narosa Publicatio				2
-	gh and K.B. Khanchandani, "Power Electronics," Mc Graw Hil				
10. JP Agarw 2002.	al," Power Electronic Systems: Theory and Design" 1e, Pearso	n	Educ	at101	1,

COs								Pos					PSO	s
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	3				2			1	3	1				2
2	3	1	2	2	2			1	3	1		1		3
3	3	1	2	2	2			1	3	1		1	2	3
4	3	1	2	2	2			1	3	1			2	2
5	3		1	1	3			1	3	1		2	1	3

Course Code	Course Title	L	Τ	Р	С
UEE2612	POWER SYSTEM SIMULATION LAB	0	0	3	1.5

Objectives:

The objective of this course is to understand power system voltage and frequency regulation and the functions of energy control centre and provide control set-points for secure power system operation using advanced power system simulation software's.

List of Experiments:

1. Computation of Parameters and Modelling of Transmission Lines.

2. Formation of Bus Admittance and Impedance Matrices.

3. Load Flow Analysis: Gauss-Seidel (GS), Newton Raphson (NR) and Fast Decoupled Load Flow (FDLF) method.

4. Fault Analysis.

5. Transient Stability Analysis of Single-Machine Infinite Bus System.

6. Switching surge analysis using EMTP.

7. Load – Frequency Dynamics of Single-Area and Two-Area Power Systems.

8. Economic Dispatch: Direct method, Lambda iteration method, Base point and participation factor method.

9. Unit commitment : Priority list method and Forward Dynamic programming.

10. Contingency analysis using linear sensitivity factors: Generator shift factors and line outage distribution factors.

Total Periods:45

Course Outcomes: Upon successful completion of the course, students will be able to

CO1:Compute transmission line parameters and model the line for steady state analysis by formulating bus admittance matrix using inspection method and analyze the computational performance via Gauss-Seidel (GS), Newton Raphson (NR) and Fast Decoupled Load Flow (FDLF) methods of solving power flow problem.

CO2:Calculate the fault current for various types of faults in the power system and analyze the transient stability by applying different fault clearing time to the circuit breakers, also analyze the switching surge in long transmission line using EMTP, subsequently analyze the power system reliability by performing Contingency Analysis using linear sensitivity factors.

CO3:Analyze load frequency control dynamics and design appropriate controllers for single and multiple area power system and compute the optimal dispatch of the generating units in a power system by solving economic dispatch problems and determine the optimal generation schedule of the generating units in a power system by solving unit commitment problems.

References:

- 1. Olle. I. Elgerd, 'Electric Energy Systems theory-An introduction', Tata Mc Graw Hill Education Pvt.Ltd., NewDelhi, 34th reprint, 2010.
- 2. Allen. J. Wood and Bruce F. Wollenberg, 'Power Generation, Operation andControl', John Wiley&Sons,Inc., 2003.
- 3. B. M. Weedy, B. J. Cory, N. Jenkins, J. B. Ekanayake, G. Strbac, 'Electric Power Systems', John Wiley & Sons Ltd., New Delhi, 5th edition 2013
- 4. Hadi Saadat, 'Power System Analysis', Tata McGraw-Hill Education, 2nd Edition, 2002.
- John .J. Grainger & Stevenson. W.D., 'Power System Analysis', McGraw Hill, 1st Edition, 2003.
- 6. Prabha Kundur, "Power System Stability and Control", McGraw Hill Education; 1st edition, 2006.

COs		POs													
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	
1	3	3			3								3	2	
2	3	3			3								3	2	
3	3	3	3	3	3								3	2	

SEMESTER VII

Course	Course Title	L	Т	Р	C
Code					
UEE2701	SOLID STATE DRIVES	3	0	0	3
Objectives:					
• To u	nderstand steady state operation and transient dynamics of a n	otor	loa	d sys	tem.
• To s	tudy and analyze the operation of the converter/chopper for	ed d	c dr	ive,	both
qual	tatively and quantitatively.				
• To s	udy and understand the operation and performance of AC mo	tor d	lrive	s.	
Unit I	DRIVE CHARACTERISTICS			9	9
Advantages	of electrical drives-Dynamics of electrical drive- Load Torque	es-St	eady	y stat	e
stability- Co	nverter motor system- Multi quadrant operation-starting and b	oraki	ng n	netho	ods-
Selection of	electric drives.				
Unit II	CONVERTER / CHOPPER FED DC MOTOR DRIVE			9	9
Analysis of	the single and three phase converter fed separately excited	DC	mot	or di	ive-
Chopper con	trolled DC drive-Four quadrant operation of converter / chopp	er fe	ed dr	ives-	DC

drive f	for tra	ction a	pplica	tions										
Unit I	II	INDU	JCTIC	ON M	отор	R DRI	VES						9)
Stator	voltag	ge cont	trol-V/	f cont	rol- Ro	otor Re	esistan	ice Coi	ntrol-S	lip pov	ver re	covery	drives	-
Vector	r conti		_						for Ele	ectric ve	ehicle	•		
Unit I	V	SYN	CHRO	NOU	S MO	TOR	DRIV	ES					9	
-	-								•	ronous				-
angle	contro	l - Bas	ic con	cepts o	of Sinu	soidal	PMA	C moto	or driv	es- Bru	shless	dc mo	tor driv	/es·
Switch	hed rel	uctanc	e mot	or driv	ves.									
Unit V	V	CON	TROI	L OF I	ELEC	TRIC	AL D	RIVES	5				9)
Transf	fer fur	oction	for D	C mot	or - c	losed	loop c	control	with	current	and	speed	feedba	ck-
armatı	ure vo	ltage	contro	l and	field	weake	ening	contro	1 – D	esign o	of co	ntroller	s; cur	ren
contro	ller ar	d spee	ed cont	roller	•									
										Т	otal P	eriods	4	5
													1	
Cours	se Out	comes	: Upo	n succ	essful	comp	letion	of the	course	, stude	nts wi	ill be al	ole to	
CO1:	Descri	be the	steady	y state	opera	tion ar	nd tran	sient d	lynami	ics of a	moto	r load s	system	
CO2: 1	Exami	ne the	opera	tion of	f the co	onvert	er/cho	pper fe	ed DC	drive				
CO3:	Analy	se the	operat	ion an	d perf	orman	ce of i	nducti	on mo	tor driv	'e			
CO4: 2	Descri	be the	opera	tion of	f syncl	nronou	is moto	or driv	e					
CO5:	Outlin	e curr	ent an	d spee	ed cont	rollers	s for a	closed	loop	motor d	lrive			
CO6:	Select	a suita	able el	ectric	drive f	for spe	cific a	pplicat	tion in	the inc	lustry	r		
Text I	Books	:												
1.Bim	al K.E	ose. N	Iodern	Powe	er Elec	tronic	s and A	AC Dri	ives, P	earson	Educ	ation, 2	2002.	
2.R.Ra	amapr	abha, l	R.Seye	zhai, l	Solid S	State D	Drives	DC an	d AC,	SCITE	CH F	ublicat	ions,2	019
Refer	ences:													
1.R.K	rishna	n, Elec	etric M	lotor &	& Driv	es: Mo	odeling	g, Anal	ysis a	nd Con	trol, I	Pearson	, 2001	
2. Gop	oal K.I	Dubey	, Fund	ament	als of	Electri	cal Dr	rives, N	Varosa	Publis	hing l	House,	1992.	
3.Shaa	ahinFe	lizade	h, "Ele	ectric I	Machi	nes an	d Driv	es", C	RC Pr	ess (Ta	ylor a	nd Fra	ncis	
	oup), 2										-			
4. Joh	n Hino	lmarsh	and A	lasda	in Ren	frew,	"Elect	rical M	Iachin	es and	Drive	s Syste	m,"	
	evier 2					,						2	,	
5. The	eodore	Wildi	. "Ele	ctrical	Mach	ines. I	Drives	and p	ower	system	s.6th	editio	ı. Pear	SOI
		n ,2015				,		r		5	,			
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		P.K. 5	SEN" I	Electri	c arrive	79 FII	II, <u>2</u> 01	<i>L</i> .						
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		P.K. S	SEN" I	Electri			11, 201	2. POs					PSO	5

Course	Course Title	L	Т	Р	С
Code UEE2702	PROTECTION AND SWITCHGEAR	3	0	0	3
Objectives:		J	U	U	U
•	cate the causes of abnormal operating conditions, types of fu	ses.	and	princ	iple
	ation of circuit breakers.	,		P	
1	part knowledge on functioning of circuit breakers.				
1	oduce the characteristics and functions of relays and protect	ion	sche	mes	
	part knowledge on apparatus protection.	1011	Jene	ines.	
-	oduce power system earthing				
	USES AND PRINCIPLES OF CIRCUIT BREAKERS				9
	Characteristics, Types of Fuses, Selection of Fuses. Ci	rcui	t Rı	-	
	ween fuse and circuit breaker, Requirement of a circuit bre				
	olator and circuit breaker, Basic principle of operation of				
	F arc, Properties of arc, Initiation and maintenance of arc,				
	ian's theory and Energy balance theory, Restriking voltage, I			-	
-	of Restriking voltage, DC circuit breaking, AC circuit b		•		0
	acitance switching, Resistance switching, Selection of break		-	Cui	Tent
	YPES OF CIRCUITS BREAKERS)
	eakers – Air break and Air blast Circuit breakers, Oil Circuit	hree	aker		
	break, minimum OCB, SF6 breaker - Preparation of SF6 ga				U
	of SF6 breakers. Vacuum circuit breakers. (Principle of				
• -	details, Advantages and disadvantages of different types of		-		
	ROTECTIVE RELAYS		une e)
	Fundamental requirements of protective relaying, Zones	of	Pro		
	ack up Protection, Classification of Relays. Electromagnetic				
	lanced Beam, Induction disc, Thermal Relays. Relay tim				
	y schemes - over current, directional and non-directional, o				
-	erential relays (Brief Description only).		,	8-	
-	PPARATUS PROTECTION			(9
	tection: Stator, rotor and other miscellaneous protections	-Sta	tor i	nter	turn
	ult and Differential protection. Transformer Protection - H				
	Percentage Differential Protection, overheating Protection,				
	inst magnetizing inrush current, Earth fault protection, Overf				•
-	ction - Differential current protection. Feeder protection				
-	wire and carrier current protection.				,
-	OWER SYSTEM EARTHING			9)
	erable limits of body current – step and touch voltage (tol	erab	le a	nd ac	tual
-	Ise behaviour of earthing systems – Neutral earthing – Arc				
– grounding pi		11	-		

Course Outcomes: Upon successful completion of the course, students will be able to

- CO1: Discuss the theory behind the operation of circuit breakers and select fuses for a given situation.
- CO2: To analyse and compare different types of circuit breakers and select the type of circuit breaker for a given application.
- CO3: To analyze the functioning of various protective relays and to explain their characteristics.
- CO4: To apply proper protective schemes for power apparatus and to design the protective system for the given power system components.
- CO5: Analyse various methods of power system earthing

Text Books:

1. Rao S.S. "Switchgear and Protection",13th ed. Khanna Publishers: Delhi; 2007.

2. Badri Ram, Vishwakarma, 'Power System Protection and Switchgear', Tata McGraw Hill, 2001.

References:

- 1. Soni M.L., Gupta P.V., Bhatnagar V.S., Chakrabarti A., "A Text Book on Power System Engineering", Dhanpat Rai & Co., 1998.
- 2. J.Nagrath, D.P.Kothari, "Power system Engineering", TMH, 1994.
- 3. C .L. Wadhwa, "Generation, Distribution and Utilisation of Electrical Energy", Wiley Eastern Ltd., 1993
- 4. Wadhwa C.L., "Electrical Power Systems", Newage International (P) Ltd., 2000.
- 5. Ravindranath B., and Chander N., "Power System Protection & Switchgear", Wiley Eastern Ltd., 1977.
- 6. Rajput R.K, "A Text book of Power System Engineering" Laxmi Publications, First Edition Reprint 2007.
- 7. Paithankar Y.G. and Bhide S.R., "Fundamentals of Power System Protection", Prentice Hall of India Pvt. Ltd., New Delhi–110001, 2003.
- 8. Oza, Nair, Mehta and Makwana, "Power System Protection and Switchgear", Tata McGraw-Hill.

9. T.S. Madhava Rao "Digital/Numerical Relays", Tata McGraw Hill 1st edition – 2005

10. V.K.Metha, Rohit Mehta, "Principles of power system", S.Chand Publications, Reprint-2006 Edition.

COs								POs					PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	
1	3	1													
2	3	1	1	1		1	1	1				2	3	2	
3	3	2	2		2	2	2	2				2	3	2	
4	3	2	1	1		2	2	2				2	3	2	
5	3					1	1	1					3	2	

Course Code	Course Title	L	Т	Р	С
UEE2703	HIGH VOLTAGE ENGINEERING	3	0	0	3
Objectives:		U	v	U	
•	ntroduce the various types of over voltages in power syste	m ai	nd p	rotec	tion
meth			1		
• To de mate	eals with the analysis of breakdown mechanisms of different t rials.	ypes	of i	nsula	ting
• To st	udy the various methods for the generation and measurement	of h	nigh	AC,	DC,
1	lse voltages and currents.				
	udy the methods of high voltage testing techniques of electric	cal e	quip	ment	s as
	andard specifications.			_	
	esign and plan the layout of high voltage laboratory and to p lination.	erfo	rm i	nsula	tion
Unit I	OVER VOLTAGES IN ELECTRICAL POWER SYSTE	MS		9)
	ver voltages and its effects on power system – Lightning, swi		וס גו	-	
	vervoltages, Corona and its effects – Reflection and Refract		-	-	
	ection against overvoltages.	1011		14/01	iiiig
	DIELECTRIC BREAKDOWN			()
	akdown in uniform and non-uniform fields – Corona disch	narge	<u>-</u>	-	
	- Conduction and breakdown in pure and commercial liquids	-			
	Breakdown mechanisms in solid and composite dielectrics.	,			• • •
Unit III	GENERATION OF HIGH VOLTAGES AND HIGH CURRENTS			ç)
Generation	of High DC, AC, impulse voltages and currents - Triggerin	ng ai	nd c	ontro	l of
impulse gene		-0			
	MEASUREMENT OF HIGH VOLTAGES AND HIGH CURRENTS			ç)
High Resist	ance with series ammeter – Dividers, Resistance, Capacit	ance	e an	d Mi	xed
dividers – P	eak Voltmeter, Generating Voltmeters - Capacitance Volta	ge 7	Trans	sform	lers,
Electrostatic	Voltmeters - Sphere Gaps - High current shunts- Digital to	echn	ique	s in l	nigh
voltage meas	surement.				
Unit V	HIGH VOLTAGE TESTING & INSULATION			Ģ)
	COORDINATION				
High voltage	e testing of electrical power apparatus as per International and	l Ind	ian s	stand	ards
-	uency, impulse voltage and DC testing of Insulators, circuit b				-
	d transformers- design, planning and layout of high volu	age	labo	orato	су -
Insulation C			<u> </u>	-	_
	Total I	eric	ods	4	3
Course Out	comes: Upon successful completion of the course, students w	ill b	e abl	e to	
	· · · ·				

CO1: Ability to understand the various types of over voltages in power system and
protection methods.
CO2: Ability to understand the Nature of Breakdown mechanism in solid, liquid and
gaseous dielectrics.
CO3: Ability to analyse the various methods for Generation of different types of over
voltages
CO4: Ability to analyse the various methods for Measurement of different types of over
voltages
CO5: Ability to analyse the various testing methods of power apparatus and apply the insulation coordination to the power system.
Text Books:
1. S.Naidu and V. Kamaraju, 'High Voltage Engineering', Tata McGraw Hill, Fifth
Edition, 2013.
2. E. Kuffel and W.S. Zaengl, J.Kuffel, 'High voltage Engineering fundamentals',
Newnes Second Edition Elsevier, New Delhi, 2005.
3. Subir Ray,' An Introduction to High Voltage Engineering' PHI Learning Private
Limited, New Delhi, Second Edition, 2013.
References:
1. S.Naidu and V. Kamaraju, 'High Voltage Engineering', Tata McGraw Hill, Fifth
Edition, 2013.
2. E. Kuffel and W.S. Zaengl, J.Kuffel, 'High voltage Engineering fundamentals',
Newnes Second Edition Elsevier, New Delhi, 2005.
3. Subir Ray,' An Introduction to High Voltage Engineering' PHI Learning Private Limited,
NewDelhi, Second Edition, 2013.
4. L.L. Alston, 'High Voltage Technology', Oxford University Press, First Indian
Edition, 2011.
5. C.L. Wadhwa, 'High voltage Engineering', New Age International Publishers, Third
Edition, 2010.

COs								POs					PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	
1	3	3	3	2	3								2	1	
2	3	3	3	2	3								2	1	
3	3	3	3	2	3								2	1	
4	3	3	3	2									2	1	
5	3	3	3	2	3								2	1	

Course	Course Title	L	Т	Р	C
Code					
UEE2716	INDUSTRIAL TRAINING / INTERNSHIP	0	0	0	2
Students shall	undergo training in R&D institutions / Academics / Industries	s for	a mi	inim	um
period of 15	days. At the end of internship students must submit a rep	ort	for	inter	mal
evaluation					
Objectives:					
• To dev	elop skills to take up technical project.				
• To est	imate the ability of the student in transforming the theoret	ical	kno	wle	dge
studied	l so far into a working model of Electrical Engineering system	ı.			
	rn use of new tools, algorithms and techniques required to	o ca	rry o	out	any
project					
0	guidance on the various procedures for validation of the prod	uct	and	anal	yze
	t effectiveness.				
	abling the students to gain exposure and experience in implementation of the students of the s		-		
	y project and thus acquire the necessary confidence to carry of	out r	nain	pro	ject
in the f	inal year.				
COURSE OU	TCOMES				
On Completio	n of the project work students will be in a position to				
CO1: Formu	late a real-world problem, identify the requirement and develo	op th	e de	sign	l
solutions.					
CO2: Express	the technical ideas, strategies and methodologies.				
CO3: Test and	validate through conformance of the developed prototype an	d an	alysi	is th	e
cost effectiven	ess. Prepare report and present the oral demonstrations				
CO4: Utilize t	he new tools, algorithms, techniques that contribute to obtain	the	solut	ion	of

COs								POs					PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	
1	3	3	2										3	1	
2				3	3					2	3		3	2	
3						3	3						2	1	
4								3	3	1	3	3	2	2	

Course	Course Title	L	Т	Р	C
Code					
UEE2711	ADVANCED ELECTRICAL AND ELECTRONICS	0	0	4	2
	DESIGN LAB				
Objectives:			1		
To pro	vide hands on experience with high voltage testing equipmen	t, ch	arac	teris	tics
-	battery, Fuel cell and interface of power electronic converter				
List of Exper-					
1. Breakdow	n Mechanism in Solid, Liquid and Air in Uniform/Non-Unifo	rm F	Field	S	
	quency Withstand Test on Transformer				
3. Determina	tion of Flashover Voltage of a 11kV Insulator				
4. Simulation	a & Experiment on Characteristics of Solar PV Panel				
5. Simulation	a &Experiment on Characteristics of Shadowing effect in Sola	ar PV	V Ar	ray.	
6. Experimen	tal study on Solar PV System with MPPT.				
7. Simulation	a & Experimental study on Wind Energy Generator.				
8. Experimen	tal study on Hybrid (Solar-Wind) Power System.				
9. Experimen	t on Performance Assessment of Fuel Cell.				
10. Experimen	tal study on Charging and Discharging Characteristics of batt	tery.			
11. Simulation	n study on Hydel Power.				
	Total P	erio	ds: 6	60	
	omes: Upon successful completion of the course, students wil				
	strate knowledge on the use of high voltage test equi	pme	nt a	und	the
characte	ristics of breaking voltages in various insulators.				
CO2: Illustrat	e the characteristics of photovoltaic modules and model	suit	able	pov	wer
	c converters.				
-	ent the wind, Wind-PV hybrid and hydel power systems and	shov	w the	eir	
characte					
CO4: Examine	e the characteristics of battery and performance parameters of	fuel	l cel	l	
References:					
1. M.S. Nai	du and V. Kamaraju, 'High Voltage Engineering', Tata Mo	cGra	w F	Iill,	3rd
Edition, 2	004.				
	and W.S. Zaengl, 'High Voltage Engineering Fundamentals', I	Perg	amo	n pro	ess,
· · · · · · · · · · · · · · · · · · ·	ondon, 1986. ari K.C. Singal, Pakash Panjan "Panawahla Energy Source	ann	ፈ ፔ•	nora	inc
	ari, K.C Singal, Rakesh Ranjan "Renewable Energy Source	s all	u El	nerg	,mg
	gies", PHI Learning Pvt.Ltd, New Delhi, 2013. ingh Solanki, "Solar Photovoltaics : Fundamentals, Te	ohn		iag	and
	ons", PHI Learning Private Limited, New Delhi, 2011	cnn(JIOG	ies a	anc
5. A.K.Muk	eriee and Nivedita Thakur." Photovoltaic Systems: Analysis a	and I	Desi	on"	

5. A.K.Mukerjee and Nivedita Thakur," Photovoltaic Systems: Analysis and Design", PHI Learning Private Limited, New Delhi, 2011

COs												PSOs					
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3		
1	2	2	1	3				1	3	1							
2	2	2	1	3			1	1	3	1							
3	2	2	2	3	2			1	3	1		1					
4	2	2	1	3			1	1	3	1							

Course	Course Title	L	Т	P	C				
Code									
UEE2718	PROJECT PHASE I	006							
Objectives:									
• To dev	elop skills to formulate a technical project.								
• To est	imate the ability of the student in transforming the theoret	tical	kno	wle	dge				
studied	studied so far into a working model of Electrical Engineering system.								
• To teach use of new tools, algorithms and techniques required to carry out the									
project	S.								

- To give guidance on the various procedures for validation of the product and analyze the cost effectiveness.
- For enabling the students to gain experience in organization and implementation of a small project and thus acquire the necessary confidence to carry out main project in the final year.
- To provide guidelines to prepare technical report of the project.

COURSE OUTCOMES

On Completion of the project work students will be in a position to

CO1: Analyze literature & formulate methodology to solve complex problems by applying fundamentals of sciences and electrical engineering

CO2: Apply modern techniques and tools to arrive at feasible solutions

CO3: Function ethically and effectively as an individual, and as a member or leader in multidisciplinary teams and prepare for independent and lifelong learning.

CO4: Discuss and illustrate the effectiveness of solutions through organized technical reports and oral presentations

COs		POs											PSOs	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	3	3	2										3	1
2				3	3					2	3		3	2
3						3	3						2	1
4								3	3	1	3	3	2	2

SEMESTER VIII

Course	Course Title	L	Т	Р	C
Code					
UEE2818	PROJECT PHASE II	0	0	16	8
Objectives:					
• To mal	ke use of the knowledge gained by the student at various stag	ges c	of the	e deg	ree
course.					
• To dev	relop the ability to solve a specific problem right from its id	lenti	ficat	ion a	and
literatu	re review till the successful solution of the same				
• To trai	n the students in preparing project reports and to face review	vs ar	nd vi	va v	oce
examir					
Each student is	s required to submit a report on the project assigned to him by	the	dep	artme	ent
	uld be based on the information available in the literature or		-		
the laboratory/					
•	ts, in addition to the home problem will be permitted to unde	ertak	e in	dustr	ial
	roject work, outside the department, in industries/Research				
• •	reightage will be given in the final assessment.				
	view committee may be constituted by the Head of the Depart	tme	nt. A	pro	iec
	red at the end of the semester. The project work is evaluate				,
	nd the project report jointly by external and internal examiner				
the Head of th					
COURSE OU	*				
	n of the project work students will be in a position to				
-	literature & formulate methodology to solve complex proble	ems	by a	nnlv	ing
•	of sciences and electrical engineering		0 9 0	PP-J	
	the feasibility of solutions through the conduct of experimen	ts w	ith e	effect	ive
	ning and reports with valid conclusions and recommendations				
	p electrical engineering solutions based on societal, health	h, s	afety	, leg	gal
	vironmental considerations for sustainable development				
	n ethically and effectively as an individual, and as a member of	or le	ader	in	
	ary teams and prepare for independent and lifelong learning.	1 4 -	1 !	- 1	
	and illustrate the effectiveness of solutions through organized al presentations	1 tec	nnic	al	

COs		POs											PSOs	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	3	3	2										3	1
2				3	3					2	3		3	2
3						3	3						2	1
4								3	3	1	3	3	2	2

Course	Course Title	L	Т	Р	С
Code					
UEN2241	LANGUAGE AND COMMUNICATION	2	0	2	3
Objectives:					
• To enl	nance communicative competence in general.				
• To im	prove the ability of the students to negotiate with meaning in	cor	ntext	•	
• To dev	velop speaking skills of the students for career needs.				
• To dev	velop sensitivity to gender, human rights, politeness and other	er as	pects	S	
	nance the skills in being persuasive in writing and speech				
	APPROACHES TO COMMUNICATION:			9)
The informat	ion Processing school, Shannon and Weaver; A Mathem	atic	al T	'heor	v of
	on, Formal Signal Processing approach.				,
	oach; information, communication and significance.				
	istinction between language structure and language use; form	n an	d fui	nctio	1.
•	cory of performance; acceptability and grammaticality.				
	ve Competency; Possibility, appropriacy, feasibility.				
	MEANING IN LANGUAGE USE				9
maxim, relation Ancient India Speaker internation Discourse me Unit III S Coherence Cohesion Initiating and Intervention	v of conversational meaning; the cooperative principle, quantional maxim, manner maxim. n theory of meaning; lexical, compositional, extended. tion in communication. aning; context and situation. STRUCTURE OF DISCOURSE/CONVERSATION: closing conversations)
Turn-taking					<u> </u>
	POWER STRUCTURE AND LANGUAGE USE:				9
Gender and la					
-	pressions and their use				
	sions of language use				
	nts as part of human rights				
	MEDIA AND PERSUASIVE COMMUNICATION:				9
	ia, Orwell's problem(Chomsky)				
	g of opinion and hidden agendas.				
	of persuasive communication.				
Persuasive qu					
Politics and co	ommunication barrier.				
	Total F	Dorid) de	45	

HSMC – ELECTIVES –HUMANITIES I (II SEMESTER)

Course Outcomes: Upon successful completion of the course, students will be able to

CO1: To improve their communicative competency across all skills of language.

CO2: To improve their writing ability in writing for persuasion and convincing someone.

CO3: To attend job interviews more confidently,

CO4: To improve social communication sensitive to gender and other prejudices.

CO5:To do better in the spoken component of the placement tasks

Text Books:

1. Stephen. C. Levenson, 1983, Pragmatics, Cambridge University press.

References:

1. Austin, 1962, J.L. How to do things with words. Oxford: Clarendon Press. Grice, P.1989.

- 2. Studies in the way of words. Cambridge, M.A: Harvard University Press.
- 3. Chomsky, N.1966. Aspects of the theory of syntax, The MITpress, Cambridge.

4. Chomsky, N.2006. Language and Mind, Cambridge University Press.

- 5. Hymes. D.N. 1972, On communication competence in J.B. Pride and J.Holmes (ed), Sociolinguistics, pp 269-293, London Penguin.
- 6. Gilbert, H.Harman, 1976. Psychological aspect of the theory of syntax in Journal of Philosophy,page75-87.

7. Stangley, J.2007. Language in Context. Clarendon press, Oxford.

8. Shannon, 1942. A Mathematical Theory of Communication.

9. Searle, J.R. 1969. Speech acts: An essay in the philosophy of language. Cambridge: Cambridge University Press.

Course		Program Outcomes													
Outco mes	PO 1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12			
CO1									2	3		2			
CO2									2	3		2			
CO3									2	3		2			
CO4									2	3		2			
CO5									2	3		2			

Course	Course Title	L	Т	Р	C
Code			0	•	
UEN2242	FUNDAMENTALS OF LINGUISTICS	2	U	2	3

Objectives:

• To introduce the students to Linguistics (the scientific study of language).

• To explore some basic issues and questions related to language such as what do we know when we know a language, the relation between language and brain, language and

society	, how does a child learn a language, how the languages of the world ar	e similar
as well	as different, how can we analyze language as a structure etc.	
To prov	vide students to a brief outline of language studies in Indian and western	tradition
and ma	ny applications of linguistics in different fields	
Unit I	DEFINING LANGUAGE	9
• What is	s language and where is language?	
	guage is a means of communication, a social product	
	guage is a cognitive ability, relation between language and brain	
-	f Language in Indian and western traditions	
Unit II	AN INSIGHT INTO LINGUISTICS	9
	s Linguistics and what is not Linguistics?	
	nguistics is not prescriptive grammar learnt in the school	
	nguistics is not learning of many languages	
	nguistics provides tools to analyze language structure scientifically	0
Unit III	FORM AND FUNCTION	9
	of Language Analysis: Form and content	
o Sour		
• Wor • Sent		
o Mea		
	ies and differences of languages	
Unit IV	APPLICATIONS	9
	ations of Linguistics	,
	tural Language Processing	
	nical Linguistics	
	ycholinguistics etc.	
Unit V	IMPACT ON CAREER	9
• Impac	et of linguistics on one's career	
o A	n understanding of Linguistics for better use of language	
o L	anguage and personality development	
0 L	inguistic features specific to Engineers.	
	Total Periods	45
	tcomes: Upon successful completion of the course, students will be abl	e to
CO1: under	stand what is linguistics	
CO2: explo	re some basic issues and questions related to language	
CO3: under	stand the subtle difference between the use of English in Indian and we	stern
tradition.		
CO4: Famil	iarize themselves with the unique features of language in technology	
CO5: Unde	rstand the basics of how children acquire languages	
Text Books		
1. Raj Kum	ar Sharma, 'Fundamentals of Linguistics', Atlantic Publishers, Chennai:	2019.
References		
	s Herbst, 'English Linguistics: A coursebook for students of English', D	e
	r Mouton Publication, Germany: 2010.	
•	a A. Fromkin (ed.), Linguistics: An introduction to linguistic theory, Bl	ackwell

Publishers, USA: 2001.

 Jeff Connor - Linto and Ralph W Fasold, 'An Introduction to Language and Linguistics', Cambridge University Press, 2014.

Course		Program Outcomes													
Outco mes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO 10	PO 11	PO 12			
C01									2	3		2			
CO2									2	3		2			
CO3									2	3		2			
CO4									2	3		2			
CO5									2	3		2			

Course	Course Title	L	Т	Р	С
Code					
UHS2243	FILM APPRECIATION	2	0	2	3
Objectives:					
• To in form.	troduce students to the development of film as an art and en	terta	inme	ent	
	scuss the language of cinema as it evolved over a century.				
	able the students to read a film and appreciate the various n as a text.	uanc	es o	f a	
• To gu	ide the students to study films joyfully.				
Unit 1	THE COMPONENT OF FILMS			9	
• The m	aterial and equipment				
• The st	ory, screenplay and script				
• The ac	tors, crew members, and the director				
• The pr	ocess of film making				
Unit II	EVOLUTION OF FILM LANGUAGE			9	
• Film la	anguage, form, movement etc.				
• Early	cinema silent film (Particularly French)				
• The er	nergence of feature films: Birth of a Nation Talkies				
• Films	and their influence on the language of people				
Unit III	FILM APPRECIATION			9	
• Realis	t theory; Auteurists				
• Psyche	banalytic, Ideological, Feminists				
	o read films?				
• Film C	Criticism / Appreciation				

Unit IV	DEVELOPMENT OF FILMS	9
• Repres	entative Soviet films	
• Repres	entative Japanese films	
• Repres	entative Italian films	
• Repres	entative Hollywood film and the studio system	
Unit V	INDIAN FILMS	9
• The ear	rly era	
• The im	portant films made by the directors E-3: The regional films	
• The do	cumentaries in India	
• The Inc	dian Film Industry and the Hollywood	
• The im	pact of Films on students in India.	T
	Total Periods	45
CO2: the evo CO3: the scr CO4: the evo	cess of the development of film as an art and entertainment form. olution of the language of cinema as it evolved over a century. ipt writing techniques of a film and appreciate the various nuances olution of film industry from the past to present appreciate all aspects of the film.	
Text Books:		
Take, Ally	, 'The Film Appreciation Book': The Film Course You Always War worth Press, New York: 2014.	nted to
References:		
Edition', H 2. Joseph M. I 2006. 3. Bernard F.	vell, 'The World Viewed: Reflections on the Ontology of Film, Enla arvard University Press, 1979. Boggs, Dennis W. Petrie, 'The Art of Watching Films', McGraw – H Dick, 'Anatomy of Film', St. Martins Press, 1990. ding the Film: An Introduction to Film Appreciation by Jan Bone an	Hill,

COs	Program Outcomes												
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	
CO1									2	3		2	
CO2									2	3		2	
CO3									2	3		2	
CO4									2	3		2	
CO5									2	3		2	

Course Code	Course Title	L	Т	Р	С
UHS2241	HUMAN RELATIONS AT WORK	2	0	2	3
	The objectives of this course are to make students:	-	U	-	0
Ū	of human relations at work its relationship with self.				
	about the processes involved in interaction with people at wo	rk			
	stand the importance of psychological and physical health in m		ainir	ıø hu	man
	ons at work and progressing in career.			8	
	stand the ways and means to improve human relations at work	~			
	the importance of safeguarding themselves from any exploit		n.		
Unit I	HUMAN RELATIONS			Ģ)
• Und	erstanding and Managing Yourself				
	an Relations and You				
• Self	Esteem and Self Confidence				
• Self	Motivation and Goal Setting				
• Emo	tional Intelligence				
• Atti	udes and Happiness				
• Valu	es and Ethics and Problem Solving and Creativity.				
Unit II	INTERPERSONAL RELATIONSHIP			9	
• Dea	ing Effectively with People				
	munication in the Workplace				
	cialized Tactics for Getting Along with Others in the Workplac	ce			
	aging Conflict; Becoming an Effective Leader				
	ivating Others and Developing Teamwork				
	ersity and Cross-Cultural Competence				
Unit III	HEALTHY LIVING			()
• Stav	ing Physically Healthy				
-	a, Pranayam				
e	cise: Aerobic and anaerobic				
Unit IV	MENTAL WELL BEING			Ç)
• Stay	ing Psychologically Healthy				
•	aging Stress and Personal Problems				
	itation				
Unit V	CAREER READINESS			Ç)
	eloping Career Thrust				
	ing Ahead in Your Career				
	ning Strategies				
	eption Span Changes				
	eloping Good Work Habits				
- DUV	Total I	Perio	ods	4	5
Course Ou	t comes: Upon successful completion of the course, students w				
	nhance their awareness about human relations at work and its				vith
				1	

self	•
------	---

CO2: become aware of the processes involved in interaction with people at work

CO3: understand the importance of psychological and physical health in maintaining human relations at work.

CO4: will be able to understand the ways and means to improve human relations at work.

CO5: will realize the importance of safeguarding themselves from any exploitation.

Text Books:

1. Dubrien, A. J. (2017). Human Relations for Career and Personal Success: Concepts, Applications, and Skills, 11thEd. UpperSaddleRiver, NJ: Pearson.

References:

- 1. Greenberg, J. S. (2017). Comprehensive stress management (14th edition). New York: McGraw Hill.
- 2. Udai, Y. (2015). Yogasanaurpranayam. New Delhi: N.S. Publications.

COs	Program Outcomes													
COS	PO1 PO2 PO			PO4	4 PO5 PO6		PO7	PO8	PO9	PO10	PO11	PO12		
CO1						2		2	3	2		2		
CO2						2		2	3	2		2		
CO3						2		2	3	2		2		
CO4						2		2	3	2		2		
CO5						2		2	3	2		2		

Course Code	Course Title	L	Т	Р	C
UHS2242	APPLICATIONS OF PSYCHOLOGY IN EVERYDAY LIFE	2	0	2	3

Objectives:

The objectives of this course are to make students:

- aware of the different applications of psychology to everyday issues of life,
- aware of the different social issues, workplace issues, and behavioural issues, and
- understand how the knowledge gained from this course can be used in their own personal and professional work life.
- Understand the psychological principles relevant to human development.
- Understand the impact of Psychology on human life

Unit I	nit I PSYCHOLOGY OF AN INDIVIDUAL					
• Intro	duction: Nature and fields.					
• The	individual human being and his or her experiences, mental processes a	nd				
beha	viors.					
Unit II	Unit II DIFFERENT TYPES OF PSYCHOLOGY					

psycho	nt types of psychology: cognitive, forensic, social, and deve logy	lopmental
Unit III	PSYCHOLOGY AND MENTAL HEALTH	9
Psychology	and mental health: Abnormality, symptoms and causes psychological	disorders.
Psychology	for better decision making, stress management and behavior.	
Unit IV	COUNSELING	9
Psychology	and Counseling: Need of Counseling, Counselor and the Counselee, C	Counseling
	eas of Counseling.	
Unit V	SOCIAL BEHAVIOR	9
Psychology	and social behavior: Group, group dynamics, teambuilding, Preju	udice and
stereotypes	; Effective Communication, conflict and negotiation	
	Total Periods	45
~ ~		
	tcomes: Upon successful completion of the course, students will be ab	
	their awareness on applications of psychology to everyday issues of lif	
	nore efficiently with different issues in society, workplace and human	
	y principles of psychology in their own personal and professional lives	5.
	he psychological principles for their own human development.	
	eciate the impact of Psychology on human life	
Text Book	3:	
1 Schultz	D. & Schultz, S.E. (2009). Psychology and Work Today (10th ed.). No	ew
1. Schultz,	earson/Prentice Hall.	
	:	
Jersey:P References	: , J. N., Mineka, S., & Hooley, J. M. (2010). Abnormal psychology (14	4th ed.).
Jersey:P References		Ith ed.).
Jersey:P References 1. Butches New Y	r, J. N., Mineka, S., & Hooley, J. M. (2010). Abnormal psychology (14 ork: Pearson	,
Jersey:P References 1. Butches New Y	r, J. N., Mineka, S., & Hooley, J. M. (2010). Abnormal psychology (14 ork: Pearson g, S. T. (2014). Counselling: A comprehensive profession. New Delhi:	

 Aronson, E., Wilson, T. D., &Akert, R. M. (2010). Social Psychology (7th Ed.). Upper Saddle River, NJ: Prentice Hall.

Con	Program Outcomes													
Cos	PO 1 PO2		PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12		
CO1						2		2	3	2		2		
CO2						2		2	3	2		2		
CO3						2		2	3	2		2		
CO4						2		2	3	2		2		
CO5						2		2	3	2		2		

Course	Course Title	L	Т	Р	С
Code					
UEN2243	UNDERSTANDING SOCIETY AND CULTURE	2	0	2	3
	THROUGH LITERATURE				
Objectives:		4			
_	skills not only the ones necessary for one's "trade", but also				
-	by b	ras t	ne ei	na or	
Ū.	better society.	no dit	iona	and	
	e understanding a society, its people, their mind, prevalent to			anu	
sustainable	h a view to developing a holistic worldview, which is essent	121 10	or a		
	society. ce students to literary works of various countries/ regions / s	ocia	tion	and	
	understand the respective traditions to which the works below		ues a	anu	
-	and the relationship between life and literature	ng.			
	TERATURE AND LIFE				
				Ç	9
	ional Knowledge.				
	Literature?				
-	ance of studying literature,				
=	g society and culture through literature,				
	anding morality through literature.		_		
-	g of Literary texts – The literary piece will be given to stude				
	y read it and become familiar with the texts before coming t			ss. In	the 1
	e text will be read once again, where doubts if any will be cl				
	scussion – The reading will be followed by a discussion whe				
•	d in detail. The students will be encouraged to share their in	terpr	etati	on of	t the
text.					
Unit II	RESOLVING DILEMMA			Ģ)
	and Description of 'Dilemma'	•			
	literary texts to confront situations where one is faced				
	ting what is right and wrong? and develop a deeper insigh	t int	o th	e var	ious
realities of			1.1	.1	
	n of analysis of the literary text (The students will keep in				
-	d and the socio-historical and cultural backgrounds whi	le p	repa	rıng	this
presentatio					
-	ion on the Presentation (the students will be encouraged to		-		
-	ective classmates regarding the presentation/analysis ini	tiati	ng a	a sec	cond
	on the text.				
	ENDER STUDIES)
	eces that question the current notions of gender, and rais	es u	ncoi	nfort	able
questions,		_	1		
	that challenges the status quo, forcing us to think about the	e rea	u me	eanin	g of
equality an	d emancipation				

• Second Discussion– (Having made their presentation, and heard the presentations made by their classmates, the students would now have a fairly good idea of the various nuances of the text, making it a ripe moment to have the second detailed discussion on the text. Here the teacher may refer to those points which may have been missed by the student Unit IV READING LITERATURE 9 • Reading of select Literary works • The author's Background, Historical and Social Background for a better understanding of the literary work • Study of other significant study material as required for an overall understanding of the literary work. 9 Unit V **READINGS** Submission of a report-Having faced questions from their classmates, and after having a second discussion on the text, the student would come across new ideas which will be incorporated into the analysis and submitted in the form of a report. 45 **Total Periods** Course Outcomes: Upon successful completion of the course, students will be able to CO1: Improve their awareness of various traditions. CO2: Not only understand the diversity found between various traditions but also celebrate them. CO3: Strengthen their analytical capability. CO4: Improve their language skills and ability of expressing complex ideas. CO5: understand the relationship between life and literature **Text Books:** 1. Literary works will be provided by the teacher. Author's Background, 2. Historical and Social Background which are significant for a better understanding of the work will be provided by the teacher. **Reference:** Reference materials or other significant study materials as required for an overall understanding of the literary work will be sourced out by the students in consultation with the teacher Course

Outco		Program Outcomes														
mes	РО 1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12				
CO1									2	3		2				
CO2									2	3		2				
CO3									2	3		2				
CO4									2	3		2				
CO5									2	3		2				

MANAGEMENT ELECTIVES (V SEMESTER)

Course	Course Title	L	Т	Р	С
Code			_	_	-
UBA2541	PRINCIPLES OF MANAGEMENT	3	0	0	3
Objectives:					
-	wledge about the following topics:				
• Ske	tch the Evolution of Management.				
• Ext	ract the functions and principles of management.				
• Lea	rn the application of the principles in an organization.				
• Stu	dy the various HR related activities.				
• Ana	alyze the position of self and company goals towards busine	SS			
	NTRODUCTION TO MANAGEMENT AND DRGANIZATIONS			9)
					6
	Management – Science or Art – Manager Vs Entrepre nagerial roles and skills – Evolution of Management –Sc				
	em and contingency approaches– Types of Business org				
	, partnership, company-public and private sector enterprise				
	vironment – Current trends and issues in Management.		- 8		
	PLANNING			9)
Nature and pu	rpose of planning – Planning process – Types of planning	– C	bjec	tives	_
	ives - Policies - Planning premises - Strategic Managem				
	hniques – Decision making steps and process.				
	ORGANISING			9	
	purpose – Formal and informal organization – Organi				
•	structure - Types - Line and staff authority - Departm				
	authority – Centralization and decentralization – Job D				
	anagement – HR Planning, Recruitment, selection,		.1n1n	g ar	nd
	Performance Management, Career planning and manageme	nt.		(<u> </u>
			(1		
	of individual and group behaviour– Motivation – Motiv				
	techniques – Job satisfaction – Job enrichment – Leader eadership – Communication – Process of communicati				
	on – Effective communication – Communication and IT.	on	- D	arre	111
	CONTROLLING			Ģ)
	rocess of controlling – Budgetary and non - Budgetary cor	ntrol	tech	-	
• •	ters and IT in Management control – Productivity problems			-	
-	performance – Direct and preventive control – Reporting				
	Total I	Perio	ods	4	5
Course Outco	omes: Upon successful completion of the course, students w	ill b	e abl	e to	
CO1: Upon co	ompletion of the course, students will be able to have clear	und	ersta	ndin	g of
manageria	al functions like planning, organizing, staffing, leading & co		lling		
	me basic knowledge on international aspect of management				

CO3:	Ability to understand management concept of organizing.							
CO4:	Ability to understand management concept of directing.							
CO5:	Ability to understand management concept of controlling.							
Text Books:								
1.	Harold Koontz and Heinz Weihrich "Essentials of Management", Tata McGraw Hill,							
	1998.							
2.	Stephen P. Robbins and Mary Coulter, "Management", Prentice Hall (India)Pvt. Ltd.,							
	10th Edition, 2009.							
Refer	ences:							
1.	Robert Kreitner and Mamata Mohapatra, "Management", Biztantra, 2008.							
2.	Stephen A. Robbins and David A. Decenzo and Mary Coulter, "Fundamentals of							
	Management", Pearson Education, 7th Edition, 2011.							
3.	Tripathy PC and Reddy PN, "Principles of Management", Tata McGraw Hill, 1999.							

Course		Program Outcomes														
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12				
CO1											2	1				
CO2									2		3	1				
CO3									2		2	1				
CO4					3					2	2	1				
CO5											1	1				

Course Code	Course Title	L	Т	Р	C
UBA2542	TOTAL QUALITY MANAGEMENT	3	0	0	3
Objectives:					

Objectives:

To impart knowledge about the following topics:

- Teach the need for quality, its evolution, basic concepts, contribution of quality gurus, TQM framework, Barriers and Benefits of TQM.
- Explain the TQM Principles for application.
- Define the basics of Six Sigma and apply Traditional tools, New tools, Benchmarking and FMEA.
- Describe Taguchi's Quality Loss Function, Performance Measures and apply Techniques like QFD, TPM, COQ and BPR.

9

• Illustrate and apply QMS and EMS in any organization.

Unit I INTRODUCTION

Introduction - Need for quality - Evolution of quality - Definition of quality - Dimensions of product and service quality –Definition of TQM-- Basic concepts of TQM –-Gurus of TQM (Brief introduction)-- TQM Framework- Barriers to TQM –Benefits of TQM.

Unit II	TQM PRINCIPLES	9
Leadership	- Deming Philosophy, Quality Council, Quality statements and St	trategic
planning C	ustomer Satisfaction –Customer Perception of Quality, Feedback, Cu	istomer
	Service Quality, Kano Model and Customer retention - Em	
	t - Motivation, Empowerment, Team and Teamwork, Recognition & I	
	nance AppraisalContinuous process improvement –Juran Trilogy,	
	nd Kaizen - Supplier partnership – Partnering, Supplier selection, S	
-	Relationship development.	11
Unit III	TQM TOOLS & TECHNIQUES I	9
The seven	traditional tools of quality - New management tools - Six-sigma I	Process
	Bench marking - Reasons to benchmark, Benchmarking process, W	
	k, Understanding Current Performance, Planning, Studying Others, La	
	ta, Using the findings, Pitfalls and Criticisms of Benchmarking - FMEA	
	ation, Stages: Design FMEA and Process FMEA.	
Unit IV	TQM TOOLS & TECHNIQUES II	9
Quality circ	les – Quality Function Deployment (QFD) - Taguchi quality loss function	on – TPM
	improvement needs – Performance measures- Cost of Quality - BPR.	
Unit V	QUALITY MANAGEMENT SYSTEM	9
	n-Benefits of ISO Registration-ISO 9000 Series of Standards-Sector	-
	AS 9100, TS16949 and TL 9000 ISO 9001 Requirements-Implem	
	tion-InternalAudits-Registration-ENVIRONMENTAL MANAC	
	Introduction—ISO 14000 Series Standards—Concepts of ISO	
	ntroduction—150° 14000° Series Standards—Concepts of 150° iso	14001—
Requirement	Total Periods	45
	1 otal 1 erious	43
Course Ou	tcomes: Upon successful completion of the course, students will be ab	le to
	lity to apply TQM concepts in a selected enterprise.	
CO2: Abi	lity to apply TQM principles in a selected enterprise.	
CO3: Abi	lity to understand Six Sigma and apply Traditional tools, New tools,	
Ben	chmarking and FMEA.	
CO4: Abi	lity to understand Taguchi's Quality Loss Function, Performance Measure	ures and
	y QFD, TPM, COQ and BPR.	
	lity to apply QMS and EMS in any organization.	
Text Books	S:	
	esterfiled, Carol B.Michna,Glen H. Bester field,Mary B.Sacre,	Hemant
	ne and Rashmi Urdhwareshe, "Total Quality Management", Pearson E	
	ed Third Edition, Indian Reprint, Sixth Impression,2013.	Jaucution
References		
	E. Ross, "Total Quality Management – Text and Cases", Routledge., 201	7
	.D.R, "Total Quality Management: Key concepts and case studies, Bu	
	iemann Ltd, 2016.	uci wortii
	and, J.S. "TQM – Text with Cases", Butterworth – Heinemann Ltd.	Ovford
	Edition,2003.	, Oxioiu,
		11 (India)
-	nthi,L and Anand Samuel, "Total Quality Management", Prentice Ha .td., 2006	in (muia)
1)x 74	td 2006	

Course	Program Outcomes													
Outcomes	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO 10	PO 11	PO 12		
C01						3		2	1		1	1		
CO2						3			2		1	1		
CO3					2	3			1		1	1		
CO4						3	1		1		1	1		
CO5						3	2		1		1	1		

Course Code	Course Title	L	Τ	Р	С
UBA2543	WORK ETHICS, CORPORATE SOCIAL RESPONSIBILITY AND GOVERNANCE	3	0	0	3

Objectives:

To impart knowledge about the following topics:

- To impart the value of professional practices with code of conduct and ethical values
- Discuss the various outlooks of roles and responsibilities with work ethics.
- Introduce the Indian constitutional statutes for ethical practices by citizens •
- Analyze the ethical commitments to be hold by industry with protecting environment
- Insist on corporate and social responsibilities through Governance practices and regulation

Unit I **INTRODUCTION**

Ethics - Definition & nature, Characteristics, Attributes of Ethics - Business Ethics; Ethical theories; Causes of unethical behavior; Ethical abuses; Work ethics; Code of conduct; Public good. 9

9

9

Unit II **ETHICS THEORY AND BEYOND**

Management of Ethics - Ethics analysis [Hosmer model]; Ethical dilemma; Ethics in practice – ethics for managers; Role and function of ethical managers- Comparative ethical behaviour of managers; Code of ethics; Competitiveness, organizational size, profitability and ethics; Cost of ethics in Corporate ethics evaluation.

Unit III LEGAL ASPECTS OF ETHICS Political – legal environment; Provisions of the Indian constitution pertaining to Business; Political setup - major characteristics and their implications for business; Prominent

features of MRTP & FERA. Social – cultural environment and their impact on business operations, Salient features of Indian culture and values. **ENVIRONMENTAL ETHICS** 9 **Unit IV**

Economic Environment; Philosophy of economic grow and its implications for business, Main features of Economic Planning with respect to business; Industrial policy and framework of government contract over Business; Role of chamber of commerce and confederation of Indian Industries.

Unit V	CORPORATE SOCIAL RESPONSIBILITY AND	9
	GOVERNANCE	

Definition- Evolution- Need for CSR; Theoretical perspectives; Corporate citizenship; Business practices; Strategies for CSR; Challenges and implementation; Evolution of corporate governance; Governance practices and regulation; Structure and development of boards; Role of capital market and government; Governance ratings; Future of governance-innovative practices; Case studies with lessons learnt.

Total Periods 45

Course Outcomes: Upon successful completion of the course, students will be able to

CO1: Understand ethical issues in workplace and have good practices in professional duties. CO2: Learn roles and responsibilities in professional career as a team worker

CO3: Understand the legal aspects in Indian constitutional for protection of societal values

CO4:Analyze the economical development by industry with importance to environment protection.

CO5: Understand need of good Governance in a corporate with ethical organizational behavior. **Text Books:**

- 1. S.A. Sherlekar, Ethics in Management, Himalaya Publishing House, 2009.
- 2. William B. Werther and David B. Chandler, Strategic corporate social responsibility, SagePublications Inc., 2011
- 3. VVRobert A.G. Monks and Nell Minow, Corporate governance, John Wiley and Sons, 2011.

References:

- 1. VW.H. Shaw, Business Ethics, Cengage Learning, 2007.
- 2. Beeslory, Michel and Evens, Corporate Social Responsibility, Taylor and Francis, 1978.
- 3. Philip Kotler and Nancy Lee, Corporate social responsibility: doing the most good for company and your cause, Wiley, 2005.
- 4. Subhabrata Bobby Banerjee, Corporate social responsibility: the good, the bad and the ugly, Edward Elgar Publishing, 2007.
- 5. Satheesh kumar, corporate governance, Oxford University, Press, 2010.
- 6. Bob Tricker, Corporate governance- Principles, policies and practices, Oxford University Press, 2009
- 7. Larue Tone Hosmer and Richard D., The Ethics of Management, Irwin Inc., 1995.
- 8. Joseph A. Petrick and John F. Quinn, Management Ethics integrity at work, Sage, 1997.

Course		Program Outcomes													
Outcomes	PO1	PO 2	PO 3	PO 4	PO 5	PO 6	PO 7	PO 8	PO 9	PO 10	PO 11	PO 12			
CO1								3	1	1		2			
CO2								3	1	1		2			
CO3						3	2	3	1	1		2			
CO4							2	3	1	1	3	2			
CO5								3	1	1	2	2			

Course	Course Title	L	3 0 adalone r of sol n. conditionationationation tems – ssues for for PV itry - E ple of a olar Ca eriods Il be ab stem and enges d Alista	Р	С
Code					
UEE2521		3	0	0	3
Objectives:					
• To s	study about solar cells and photovoltaic system design for s	anda	lone	and	grid
conr	nected applications				
• To u	inderstand different applications of photovoltaic system.				
Unit I	INTRODUCTION			•	9
Characterist	tics of sunlight - semiconductors and P-N junctions -behavior	our o	f sol	ar ce	lls –
cell properti	ies and design - PV Cell interconnection and module fabricat	ion.			
Unit II	STAND ALONE PHOTOVOLTAIC SYSTEM			9)
Standalone	PV system design - Solar modules - storage systems - powe	r con	ditic	ning	and
regulation -	Balance of system components - Designing standalone PV s	ysten	1s - s	sizing	g.
Unit III	GRID CONNECTED PHOTOVOLTAIC SYSTEMS			9)
PV systems	in buildings - utility applications for photovoltaics - design	n issu	es fo	or cen	ntral
power static	ons - safety - Economic aspect -standards and guideline	s for	PV	syste	ems,
Efficiency a	nd performance - International PV programs.				
Unit IV	PHOTOVOLTAIC WATER PUMPING SYSTEM				9
	COMPONENTS				
C (
System con	figuration - Water Pumps - Motors - Power conditioning cir	cuitry	y - B	atter	ies -
-	iguration - Water Pumps - Motors - Power conditioning cir ag and mounting - PV water pumping system design -Exa	-			
-	ng and mounting - PV water pumping system design -Exa	-			
Array wirin	ng and mounting - PV water pumping system design -Exa	-		ı dire	
Array wirin coupled sys Unit V	ng and mounting - PV water pumping system design -Exa tem design.	mple	of a	ı dire	ectly
Array wirin coupled sys Unit V Space - Mar	ng and mounting - PV water pumping system design -Exa tem design. SOLAR APPLICATIONS	mple	of a	ı dire	ectly
Array wirin coupled sys Unit V Space - Mar	ng and mounting - PV water pumping system design -Exa tem design. SOLAR APPLICATIONS rine - Telecommunications - Photovoltaic powered transport - Solar Refrigeration.	mple Sola	of a ar Ca	n dire 9 rs - S	ectly
Array wirin coupled sys Unit V Space - Mar	ng and mounting - PV water pumping system design -Exa tem design. SOLAR APPLICATIONS rine - Telecommunications - Photovoltaic powered transport - Solar Refrigeration.	mple Sola	of a ar Ca	n dire 9 rs - S	ectly 9 Iolar
Array wirin coupled sys Unit V Space - Mar Furnaces - S	ng and mounting - PV water pumping system design -Exa tem design. SOLAR APPLICATIONS rine - Telecommunications - Photovoltaic powered transport - Solar Refrigeration.	mple Sola Perio	of a r Ca ods	n dire rs - S 4	ectly 9 Iolar
Array wirin coupled sys Unit V Space - Mar Furnaces - S Course Out	ng and mounting - PV water pumping system design -Exa tem design. SOLAR APPLICATIONS rine - Telecommunications - Photovoltaic powered transport - Solar Refrigeration. Total	mple Sola Peri will b	of a r Ca ods e ab	t dire 9 rs - S 4 le to	ectly Jolar 5
Array wirin coupled sys Unit V Space - Mar Furnaces - S Course Out	and mounting - PV water pumping system design -Exa tem design. SOLAR APPLICATIONS rine - Telecommunications - Photovoltaic powered transport - Solar Refrigeration. Total teomes: Upon successful completion of the course, students v in the characteristics, techniques of solar energy conversion s	mple Sola Peri will b	of a r Ca ods e ab	t dire 9 rs - S 4 le to	ectly Jolar 5
Array wirin coupled syss Unit V Space - Mar Furnaces - S Course Out CO1: Expla module fabr	and mounting - PV water pumping system design -Exa tem design. SOLAR APPLICATIONS rine - Telecommunications - Photovoltaic powered transport - Solar Refrigeration. Total teomes: Upon successful completion of the course, students v in the characteristics, techniques of solar energy conversion s	mple Sola Peri will b	of a r Ca ods e ab	t dire 9 rs - S 4 le to	ectly Jolar 5
Array wirin coupled syst Unit V Space - Mar Furnaces - S Course Out CO1: Expla module fabr CO2: Desig	ag and mounting - PV water pumping system design -Exa tem design. SOLAR APPLICATIONS rine - Telecommunications - Photovoltaic powered transport - Solar Refrigeration. Total teomes: Upon successful completion of the course, students v in the characteristics, techniques of solar energy conversion s rication	mple Sola Perio will b	of a r Ca ods e abl n and	t dire 9 rs - S 4 le to	ectly Jolar 5
Array wirin coupled syss Unit V Space - Mar Furnaces - S Course Out CO1: Expla module fabr CO2: Desig CO3: Descr	ag and mounting - PV water pumping system design -Exa tem design. SOLAR APPLICATIONS tine - Telecommunications - Photovoltaic powered transport - Solar Refrigeration. Total tcomes: Upon successful completion of the course, students v in the characteristics, techniques of solar energy conversion s tication n a standalone photovoltaic system	mple Sola Perio will b	of a r Ca ods e abl n and	t dire 9 rs - S 4 le to	ectly Jolar 5
Array wirin coupled sys Unit V Space - Mar Furnaces - S Course Out CO1: Expla module fabr CO2: Desig CO3: Descr CO4: Desig	ag and mounting - PV water pumping system design -Exa tem design. SOLAR APPLICATIONS tine - Telecommunications - Photovoltaic powered transport - Solar Refrigeration. Total teomes: Upon successful completion of the course, students v in the characteristics, techniques of solar energy conversion s tication n a standalone photovoltaic system ibe a grid connected photovoltaic system and identify the characteristics and the characteristics of solar standalone photovoltaic system and identify the characteristics of solar system and identify the solar system and identify the solar system and identify the system and identify the solar system and solar system and solar system and identify the solar system and solar system	mple Sola Perio will b	of a r Ca ods e abl n and	t dire 9 rs - S 4 le to	ectly Jolar 5
Array wirin coupled sys Unit V Space - Mar Furnaces - S Course Out CO1: Expla module fabr CO2: Desig CO3: Descr CO4: Desig	ag and mounting - PV water pumping system design -Exa tem design. SOLAR APPLICATIONS tine - Telecommunications - Photovoltaic powered transport - Solar Refrigeration. Total tcomes: Upon successful completion of the course, students v in the characteristics, techniques of solar energy conversion s tication n a standalone photovoltaic system ibe a grid connected photovoltaic system and identify the char n a PV water pumping system ss the applications of solar energy	mple Sola Perio will b	of a r Ca ods e abl n and	t dire 9 rs - S 4 le to	ectly Jolar 5
Array wirin coupled syss Unit V Space - Mar Furnaces - S Course Out CO1: Expla module fabr CO2: Desig CO3: Descr CO4: Desig CO5: Discu Text Books	ag and mounting - PV water pumping system design -Exa tem design. SOLAR APPLICATIONS tine - Telecommunications - Photovoltaic powered transport - Solar Refrigeration. Total tcomes: Upon successful completion of the course, students v in the characteristics, techniques of solar energy conversion s tication n a standalone photovoltaic system ibe a grid connected photovoltaic system and identify the char n a PV water pumping system ss the applications of solar energy	mple Sola Perio will b syster	of a r Ca ods e abl n and es	a dire	olar 5
Array wirin coupled syst Unit V Space - Mar Furnaces - S Course Out CO1: Expla module fabr CO2: Desig CO3: Descr CO4: Desig CO5: Discu Text Books 1. Stuart R.V	ag and mounting - PV water pumping system design -Exa tem design. SOLAR APPLICATIONS rine - Telecommunications - Photovoltaic powered transport - Solar Refrigeration. Total teomes: Upon successful completion of the course, students v in the characteristics, techniques of solar energy conversion s rication n a standalone photovoltaic system ibe a grid connected photovoltaic system and identify the cha n a PV water pumping system ss the applications of solar energy :	mple Sola Perio will b syster	of a r Ca ods e abl n and es	a dire	olar 5
Array wirin coupled syss Unit V Space - Mar Furnaces - S Course Out CO1: Expla module fabr CO2: Desig CO3: Descr CO4: Desig CO5: Discu Text Books 1. Stuart R.V "Applied	ag and mounting - PV water pumping system design -Exa tem design. SOLAR APPLICATIONS tine - Telecommunications - Photovoltaic powered transport - Solar Refrigeration. Total tcomes: Upon successful completion of the course, students v in the characteristics, techniques of solar energy conversion s tication n a standalone photovoltaic system ibe a grid connected photovoltaic system and identify the cha n a PV water pumping system ss the applications of solar energy : Wenham, Martin A.Green, Muriel E. Watt, Richard Corkish a	mple Sola Will b Syster	of a r Ca ods e ab n and es	t dire	olar 5
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Array wirin coupled sys Unit V Space - Mar Furnaces - S Course Out CO1: Expla module fabr CO2: Desig CO3: Descr CO4: Desig CO3: Descr CO4: Desig CO5: Discu Text Books 1. Stuart R.V "Applied 2. Solanki C	ng and mounting - PV water pumping system design -Exa tem design. SOLAR APPLICATIONS rine - Telecommunications - Photovoltaic powered transport - Solar Refrigeration. Total teomes: Upon successful completion of the course, students v in the characteristics, techniques of solar energy conversion s rication n a standalone photovoltaic system ibe a grid connected photovoltaic system and identify the cha n a PV water pumping system ss the applications of solar energy : Wenham, Martin A.Green, Muriel E. Watt, Richard Corkish a Photovoltaics", Third Edition, 2011,Earthscan, UK. C.S., "Solar Photovoltaics: Fundamentals, Technologies And A pvt. Ltd., 2015.	mple Sola Will b Syster	of a r Ca ods e ab n and es	t dire	olar 5

PROFESSIONAL ELECTIVE I (SEMESTER – V)

Progensa,1994.

Solar & Wind Energy Technologies – McNeils, Frenkel, Desai, Wiley Eastern, 1990
 S.P. Sukhatme , "Solar Energy", Tata McGraw Hill,1987.

COs								POs					PSOs	5
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	3												1	2
2	3	3	2	3	2				2	1		1	1	2
3	3	3	2	3	2				2	1		1	2	3
4	3	3	2	3	2		2		2	1		1	2	2
5	3	3	2	3	2		2		2	1		1	1	3

Course	Course Title	L	Τ	Р	С
Code					
UEE2522	FUNDAMENTALS OF DIGITAL SIGNAL	3	0	0	3
	PROCESSING				
OBJECTIV	VES				
• To le	earn the fundamentals of Discrete Fourier transform and its pro-	oper	ties		
• To u	nderstand the design aspects of frequency selective digital filt	ers			
• To in	nterpret the implementation issues in designing digital filters				
• To u	nderstand the concepts of Liner predictive coding and adaptiv	e filt	ers		
Unit I	DISCRETE-TIME RANDOM SIGNALS			1	0
Discrete For	urier Transforms: Review of main concepts form Signals and	Sys	stem	s cou	rse-
Frequency a	lomain sampling and reconstruction of discrete time signals	- T	he I	OFT a	as a
Linear Tran	sformation - Relationship of the DFT to other Transforms - Pr	oper	ties	of Dl	FT -
	ring methods based on DFT - Efficient computation of the DFT		•		
	g data sequences - overlap save and overlap add method. Effic				
	Two real sequences - efficient computation of the DFT of	a 2N	I- Po	oint I	Real
	Use of FFT in Linear filtering and correlation.				
Unit II	DESIGN OF FIR FILTERS			8	-
Ideal filter	characteristics, causality and its implications, characteristics	stics	of	pract	ical
frequency so	elective filters. Design of FIR filters - Symmetric FIR filters,	des	ign (of lin	ear-
phase FIR	filters using windows: rectangular window, Hamming win	ndov	v. F	reque	ency
sampling me	ethod.FIR filters for harmonic elimination.				
Unit III	DESIGN OF IIR FILTERS			8	3
Design from	Analog filters. Design of digital IIR low-pass filter from analo	g fil	ters -	- Imp	1
	and Bilinear Transformation. Frequency transformations for a				ulse
	the Difficult Transformation. Trequency transformations for t			ia aiș	
filters.	and Difficul Transformation. Trequency transformations for e		0	10 018	
	DIGITAL FILTER REALIZATION		0		gital

form structures, cascade form structures, frequency sampling structures. Structures for IIR systems - Direct form structures, Cascade form structures, Parallel form structures and Analysis of Finite Word Length Effect and limit cycle oscillations in recursive systems.

Unit VAPPLICATIONS OF DSP IN ELECTRICAL ENGINEERING11Multi-rate processing, Sampling rate conversion, Decimation and interpolation, Introduction
to QMFs.Linear predictive coding, forward linear prediction, Levinson-Durbin algorithm,
signal synthesis, Application in power systems. Basics of adaptive filters, FIR Adaptive
filters, Adaptive filters based on steepest descent method, the LMS algorithm, Application
in control systems.

Total Periods	45
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Course Outcomes: Upon successful completion of the course, students will be able to

CO1: Apply discrete Fourier transform for the analysis of digital signals and systems CO2: Design and realize FIR filters

CO3: Design and realize a frequency selective digital IIR filters

CO4: Realize different structures of digital filters

CO5: Apply the concepts filtering in electrical engineering

Text Books:

- 1. Sanjit K. Mitra, "Digital Signal Processing, A Practical approach", Tata McGraw Hill Publishing Company Limited, 2005
- 2. John G.Proakis, Dimitris G. Manolakis, "Digital Signal Processing", Pearson, Fourth, 2007.

References:

- 1. Alan V. Oppenheim, Ronald W. Schaffer and John R. Buck, Discrete time signal processing, Prentice Hall, Third Edition, 2009.
- 2. Vinay K. Ingle and John G. Proakis, Digital Signal Processing using MATLAB, Cengage learning, Third Edition, 2011.
- 3. Ashok Ambardar, Digital Signal Processing: A modern introduction, Cengage Learning, First Edition, 2006.

COs		Pos														
	1	2	3	4	5	6	7	8	9	10	11	12	1	2		
1	3	3	3		1											
2	1	2	3	2									3			
3	1	2	3	2									3			
4	1	1	3	1												
5									2			2	3	3		

Course	Course Title	L	Т	Р	С
Code					
UEE2523	ENERGY RESOURCES AND UTILIZATION	3	0	0	3
Objectives:					
• To intr	oduce energy scenario and to discuss various commercial en	nerg	y ava	ailabl	e in
India					
• To intr	oduce renewable energy source like Solar and Wind				
• To dise	cuss utilization of electrical energy based on domestic consu	mer	s.		
• To disc	cuss utilization of electrical energy with respect to refrigerat	ion a	and a	air	
conditi	oning				
• To exp	lain industrial utilization and traction of electrical energy				
Unit I C	COMMERCIAL ENERGY			Ģ)
Coal, Oil, Nati	ural gas, Nuclear power and Hydro - their utilization pattern i	n the	e pas	t, pre	sent
and future pr	rojections of consumption pattern - Sector-wise energy	co	nsur	nptio	n –
environmental	impact of fossil fuels - Energy scenario in India - Growth	n of	ener	gy se	ctor
and its plannir	ng in India.				
Unit II R	ENEWABLE ENERGY			ç)
Solar radiation	at the earth's surface – solar radiation measurements – estin	nati	on o	f ave	rage
solar radiation	-principle of photovoltaic conversion of solar energy, type	es of	sola	ar cel	ls –
	wind – power in the wind – factors influencing wind – wind				
estimation - w	ind speed monitoring - wind resource assessment - Betz lim	it - s	ite so	electi	on -
wind energy c	onversion devices - classification, characteristics				
Unit III D	OMESTIC UTILIZATION AND ILLUMINATION			g)
Online and OI	FF line UPS, Batteries - Power quality aspects – nonlinear and	nd de	ome	stic lo	bads
– Earthing –	Importance of lighting -laws of illumination -types of	lam	ps –	ligh	ting
calculations -	basic design of illumination schemes for residential, co	omn	nerci	al, st	reet
lighting, factor	ry lighting and flood lighting – LED lighting and energy eff	icier	t lar	nps.	
	EFRIGERATION AND AIR CONDITIONING			ç)
Refrigeration-	Domestic refrigerator and water coolers - Air-Conditioning	-Vai	rious	type	s of
air-conditionin	ng system and their applications, smart air conditioning units	- En	ergy	Effic	ient
motors: Stand	lard motor efficiency, need for efficient motors, Motor	life	cycl	e, Di	rect
Savings and p	ayback analysis, efficiency evaluation factor.				
Unit V I	NDUSTRIAL UTILIZATION AND TRACTION			ç)
Role of electri	c heating for industrial applications – resistance heating – in	duct	ion	heati	ng –
	ting. Brief introduction to electric welding – welding ge				
	nd the characteristics. Merits of electric traction - require				
traction system	n – supply systems – mechanics of train movement – tra	ction	n mo	otors	and
	ing – recent trends in electric traction.				
	Total I	Perio	ods	4	5
Course Outco	omes: Upon successful completion of the course, students w	ill b	e abl	e to	
					4
CO1: Discuss	the basics of commercial energy and their utilization p	atter	n ar	nd fu	lure

CO2: Demonstrate the renewable energy resources like solar and wind and their electrical conversion.

CO3: Explain the domestic utilization of electricity in particular to UPS, and power quality issues along with illumination techniques and LED lightning.

CO4: Explain the refrigeration and air conditioning system, along with energy efficient motors and their saving in energy utilization.

CO5: Explain the industrial utilization of electricity in particular toheating, welding and electric traction.

Text Books:

- 1. Wadhwa, C.L. "Generation, Distribution and Utilization of Electrical Energy", New Age International Pvt. Ltd, 2003.
- 2.Dr. Uppal S.L. and Prof. S. Rao, 'Electrical Power Systems', Khanna Publishers, New Delhi, 15th Edition, 2014.
- 3. Bent Sorensen, "Renewable Energy", Elsevier, Academic Press, 2011.
- 4. Kishore V.V.N., "Renewable Energy Engineering and Technology", Teri Press, New Delhi,2012

References:

- 1. Partab.H, "Art and Science of Utilisation of Electrical Energy", Dhanpat Rai and Co, New Delhi, 2004.
- 2. Openshaw Taylor.E, "Utilization of Electrical Energy in SI Units", Orient Longman Pvt. Ltd, 2003.
- 3.Gupta.J.B, "Utilization of Electric Power and Electric Traction", S.K.Kataria and Sons, 2002.
- 4.Sukhatme S.P., "Solar Energy", Tata McGraw Hill, 1984.

5.Twidell J.W. and Weir A., "Renewable Energy Sources", EFN Spon Ltd., 1986.

6. Veziroglu T.N., Alternative Energy Sources", Vol 5 and 6, McGraw-Hill, 1990.

COs								POs					PS	SOs
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	3	3						2				1		
2	3	3	1					2					2	1
3	3	3	1	1				2				2	1	2
4	3	3	1	1				2				2		
5	3	3						2				2	1	1

Course	Course Title I		Т	Р	С
Code					
UEE2524	COMMUNICATION ENGINEERING 3	3	0	0	3
Objectives:					
• To stuc	ly the various analog and digital modulation techniques				
• To stuc	ly the various digital communication techniques				
• To stuc	ly the principles behind information theory and coding				
• To und	erstand the concept of spread spectrum system				
Unit I A	NALOG MODULATION			Ģ)
Amplitude Mo	odulation - AM, DSBSC, SSBSC, VSB - modulators and o	lei	mod	ulato	rs –
Angle modula	tion – PM and FM, modulators and demodulators – Sup	pe	r he	teroc	lyne
	parison of AM, FM and PM				
Unit II P	ULSE MODULATION			Ģ)
Low pass sam	pling theorem – Quantization – Pulse Amplitude Modulation	(]	PAN	1) – I	Line
coding - Puls	e Code Modulation (PCM), DPCM, Delta Modulation (DI	M)	, an	d AI	DМ,
Channel Voco	der - Time Division Multiplexing, Frequency Division Multip	lez	xing	•	
Unit III D	IGITAL MODULATION AND TRANSMISSION			Ģ)
Phase shift ke	ying – BPSK, DPSK, QPSK – Principles of M-arysignaling	N	1-ary	/ PSI	Κ&
	parison, ISI – Pulse shaping – Duo binary encoding – Cosir				
pattern, equaliz	zers.				-
Unit IV I	NFORMATION THEORY AND CODING			Ģ)
Measure of in	formation – Entropy – Source coding theorem – Shannor	۱—J	Fanc	cod	ing,
Huffman Codi	ng, LZ Coding – Channel capacity – Shannon-Hartley law –	Sh	anno	on's l	imit
– Error contr	ol codes - Cyclic codes, Syndrome calculation - Convo	lu	tion	Cod	ing,
Sequential and	Viterbi decoding.				
Unit V S	PREAD SPECTRUM AND MULTIPLE ACCESS			Ģ)
PN sequences	- properties - m-sequence - Direct Sequence Spread Spec	tru	ım (DSS	S) –
Processing gai	n, Jamming – Frequency Hoping Spread Spectrum (FHSS) – S	yr	nchro	oniza	tion
and tracking	- Multiple Access - FDMA, TDMA, CDMA, Application	on	of	wire	eless
communication	n – GSM				
	Total Per	rio	ds	4	5
Course Outco	mes: Upon successful completion of the course, students will	be	e abl	e to	
CO1:Explain t	he basic analog modulation techniques				
CO2:Explain t	he basic digital modulation and transmission techniques.				
CO3:Explain t	he various pulse modulation and line coding techniques.				
	d analyze, how encoding and decoding technique is processed	us	sing	simp	le
maths			U	1	
CO5: Explain	the various spread spectrum and multiple access techniques.				
Text Books:					
	Schilling, G Saha, "Principles of Communication Systems"	3/e	e, TN	ИН 2	007
	Digital Communications" John Wiley 2005.		,		

References:

- 1. B.P.Lathi, "Modern Digital and Analog Communication Systems", 3rd edition, Oxford University Press, 2007.
- 2. H P Hsu, Schaum Outline Series "Analog and Digital Communications" TMH 2006.
- 3.B.Sklar, Digital Communications Fundamentals and Applications" 2/e Pearson Education 2007.

COs	POs												PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	
1	1	1			2				1			1	2	1	
2	1	1			2				1			1		1	
3	1	1			2				1			1		1	
4	3	1			2				1			1		1	
5	1	1			2				1			1		1	

Course	Course Title	L	Т	Р	С
Code					
UEE2525	LOW VOLTAGE DIRECT CURRENT SYSTEMS	3	0	0	3
Objectives:					
•	To introduce the students to LVDC				
•	To explore some basic issues and questions related standards				
•	To provide students to a brief DC Power System Architecture	and	mici	ogrie	t
Unit I	INTRODUCTION TO LVDC			Ģ	9
Introduction	to LVDC (Low Voltage Direct Current) Microgrid for Comm	nerci	al B	uildiı	ngs
DC Microg	id Characteristics, Safety and protection, Reliability, Integratio	on. I	DC N	/licro	grid
Design Me	hodology, DC Converters, DC Microgrid Applications, I	DC N	Micr	ogrid	for
Commercia	Building, Monitoring System for Microgrid				
Unit II	COMMUNICATIONS STANDARDS			Ģ	9
	tions standards DC Loads, Present DC Loads DC Loads for t				<u> </u>
	DC Microgrid, PV Solar Cell, Fuel Cell, Types of PV Solar C	onve	ersio	n En	ergy
	DC Microgrid Battery, Super capacitor				
Unit III	DC POWER SYSTEM ARCHITECTURE			9	9
Power Syste	em Architecture, Utility Grid Energy Storage System, PV Sola	r Pa	nel i	ntegr	ated
system					
Unit IV	DC MICROGRID			9	9
Loads in D	C Microgrid, Power Array Conversion for DC Microgrid, A	Arra	y Co	onver	sion
Architecture	e, Array Conversion Mathematical Model				
Unit V	SWITCHING FUNCTION			Ç	9

Switching Function for Array Conversion, Simulation Setup Configuration of the Simulation System, DC Microgrid Components for Simulation

Total Periods 45

Course Outcomes: Upon successful completion of the course, students will be able to

CO1: Explain microgrid design methodology and applications

CO2: Analyse PV solar cell, fuel cell and energy storage types for DC micro grid.

CO3: Explain DC power system architecture

CO4: Realise Efficient Low Voltage DC Microgrid with Power Array Conversion

CO5: Illustrate the switching function for array conversion and DC Microgrid Components

Text Books:

1. LVDC: Electricity for the 21st century, IEC Technology Report

- 2. An Efficient Low Voltage DC Microgrid with Power Array Conversion for Commercial Buildings, Ph D Thesis, Zhiqing Wu, Florida Institute of Technology, 2019
- 3. Bimal k Bose, "Modern power electronics : evolution, technology, and applications", Newyork Publishers, IEEE press, 1991.
- 4. Ahmed F Zobaa, "Energy Storage: Technologies and Applications", 23 January 2013, Intechopen Publisher, ISBN-13 : 978-9535109518
- 5. Fang Lin Luo, Hong Ye, "Advanced Multi-Quadrant Operation DC/DC Converters", CRC Press, First edition, 2005, ISBN-13 : 978-0849372391.

References:

 Jens Bo Holm-Nielsen and Padmanaban Sanjeevikumar, "Power Electronic Converter Configuration and Control for DC Microgrid Systems", MDPI publishers, ISBN 978-3-03936-431-2 (Hbk); ISBN 978-3-03936-432-9, July 2020 edition. <u>https://doi.org/10.3390/books978-3-03936-432-9</u>

2. El-Shahat A, Sumaiya S. "DC-microgrid system design, control, and analysis", Electronics. MDPI Publishers, 2019 Feb;8(2):124.

COs								Pos	5				PSO	S
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	1		1	1	1									2
2	3		2	2	2								1	3
3	3		2	2	2								2	3
4	3		2	2	2								1	2
5	3		2	2	2									2

PROFESSIONAL ELECTIVE II (SEMESTER -VI)

Course	Course Title	L	Т	Р	С
Code					
UEE2621	WIND ENERGY CONVERSION SYSTEMS	3	0	0	3
Objectives:					
• To lease	rn the design and control principles of Wind turbine.				
• To un	derstand the concepts of fixed speed and variable spe	eed	winc	d ene	ergy
conver	rsion systems.				
• To ana	lyze the grid integration issues.				
Unit I I	NTRODUCTION			Ģ)
Components	of WECS-WECS schemes-Power obtained from wind-si	mple	e mo	omen	tum
theory - Powe	r coefficient- Sabinin'stheory-Aerodynamics of Wind turbin	ie.			
	VIND TURBINES			ç)
HAWT-VAW	T-Power developed -Thrust-Efficiency-Rotor Selection	on-R	otor	de	sign
considerations	Tip speed ratio-No. of Blades-Blade profile-Power Regula	tion	-yaw	ont	rol-
Pitch angle co	ntrol stall control-Schemes for maximum power extraction.				
Unit III F	IXED SPEED SYSTEMS			Ģ)
Generating Sy	stems- Constant speed constant frequency systems -Choic	e of	Ger	nerato	ors -
Deciding fact	ors-Synchronous Generator-Squirrel Cage Induction Gen	erato	or- N	Aode	l of
Wind Speed-	Model wind turbine rotor - Drive Train model- Generator	mod	el fo	or Ste	ady
state and Tran	sient stability analysis.				
Unit IV V	ARIABLE SPEED SYSTEMS			ç)
	ble speed systems-Power-wind speed characteristics - Varial	-	-		
frequency sys	stems synchronous generator- DFIG- PMSG -Variable	spee	d g	enera	tors
modelling - V	ariable speed variable frequency schemes.				
Unit V G	GRID CONNECTED SYSTEMS			9)
	nection requirements, low-voltage ride through (LVRT), ram	-			
and supply of	ancillary services for frequency and voltage control, curr	ent	prac	tices	and
•	s wind interconnection impact on steady-state and dynamic p	erfo	rmar	nce of	the
power system	including modelling issue.				
	Total I	Perio	ods	4	5
	omes: Upon successful completion of the course, students w			e to	
-	knowledge on the basic concepts of wind energy conversion	ı sys	tem		
	strate the types of wind turbine and aero dynamics				
=	the principle of fixed speed system.				
	e the working and design of variable speed system.				
	the grid integration issues and current practices of wind int	erco	nnec	tion.	
Text Books:					
	Wind Energy conversion Systems", Prentice Hall, 1990	-			
2.S.N.Bhadra,	D.Kastha, S.Banerjee,"Wind Electrical Sytems",Ox	ford	U	nive	sity
Press,2010.					

References:

1. Ion Boldea, "Variable speed generators", Taylor & Francis group, 2006.

2.E.W.Golding "The generation of Electricity by wind power", Redwood burn Ltd., Trowbridge, 1976

3. N. Jenkins," Wind Energy Technology" John Wiley & Sons, 1997

4.S.Heir "Grid Integration of WECS", Wiley 1998.

COs					POs									S
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	2												1	2
2	3	2	1											2
3	3	2	2	3								2		2
4	3	2	2	3								2	2	3
5	3	2	2	3	3				2	1		2	2	3

Course Code	Course Title	L	T	Р	C
UEE2622	ADVANCED CONTROL THEORY	3	0	0	3
Objectives					

Objectives:

- To give exposure to linear vector spaces.
- To impart knowledge and skills needed to design state feedback controller and state observer fir Time-Invariant Linear system (Continuous time)
- To introduce concepts needed to understand and analyseliner and nonlinear systems.
- To give exposure to design of nonlinear controller
- To provide the ability to apply advanced control strategies to practical engineering Problems
- Unit I

FUNDAMENTAL MATHEMATICS FOR STATE SPACE ANALYSIS

9

9

Linear vector spaces – Basis – Span – Subspaces-Rank Nullity dimension theorem- Similarity transformations- Inner product – Matrix norms - Cayley Hamilton theorem - Quadratic functions and Definiteness of matrices - Projection theorem- Gram Smith orthonormalization procedure – Grammian matrix – Factorization – Eigen decomposition- Jordon form -Singular value decomposition.

Unit II STATE VARIABLE ANALYSIS

Introduction- Concepts of state space – non uniqueness of state model –Evaluation of matrix exponents - Solution of state equations- Decomposition – Controllable, Observable & canonical from- Controllability & Observability - Duality (LTI).

Unit III	STATE CONTROLLER DESIGN	9
Controllabi	lity and Observability Grammians, Open loop minimum energy cont	rol, State

feedback - Pole placement - Design of State regulator & state observer- Separation principle-
Design of servo systems: State feedback with integral control.

Unit IV NON LINEAR SYSTEMS

Common physical nonlinearities, Phase plane method: concepts, Singular points, phase plane trajectories- Stability analysis by describing function method, Jump resonance.

Unit V NON LINEAR CONTROL

Lyapunov's stability theory - Jacobian linearization and gain scheduling - Feedback linearization: Input-output linearization, full-state linearization, stabilization, Sliding Mode Control.

Total Periods

9

9

45

Course Outcomes: Upon successful completion of the course, students will be able to

CO1: Ability to remember and apply linear vector space concepts.

CO2: Ability to design and analyse state feedback controller and state observer.

CO3: Ability to understand and analyse linear and nonlinear systems using phase plane method and analyse nonlinear systems using describing function method.

CO4: Ability to understand and design a nonlinear control

CO5: Ability to apply advanced control strategies to practical engineering problems.

Text Books:

1.M.Gopal, "Digital Control and State Variable Methods", 4th edition, McGraw Hill India, 2012

2.K.P.Mohandas, "Modern Control Engineering", Sanguine Technical Publishers, 2006.

References:

1.M.Gopal, Modern Control System Theory, 3rd edition, New Age International Publishers, 2014.

2.GlibertStang, Introduction to Linear Algebra – 5th Edition, Wellesley - Cambridge Press, 2016

3. William S Levine, "Control System Fundamentals," The Control Handbook, CRC Press, Tayler and Francies Group, 2011.

4. K. Ogata, 'Modern Control Engineering', 5th Edition, Pearson, 2012.

COs								Pos					PSOs	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	3			1									3	
2		2			2								3	2
3		3			2								3	2
4		3	2		2								3	2
5				3	2								3	

Code Image: Code Structure Str	Course	Course Title	L	T	Р	С
Objectives: • To understand the basics of system dynamics in power system. • To understand the modeling of synchronous machine. • To understand excitation systems and speed governing controllers. • To analyze the transient stability of multi machine power system. • To understand the dynamic stability of power system. • To understand the dynamic stability of power system. 9 Basics of system dynamics – numerical techniques – introduction to software packages to study the responses. Concept and importance of power system stability in the operation and design – distinction between transient and dynamic stability of interconnected systems. Unit II SYNCHRONOUS MACHINE MODELLING 9 Synchronous machine - flux linkage equations - Park's transformation - per unit conversion - normalizing the equations - equivalent circuit - current space model - flux linkage state space model. Sub-transient and transient inductances - time constants. Simplified models (one axis and constant flux linkage) - steady state equations and phasor diagrams. 9 Exciter and voltage regulators - function and types of excitation systems - typical excitation system - saturation function - stabilizing circuit. Function of IEEE type 1 9 State equation for multi machine system with one axis machel and simulation – modelling of multi machine system with one axis machel and simulation - modelling of multi machine system with one axis machel and simulation system and speed governing system and simulation signers with one axis machel and simulation system and speed governing system and simulation using R-K method of fourth order (Gill's techniq	Code					1
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 To understand the modeling of synchronous machine. To understand excitation systems and speed governing controllers. To analyze the transient stability of multi machine power system. To understand the dynamic stability of power system. To understand the dynamic stability of power system. INTRODUCTION 9 Basics of system dynamics – numerical techniques – introduction to software packages to study the responses. Concept and importance of power system stability in the operation and design – distinction between transient and dynamic stability - complexity of stability problem in large system – necessity for reduced models - stability of interconnected systems. Unit II SYNCHRONOUS MACHINE MODELLING 9 Synchronous machine - flux linkage equations - Park's transformation - per unit conversion - normalizing the equations - equivalent circuit - current space model - flux linkage state space model. Sub-transient and transient inductances - time constants. Simplified models (one axis and constant flux linkage) - steady state equations and phasor diagrams. Unit III MACHINE CONTROLLERS 9 Exciter and voltage regulators - function and types of excitation systems - typical excitation system - staturation function - stabilizing circuit. Function of IEEE type 1 excitation system - saturation function - stabilizing circuit. Function of speed governing systems - block diagram and state space representation of IEEE mechanical hydraulic governors and electrical hydraulic governors for hydro turbines and steam turbines. Unit IV TRANSENT STABILITY 9 State equation for multi machine system with one axis model and simulation – modelling of multi machine power system and simulation using R-K method of fourth order (Gill's technique) for transient stability analysis - power system stabilizer. For all simulations, the algorithm and flow chart have to be discussed. <l< td=""><td>Objectives:</td><td></td><td></td><td></td><th></th><td></td></l<>	Objectives:					
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design – distinction between transient and dynamic stability - complexity of stability problem in large system – necessity for reduced models - stability of interconnected systems. Unit II SYNCHRONOUS MACHINE MODELLING 9 Synchronous machine - flux linkage equations - Park's transformation - per unit conversion - normalizing the equations - equivalent circuit - current space model - flux linkage state space model. Sub-transient and transient inductances - time constants. Simplified models (one axis and constant flux linkage) - steady state equations and phasor diagrams. Unit III MACHINE CONTROLLERS 9 Exciter and voltage regulators - function and types of excitation systems - typical excitation system - saturation function - stabilizing circuit. Function of IEEE type 1 excitation system - saturation function - stabilizing circuit. Function of speed governing systems - block diagram and state space representation of IEEE mechanical hydraulic governor and electrical hydraulic governors for hydro turbines and steam turbines. 9 State equation for multi machine system with one axis model and simulation – modelling of multi machine system with one axis model including excitation system and speed governing system and simulation using R-K method of fourth order (Gill's technique) for transient stability analysis - power system stabilizer. For all simulations, the algorithm and flow chart have to be discussed. 9 Vint V DYNAMIC STABILITY 9 System response to small disturbances - linear model of the unregulated synchronous machine and its modes of oscillation - regulated synchron	Basics of syst	em dynamics – numerical techniques – introduction to soft	ware	e pac	kage	s to
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Unit II SYNCHRONOUS MACHINE MODELLING 9 Synchronous machine - flux linkage equations - Park's transformation - per unit conversion - normalizing the equations - equivalent circuit - current space model - flux linkage state space model. Sub-transient and transient inductances - time constants. Simplified models (one axis and constant flux linkage) - steady state equations and phasor diagrams. 9 Unit III MACHINE CONTROLLERS 9 Exciter and voltage regulators - function and types of excitation systems - typical excitation system configuration - block diagram and state space representation of IEEE type 1 excitation system - saturation function - stabilizing circuit. Function of speed governing systems - block diagram and state space representation of IEEE mechanical hydraulic governor and electrical hydraulic governors for hydro turbines and steam turbines. 9 State equation for multi machine system with one axis model and simulation - modelling of multi machine system with one axis machine model including excitation system and speed governing system and simulation using R-K method of fourth order (Gill's technique) for transient stability analysis - power system stabilizer. For all simulations, the algorithm and flow chart have to be discussed. 9 Unit V DYNAMIC STABILITY 9 System response to small disturbances - linear model of the unregulated synchronous machine and its modes of oscillation - regulated synchronous machine distribution of power impact - linearization of the load equation for the one machine problem - simplified linear model - effect of excitation on dynamic stability - approximate system representation - supplementary stabilizing signals	problem in lar	ge system – necessity for reduced models - stability of interco	onne	cted	syste	ems.
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governor and electrical hydraulic governors for hydro turbines and steam turbines. 9 Unit IV TRANSIENT STABILITY 9 State equation for multi machine system with one axis model and simulation – modelling of multi machine power system with one axis machine model including excitation system and speed governing system and simulation using R-K method of fourth order (Gill's technique) for transient stability analysis - power system stabilizer. For all simulations, the algorithm and flow chart have to be discussed. 9 Unit V DYNAMIC STABILITY 9 System response to small disturbances - linear model of the unregulated synchronous machine and its modes of oscillation - regulated synchronous machine - distribution of power impact – linearization of the load equation for the one machine problem – simplified linear model - effect of excitation on dynamic stability - approximate system representation - supplementary stabilizing signals – dynamic performance measure - small signal performance measures 45 Course Outcomes: Upon successful completion of the course, students will be able to CO1: Ability to study the basics of dynamics and stability problems. 45	excitation syst	tem - saturation function - stabilizing circuit. Function of	spe	ed g	overi	ning
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State equation for multi machine system with one axis model and simulation – modelling of multi machine power system with one axis machine model including excitation system and speed governing system and simulation using R-K method of fourth order (Gill's technique) for transient stability analysis - power system stabilizer. For all simulations, the algorithm and flow chart have to be discussed. Unit V DYNAMIC STABILITY 9 System response to small disturbances - linear model of the unregulated synchronous machine and its modes of oscillation - regulated synchronous machine - distribution of power impact – linearization of the load equation for the one machine problem – simplified linear model - effect of excitation on dynamic stability - approximate system representation - supplementary stabilizing signals – dynamic performance measure - small signal performance measures 45 Course Outcomes: Upon successful completion of the course, students will be able to CO1: Ability to study the basics of dynamics and stability problems. 45	governor and o	electrical hydraulic governors for hydro turbines and steam t	urbi	nes.		
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System response to small disturbances - linear model of the unregulated synchronous machine and its modes of oscillation - regulated synchronous machine - distribution of power impact – linearization of the load equation for the one machine problem – simplified linear model - effect of excitation on dynamic stability - approximate system representation - supplementary stabilizing signals – dynamic performance measure - small signal performance measures Total Periods 45 Course Outcomes: Upon successful completion of the course, students will be able to CO1: Ability to study the basics of dynamics and stability problems.						
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supplementary stabilizing signals – dynamic performance measure - small signal performance measures Total Periods 45 Course Outcomes: Upon successful completion of the course, students will be able to CO1: Ability to study the basics of dynamics and stability problems.	-			-		
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Total Periods 45 Course Outcomes: Upon successful completion of the course, students will be able to CO1: Ability to study the basics of dynamics and stability problems.			-	smal	l si	gnal
Course Outcomes: Upon successful completion of the course, students will be able to CO1: Ability to study the basics of dynamics and stability problems.	performance n					
CO1: Ability to study the basics of dynamics and stability problems.		Total F	Perio	ods	4	5
CO1: Ability to study the basics of dynamics and stability problems.	Course Outco	omes: Upon successful completion of the course, students w	ill b	e abl	e to	

CO3: Ability to analyse the need and study the operation of the excitation system and speed-governing controllers.

CO4: Ability to analyse the transient stability simulation of multi machine power system.

CO5: Ability to model and analyse the dynamic stability of synchronous machine in power system.

Text Books:

- 1. P.M. Anderson and A.A.Fouad, 'Power System Control and Stability', Galgotia Publications, New Delhi, 2003.
- 2. P. Kundur, 'Power System Stability and Control', McGraw Hill Inc., USA, 1994.

3. R.Ramanujam, "Power System Dynamics – Analysis and Simulation", PHI, 2009. **References:**

1.M.A.Pai and W.Sauer, 'Power System Dynamics and Stability', Pearson Education Asia, India, 2002.

2.James A.Momoh, Mohamed. E. EI-Hawary. "Electric Systems, Dynamics and Stability with Artificial Intelligence applications", Marcel Dekker, USA First Edition, 2000.

- 3. C.A.Gross, "Power System Analysis," Wiley India, 2011.
- 4. B.M.Weedy, B.J.Lory, N.Jenkins, J.B.Ekanayake and G.Strbac," Electric Power Systems", Wiley India, 2013.
- 5. K.Umarao, "Computer Techniques and Models in Power System," I.K. International, 2007.

COs						POs								S
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	3	3	3	3	3									
2	3	3	3	3	3									
3	3	3	3	3	3									
4	3	3	3	3	3								1	
5	3	3	3	3	3								1	

Course Code	Course Title	L	Τ	Р	С		
UEE2624	624VLSI DESIGN TECHNIQUES3						
Objectives:							
•] •] a	To learn the fundamentals of CMOS circuits and its characteris To understand the combinational and sequential circuit design To gain knowledge about design choices of arithmetic circ rchitectures To learn the programming constructs of VHDL			d FI	PGA		
Unit I	MOS TRANSISTOR THEORY			9	9		
NMOS and	PMOS transistors, CMOS logic, MOS transistor theory	/	Intro	oduct	tion,		
Enhancemen	t mode transistor action, Ideal I-V characteristics, DC transf	er cl	narac	cteris	tics,		

	oltage- Body effect- Design equations- Second order effects. MOS mo	dels and
small signal	AC characteristics, Simple MOS capacitance Models.	
Unit II	COMBINATIONAL AND SEQUENTIAL LOGIC CIRCUITS	9
Introduction	n, Static CMOS Design- Complex Logic Gates, Ratioed Logic, Pass-T	ransisto
Logic, Tran	smission gate Logic, Dynamic CMOS Logic Design: Dynamic Logic	e Design
Considerati	ons. Static and Dynamic Latches and Registers, Timing issues, pipelinin	g- Speed
and Power I	Dissipation.	
Unit III	DESIGN OF ARITHMETIC CIRCUITS	9
Adders-Rip	pple carry, Carry-Look ahead, Multiplier using Array based-Ripp	le carry
adder, Ca	rry Save adder, Multiplier -Wallace Tree, Dadda Tree, Booth	, Barre
Shifter, Po	wer and Speed trade-off.	
Unit IV	IMPLEMENTATION STRATEGIES	9
Full custom	and Semi custom design, Standard cell design and cell libraries, Progra	ammable
Logic Devi	ces- PLA, PAL, GAL, CPLD. FPGA building block architectures	, FPGA
interconnec	t routing procedures.	
Unit V	VHDL PROGRAMMING	9
RTL Design	- Structural level Design -combinational logic – Types – Operators – Pa	ckages-
Sequential	circuit - Sub programs - Test benches. (Examples: adder, counters, fl	ip flops
FSM, Multi	plexers / Demultiplexers)	
	Total Periods	45
Course Ou	tcomes: Upon successful completion of the course, students will be able	e to
CO1: Analy	ze the DC and AC characteristics of MOS transistors	
CO2: Desig	n combinational and sequential logic circuits using CMOS and analyze	its
power strate	gies	
CO3: Desig	n arithmetic circuits and analyze its performance metrics	
CO4: Under	rstand and Apply implementation of basic circuits using FPGA	
CO5: Und	erstand and use HDL constructs to develop application specific	digita
architecture	S.	
Text Books	:	
1.Neil H.E	. Weste and Kamran Eshraghian, Principles of CMOS VLSI	Design
Pearson	Education ASIA, 2nd edition, 2000.	
i curboll .		
	abaey ,AnanthaChandrakasan, Borivoje. Nikolic, IDigital Integrated C	ircuits:A
2. Jan M. R	abaey ,AnanthaChandrakasan, Borivoje. Nikolic, IDigital Integrated Carespective, Second Edition , Pearson , 2016.	ircuits:A
2. Jan M. R Design p		
2. Jan M. R Design p	erspective, Second Edition , Pearson , 2016. Perry, 'VHDL Programming By Example', Tata McGraw Hill, 3rdEditie	
 Jan M. R Design p Douglas References 	erspective, Second Edition , Pearson , 2016. Perry, 'VHDL Programming By Example', Tata McGraw Hill, 3rdEditie	on.2007
 Jan M. R Design p Douglas References 	erspective, Second Edition , Pearson , 2016. Perry, 'VHDL Programming By Example', Tata McGraw Hill, 3rdEdition: nell, K.Eshraghian, 'Basic VLSI Design', 3rd Edition, Prentice Hall of	on.2007
2. Jan M. R Design p 3. Douglas References 1.D.A.Puck New Del	erspective, Second Edition , Pearson , 2016. Perry, 'VHDL Programming By Example', Tata McGraw Hill, 3rdEdition: nell, K.Eshraghian, 'Basic VLSI Design', 3rd Edition, Prentice Hall of	on.2007
 Jan M. R Design p Douglas I References 1.D.A.Puck New Del Wayne W 	erspective, Second Edition , Pearson , 2016. Perry, 'VHDL Programming By Example', Tata McGraw Hill, 3rdEdition nell, K.Eshraghian, 'Basic VLSI Design', 3rd Edition, Prentice Hall of hi, 2003	on.2007
2. Jan M. R Design p 3. Douglas 3. References D.A.Puck New Del 2. Wayne W	erspective, Second Edition , Pearson , 2016. Perry, 'VHDL Programming By Example', Tata McGraw Hill, 3rdEdition: nell, K.Eshraghian, 'Basic VLSI Design', 3rd Edition, Prentice Hall of hi, 2003 Volf ''Modern VLSI Design System on chip. Pearson Education.2002.	on.2007

2002

5. Eugene D.Fabricius, Introduction to VLSI Design McGraw Hill International Editions,

1990.

COs								POs					PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	
1	3											2	2		
2	3	3	2	2									2	1	
3	3	3	2	2									1	1	
4	3	2	2			1						2	2		
5	3		2	2	2	1						2	2		

Course	Course Title	L	Т	Р	C
Code			-	•	
UEE2625	SWITCHED MODE POWER SUPPLIES	3	0	0	3
Objectives:					<u> </u>
• To un	derstand the basic concepts and operation of efficient switch	hed-	mod	de po	ower
conve	rsion techniques.				
• To pro	ovide conceptual knowledge in modern power electronic c	conv	erter	s and	d its
applic	ations in electric power utility.				
Unit I I	BASIC DC-DC CONVERTER CIRCUITS			Ģ	9
Operation and	d design of Buck , Boost , Buck- Boost and Cuk Converter	rs (1	both	CCN	Л &
DCM), Choic	e of switching frequency and applications.				
Unit II I	SOLATED SMPS			Ģ	9
Operation and	d design of Fly back Converter, Forward Converter, Half	-Bri	dge	and	Full
Bridge Conve	erters, Push-Pull Converter and SMPS with multiple outputs.				
Unit III (CONTROL ASPECTS OF SMPS			Ģ	9
PWM Control	llers, Isolation in feedback loop, Power Supplies with multipl	e ou	tput.	Stab	ility
analysis using	g Bode Diagrams				
Unit IV I	DESIGN CONSIDERATIONS OF SMPS			Ç	9
Selection of o	output filter capacitor, Selection of energy storage inductor	, De	sign	of H	ligh
Frequency Inc	ductor and High frequency Transformer, Selection of switche	s. Sr	nubb	er ciı	cuit
design, Desig	n of driver circuits.				
Unit V I	ELECTROMAGNETIC INTERFERENCE (EMI)			9	9
	Components, Conducted EMI suppression, Radiated E			-	
Measurement	. Protection - Over current protection, over voltage protection	on, I	nrus	h cur	rent
-	nermal Model - Thermal Resistance, Cooling Considerations,	Sele	ection	n of I	Heat
sinks, Simple	Heat sink calculations.				
	Total I	Perio	ods	4	5

Course Outcomes: Upon successful completion of the course, students will be able to

CO1: Outline the fundamentals of isolated and non-isolated converter for SMPS.

CO2: Analyze the feedback controller for regulated output voltage.

CO3: Choose appropriate components for the design of SMPS.

CO4: Analyze and simulate various power electronic converter topologies.

CO5: Assess the thermal performance of SMPS, and design suitable filters and heat sink.

Text Books:

- 1. H. W. Whittington, B. W. Flynn and D. E. MacPherson, Switched Mode Power Supplies, Design and Construction, Universities Press, 2009 Edition.
- 2. Mohan N. Undeland T. & Robbins W., Power Electronics Converters, Application and Design. John Wiley, 3rd edition, 2002

References:

1.KreinP.T .Elements of Power Electronics., Oxford University Press

2. M. H. Rashid, Power Electronics. Prentice-Hall of India

3.Umanand L., Bhat S.R., Design of magnetic components for switched Mode Power Converters., Wiley Eastern Ltd.,1992

4. Robert. W. Erickson, D. Maksimovic, Funda

mentals of Power Electronics, Springer International Edition, 2005

5. Course Material on Switched Mode Power Conversion, V. Ramanarayanan

COs								POs	5				PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	
1	3														
2	3	2			1										
3	3	2	2	2	1								1	2	
4	3	2	1	2	3					1		2	1	2	
5	2	2	2	2	2								1	2	

Course Title Т С Course L Р Code **UEE2626** 3 **ENERGY STORAGE SYSTEMS** 3 0 0 **Objectives:** To understand the concepts and technologies used in various multidisciplinary energy storage devices. To understand selection and sizing of a suitable energy storage device for a specific application. • To learn the energy storage management for grid connected power systems. THERMAL ENERGY STORAGE Unit I 9 Thermal Energy - Principle - Benefits - Criteria for Evaluation - Operating Characteristics -Sensible, Latent and Cold Thermal Energy Storage - Heating and Cooling Applications Unit II ELECTROCHEMICAL ENERGY STORAGE 9 Battery composition, Construction and Principle of operation of Secondary batteries -Modern batteries - Flow batteries - High temperature batteries; Fuel Cells - Operation, Types **Unit III** ELECTROMAGNETIC ENERGY STORAGE Energy Storage in Capacitors - Supercapacitors - Principle - Charging and Discharging Characteristics - Types - Equivalent Circuits; Superconducting magnetic energy storage -Principles - Superconducting coils - Cryogenic systems- Energy transfer efficiency **Unit IV** MECHANICAL ENERGY STORAGE 9 Flywheel storage - Structure - System dynamics - Operation; Compressed air energy storage-Principle - Function - Technical characteristics; Pumped hydro storage - Principle - power extraction system Unit V **ENERGY STORAGE MANAGEMENT** 9 Techno-Economic Analysis - Estimation of Energy Storage - Dynamic Energy Storage Management for dependable Renewable Electricity Generation - Energy Storage Installations in the Power System - Grid Tied AC Microgrid Applications **Total Periods** 45 Course Outcomes: Upon successful completion of the course, students will be able to CO1: Describe the thermal energy storage systems and their applications. CO2: Illustrate the operating principles of electrochemical energy storage systems. CO3: Summarize the principles underpinning the operation of electromagnetic energy storage systems. CO4: Explain the operation of mechanical energy storage systems. CO5: Solve the grid integration issues of renewable energy sources by energy storage techniques. **Text Books:** 1. J. K. Kaldellis, Stand-alone and Hybrid Wind Energy Systems -Technology, Energy Storage and Applications, Woodhead Publishing Series in Energy, CRC Press, 2010 2. Rosario Carbone, Energy Storage in the Emerging Era of Smart Grids, 2011, InTech

PROFESSIONAL ELECTIVE- III (SEMESTER – VI)

References:

- 1. Frank S. Barnes & Jonah G. Levine, Large Energy storage Systems Handbook, CRC Press, 2011.
- 2. Ziad Melhem, Electricity transmission, distribution and storage systems, Woodhead Publishing Series in Energy, 2013.
- 3. H. P. Garg, S. C. Mullick, A. K. Bhargava, Solar Thermal Energy Storage, Springer, 1985.
- 4. Artur Braun, Electrochemical Energy Systems- Foundations, Energy Storage and Conversion, De Gruyter, CPI Books, 2018.
- 5. Robert A. Huggins, Energy Storage, Springer, 2010.

COs		POs													
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	
1		3	2	2	2								1	3	
2		3	2	2	2									2	
3		3	2	2	2								1	2	
4		3	2	2	2									2	
5		3	3	2	2					2			2	3	

Course Code	Course Title	L	Т	Р	С
UEE2627	SYSTEM IDENTIFICATION AND ADAPTIVE CONTROL	3	0	0	3

Objectives:

- To impart knowledge on how to recursively estimate the parameters of discrete input output models (BJ/MA/ARX/ARMAX etc.) using least squares method and recursive parameter estimation methods.
- To enable the student to tune the PID controller parameters using various auto tuning methods applied to real time systems.
- To make the student understand the principles of STR, MRAC and Gain scheduling with real time applications
- To make the student design simple adaptive controllers for linear systems using above methods.

8

8

Unit I NON-PARAMETRIC METHODS

Non-parametric methods - Transient analysis - frequency analysis - Correlation analysis - Spectral analysis - Input signal design for identification

Unit II PARAMETRIC METHODS

Least squares estimation - Analysis of the least squares estimate - Best linear unbiased

estimate – N	Model parameterizations - Prediction error methods.	
Unit III	RECURSIVE IDENTIFICATION METHODS	9
The recursi	ve least square methods - Model validation -Model structure determ	nination
Introduction	n to closed loop system identification.	
Unit IV	ADAPTIVE CONTROL SCHEMES	10
Introduction	n – Auto-tuning of PID controller using relay feedback approach –	Types o
adaptive co	ntrol, Gain scheduling, Model reference adaptive control, Self-tuning	controlle
 Design of 	gain scheduled adaptive controller – Applications of gain scheduling	– Conica
Tank System	m Example.	
Unit V	MODEL-REFERENCE ADAPTIVE SYSTEM (MRAS) and	10
	SELF-TUNING REGULATOR (STR)	
STR – Pol	e placement design - Indirect STR and direct STR - MRAC - M	T rule
	heory – Relationship between MRAC and STR - Design of minimum	varianc
controller -	Design of moving average controller -stochastic self-tuning regulators	
	Total Periods	45
Course Ou	tcomes: Upon successful completion of the course, students will be ab	le to
CO1: Abilit	ty to understand various system identification techniques and features of	of
adaptive con	ntrol like STR and MRAC.	
CO2: Abilit	ty to analyze with the analytical concepts of system identification and a	daptive
control		
	ty to understand about Black-box approach-based system identification	•
	ty to Explain the Pontryagin Minimum Principle.	
CO5: Abilit	ty to get knowledge about batch and recursive identification.	
Text Books		
	rom and PetreStoica, System Identification, Prentice Hall International (UK) Ltd
1989		
	Astrom and Bjorn Witten mark, Adaptive Control, Pearson Education	, Secon
	Fifth impression, 2009.	
	angirala, "Principles of System Identification – Theory and Practice", Cl	RC Press
2015.		
References		
	System Identification - Theory for the User, 2nd edition, PTR Prentice addle River, N.J., 1999.	Hall, 11
2. K. S. Nar	rendra and A. M. Annaswamy, Stability Adaptive Systems, Prentice-Ha	all, 1989
3. H. K. Kh	alil, Nonlinear Systems, Prentice Hall, 3rd edition, 2002.	
4 William	S.Levine, "Control Systems Advanced Methods, the Control Handbo	ok, CRO
T. William	11	
Press 20	11.	

COs								PO	5				PSOs			
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1	3				3							3				
2	3	1	2	2	2	1				1		2				
3	3		2		2	2						3				
4			2		2	2										
5				1	1					1	1					

Course	Course Title	L	Т	Р	С
Code					
UEE2628	ARTIFICIAL INTELLIGENCE FOR POWER	3	0	0	3
	SYSTEMS				
Objectives:					
• To in	troduce operating principles of Intelligent System a	nd	Evo	lutio	nary
progra	mming techniques.				
• To exp	plain the application of Intelligent system and Evolution	ary	prog	ramn	ning
technic	ques to power system problems like optimal power flow,	vol	tage	and	var
contro	l, vulnerability assessment and control co-ordination problem	ns			
Unit I I	NTELLIGENT SYSTEM			Ģ)
	s – Architecture and Implementation – Fuzzy Logic Systems		-	nenta	tion
	gorithm – Artificial Neural Network – Overview and Formu	latio	on		
	VOLUTIONARY PROGRAMMING			-)
	n Optimization – Formulation and Algorithm – Ant Color	•	-		
	nd Algorithm – Genetic Algorithm – Implementation and A	Algo	rithr	n - 1	abu
	s and procedure for developing Tabus PTIMAL POWER FLOW PROBLEM				9
		hm	Euo	-	
	ion – Application of ANN, Fuzzy Logic, Genetic Algorit – Tabu Search – PSO and Ant Colony Optimization – Case			iutio	nai y
	OLTAGE AND VAR CONTROL	Stut	1 y)
		1'	41		
	ormulation – Application of Fuzzy Logic, PSO, Genetic A ization – Case Study	igor	unm	and	Ant
	ULNERABILITY ASSESSMENT AND CONTROL			ç)
0	COORDINATION				
	Assessment – Generalized model – Challenges – Applicati	on c	of Al	NN, I	PSO
Vulnerability	Assessment – Generalized model – Challenges – Applicati lgorithm – Case study	on c	of Al	NN, I	PSO
Vulnerability and Genetic A	lgorithm – Case study				
Vulnerability and Genetic A Control Coord		n of	Fuzz	zy Lo	ogic,
Vulnerability and Genetic A Control Coord	lgorithm – Case study lination – Problem definition and formulation - Application	n of atior	Fuzz	zy Lo	ogic, tudy
Vulnerability and Genetic A Control Coord	lgorithm – Case study lination – Problem definition and formulation - Application n Optimization, Genetic Algorithm and Ant Colony Optimization	n of atior	Fuzz	zy Lo ase st	ogic, tudy
Vulnerability and Genetic A Control Coord Particle Swarr	lgorithm – Case study lination – Problem definition and formulation - Application n Optimization, Genetic Algorithm and Ant Colony Optimization	n of atior Perio	Fuzz = C	zy Lo ase st 4	ogic, tudy

Logic Systems and Artificial Neural Network.

CO2: Understand and comprehend the principles lying behind Evolutionary program techniques like PSO, ACO, GA, EP, TS.

CO3: Apply Intelligent system technique and EP based technique to solve complex nonlinear optimal power flow problem.

CO4: Apply Intelligent system technique and EP based technique to voltage and VAR control problems in power system.

CO5: Apply Intelligent system technique and EP based technique to Vulnerability Assessment Control Coordination in power System.

Text Books:

- 1. Momoh, James A, "Adaptive stochastic optimization techniques with applications" CRC Press, 2016.
- 2. Kevin Warwick, Arthur Ekwue and Raj Aggarwal, "Artificial Intelligence Techniques in Power Systems" IET Power and energy series, First edition, 1997.
- 3. W Ongsakul, D.N Vo,"Artificial Intelligence in Power System Optimization", CRC Press, 2013

References:

- 1. James A. Momoh, Mohamed E. El-Hawary, "Electric Systems, Dynamics, and Stability with Artificial Intelligence Applications" Power Engineering CRC Press (1999)
- 2. Erik Cuevas, Emilio Barocio Espejo, Arturo Conde Enríquez, "Metaheuristics Algorithms in Power Systems" Springer International Publishing, 2019
- Ahmed F. Zobaa, Alfredo Vaccaro, "Computational Intelligence Applications in Smart Grids_ Enabling Methodologies for Proactive and Self-Organizing Power Systems", Imperial College Press, 2015.

COs								POs					PSOs	
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2	3	3		3	3							1		
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4	3	3	2	3	3							1	1	
5	3	3	2	3	3							1	1	

Course	Course Title	L	Т	Р	С					
Code										
UEE2629	AUTOMOTIVE ELECTRONICS	3	0	0	3					
Objectives:										
• To underst	• To understand the emission standards of automotive electronic systems									

• To understand the electronic modules used in automotive applications such as ignition system, engine control system, sensors and actuators

electro	nics	
Unit I	INTRODUCTION	8
Evolution	of electronics in automobiles – emission laws – introduction to Euro I,	, Euro II,
Euro III, H	Euro IV, Euro V standards – Equivalent Bharat Standards. Charging	systems:
Working a	nd design of charging circuit diagram – Alternators – Requirements of	f starting
system - St	arter motors and starter circuits.	
Unit II	IGNITION AND INJECTION SYSTEMS	10
Ignition sy	stems: Ignition fundamentals - Electronic ignition systems - Programmed	l Ignition
 Distribut 	ion less ignition - Direct ignition - Spark Plugs. Electronic fuel Control	ol: Basics
of combus	tion – Engine fuelling and exhaust emissions – Electronic control of ca	rburetion
– Petrol fu	el injection – Diesel fuel injection.	
Unit III	SENSOR AND ACTUATORS IN AUTOMOTIVES	7
	rinciple and characteristics of Airflow rate, Engine crankshaft angular	-
	, Throttle angle, temperature, exhaust gas oxygen sensors – study of fuel	•
-	s recirculation actuators, stepper motor actuator, vacuum operated actua	
Unit IV	ENGINE CONTROL SYSTEMS	10
	odes for fuel control-engine control subsystems – ignition control method t ECU's used in the engine management – block diagram of the	
		-
manageme	nt system. In vehicle networks: CAN standard, format of CAN sta	andard –
-	nt system. In vehicle networks: CAN standard, format of CAN states systems in modern automobiles.	andard –
diagnostics Unit V Traction	systems in modern automobiles. CHASSIS AND SAFETY SYSTEMS control system – Cruise control system – electronic control of a	10 utomatic
diagnostics Unit V Traction c transmissio	systems in modern automobiles. CHASSIS AND SAFETY SYSTEMS control system – Cruise control system – electronic control of a on – antilock braking system – electronic suspension system – working MEMS in airbag systems – centralized door locking system – climate control syst	10 utomatic of airbag
diagnostics Unit V Traction c transmissic and role of	systems in modern automobiles. CHASSIS AND SAFETY SYSTEMS control system – Cruise control system – electronic control of a on – antilock braking system – electronic suspension system – working	10 automatic of airbag control of
diagnostics Unit V Traction c transmissic and role of cars.	systems in modern automobiles. CHASSIS AND SAFETY SYSTEMS control system – Cruise control system – electronic control of a on – antilock braking system – electronic suspension system – working MEMS in airbag systems – centralized door locking system – climate c Total Periods	10 nutomatic of airbag control of 45
diagnostics Unit V Traction of transmission and role of cars. Course On	systems in modern automobiles. CHASSIS AND SAFETY SYSTEMS control system – Cruise control system – electronic control of a on – antilock braking system – electronic suspension system – working MEMS in airbag systems – centralized door locking system – climate control syst	10 nutomatic of airbag control of 45
diagnostics Unit V Traction of transmission and role of cars. Course On CO1: Know	Systems in modern automobiles. CHASSIS AND SAFETY SYSTEMS control system – Cruise control system – electronic control of a on – antilock braking system – electronic suspension system – working MEMS in airbag systems – centralized door locking system – climate c Total Periods atcomes: Upon successful completion of the course, students will be able w the importance of emission standards in automobiles.	10 automatic of airbag control of 45 le to
diagnostics Unit V Traction of transmission and role of cars. Course On CO1: Know CO2: Under	Systems in modern automobiles. CHASSIS AND SAFETY SYSTEMS control system – Cruise control system – electronic control of a on – antilock braking system – electronic suspension system – working MEMS in airbag systems – centralized door locking system – climate c Total Periods atcomes: Upon successful completion of the course, students will be able w the importance of emission standards in automobiles. erstand the electronic fuel injection/ignition components and their function	10 automatic of airbag control of 45 le to
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diagnostics Unit V Traction of transmission and role of cars. Course On CO1: Know CO2: Unde CO3: Choo temperatur CO4: Anal	A systems in modern automobiles. CHASSIS AND SAFETY SYSTEMS control system – Cruise control system – electronic control of a son – antilock braking system – electronic suspension system – working MEMS in airbag systems – centralized door locking system – climate control systems. Total Periods atcomes: Upon successful completion of the course, students will be able with a importance of emission standards in automobiles. erstand the electronic fuel injection/ignition components and their functions and use sensors and equipment for measuring mechanical quantities, e and appropriate actuators. yses the chassis and vehicle safety system.	10 nutomatic of airbag control of 45 le to
diagnostics Unit V Traction of transmission and role of cars. Course On CO1: Know CO2: Unde CO3: Choo temperatur CO4: Anal	A systems in modern automobiles. CHASSIS AND SAFETY SYSTEMS control system – Cruise control system – electronic control of a on – antilock braking system – electronic suspension system – working MEMS in airbag systems – centralized door locking system – climate control systems: Upon successful completion of the course, students will be able with the importance of emission standards in automobiles. erstand the electronic fuel injection/ignition components and their functions and use sensors and equipment for measuring mechanical quantities, e and appropriate actuators. yses the chassis and vehicle safety system. yse various methods of power system earthing.	10 nutomatic of airbag control of 45 le to
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4. Tom Denton, "Automobile Electrical and Electronics Systems", Edward Arnold Publishers, 2000.

COs	POs													
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3	3	2	2	1			1						2	2
4	3	3	2			1	2							2
5	3	2	2	1		3	2						1	2

Course											
Code											
UEE2631	31ELECTRICAL MACHINE DESIGN30										
Objectives:											
• To im	part knowledge on the following topics:										
• Influer											
electri	cal machines and their design considerations										
 Design 	n of Armature and field systems of D.C. machines and Co	re, yo	oke, '	wind	ings						
and co	oling systems of transformers.										
Design	n of stator and rotor of induction machines and synchronous	s mac	chine	s.							
• The in	portance of computer aided design methods and use it for th	ne des	sign o	of spe	ecial						
machi	nes like brushless dc, permanent magnet synchronous m	nachi	nes,	swite	ched						
relucta	nce and synchronous reluctance machines										
Unit I F	UNDAMENTAL ASPECTS OF ELECTRICAL MAC	IINI	E	9	9						
E	DESIGN										
Design of M	achines, Design Factors, Limitations in design, Modern	Tren	ds in	n des	sign,						
manufacturing	g Techniques. Dimensions and Rating of Machines, Mate	rials	for I	Electi	rical						
Machines, He	ating and Cooling of Machines, Magnetic Circuit Calculation	ons, (Calcu	ilatio	n of						
MMF, Estima	tion of True and Apparent Flux Densities, Iron Losses, Leal	kage	Calc	culati	ons,						
thermal rating											
Unit II E	DESIGN OF DC MACHINES AND TRANSFORMERS			ļ	9						
Output Equat	Output Equation, Choice of Specific Loadings and Choice of Number of Poles, Main										
Dimensions o	f armature, Design of Armature Slot Dimensions, Commu	tator	and	Brus	hes.						
Estimation of	Ampere Turns for the Magnetic Circuit. Dimensions of Yo	oke, N	Main	Pole	and						
Air Gap. Desi	gn of Shunt and Series Field Windings.										
Output Equat	ions of Single Phase and Three Phase Transformers, C	Choic	e of	Spee	cific						
Loadings, Ex	pression for Volts/Turn, Determination of Main Dimens	sions	of t	he C	ore,						
Estimation of	Number of Turns and Conductor Cross Sectional are	a of	Prin	nary	and						

Secondary	Windings, No Load Current. Expression for the Leakage Reactance of c	~ 1
transforme	r with concentric coils, and calculation of Voltage Regulation. Design	of Tank
and Coolin		
Unit III	DESIGN OF THREE PHASE INDUCTION MOTORS	9
Output Equ	ation, Choice of Specific Loadings, Main Dimensions of Stator. Design	of stato
	Vinding, Choice of Length Air Gap, Estimation of Number of Slots for	
	r. Design of Rotor Bars and End Ring. Design of Slip Ring rotor. Estin	-
-	urrent and Leakage Reactance.	
Unit IV	DESIGN OF THREE PHASE SYNCHRONOUS MACHINES	9
Output Eq	uation, Choice of Specific Loadings, Short Circuit Ratio, Main Dimer	nsions o
Stator. Des	ign of stator slots and Winding. Design of Salient and non- salient Pole	e Rotors
Magnetic C	Circuit and Field Winding.	
Unit V	COMPUTER AIDED DESIGN AND ANALYSIS OF SPECIAL	9
	MACHINES	
Introductio	n to Finite element method - historical background, applications, adv	antages
Study of ne	w computer aided machine software using Finite Element. Case study: C	Complete
design of S	witched Reluctance machine, Permanent Magnet Synchronous Machine	e Design
of Brushles	s DC machine Design of Synchronous reluctance machine	
	Total Periods	45
	Itcomes: Upon successful completion of the course, students will be able	
CO1: Unde	erstand basics of design considerations for rotating and static electrical m	
CO1: Unde and apprec	erstand basics of design considerations for rotating and static electrical m iate the importance of magnetic circuit calculations	
CO1: Under and apprec CO2: Desig	erstand basics of design considerations for rotating and static electrical m iate the importance of magnetic circuit calculations gn and analyze single, three phase transformer and DC machines	
CO1: Unde and apprec CO2: Desig CO3: Desig	erstand basics of design considerations for rotating and static electrical m iate the importance of magnetic circuit calculations gn and analyze single, three phase transformer and DC machines gn and analyze stator and rotor of induction motor	
CO1: Under and apprec CO2: Desig CO3: Desig CO4: Desig	erstand basics of design considerations for rotating and static electrical m iate the importance of magnetic circuit calculations gn and analyze single, three phase transformer and DC machines gn and analyze stator and rotor of induction motor gn and analyze stator and rotor of synchronous motor	
CO1: Unde and apprec CO2: Desig CO3: Desig CO4: Desig CO5: Desig	erstand basics of design considerations for rotating and static electrical m iate the importance of magnetic circuit calculations gn and analyze single, three phase transformer and DC machines gn and analyze stator and rotor of induction motor gn and analyze stator and rotor of synchronous motor gn of special machines by computer aided methods	
CO1: Under and apprec CO2: Desig CO3: Desig CO4: Desig CO5: Desig Text Book	erstand basics of design considerations for rotating and static electrical materiate the importance of magnetic circuit calculations gn and analyze single, three phase transformer and DC machines gn and analyze stator and rotor of induction motor gn and analyze stator and rotor of synchronous motor gn of special machines by computer aided methods s:	nachines
CO1: Unde and apprec CO2: Desig CO3: Desig CO4: Desig CO5: Desig Text Book 1. Sawhney	erstand basics of design considerations for rotating and static electrical m iate the importance of magnetic circuit calculations gn and analyze single, three phase transformer and DC machines gn and analyze stator and rotor of induction motor gn and analyze stator and rotor of synchronous motor gn of special machines by computer aided methods	nachines
CO1: Unde and apprec CO2: Desig CO3: Desig CO4: Desig CO5: Desig Text Book 1. Sawhney Delhi, F	erstand basics of design considerations for rotating and static electrical m iate the importance of magnetic circuit calculations gn and analyze single, three phase transformer and DC machines gn and analyze stator and rotor of induction motor gn and analyze stator and rotor of synchronous motor gn of special machines by computer aided methods s: 7, A.K., 'A Course in Electrical Machine Design', Dhanpat Rai& Sons, I	nachines
CO1: Under and apprec CO2: Desig CO3: Desig CO4: Desig CO5: Desig Text Book 1. Sawhney Delhi, F	erstand basics of design considerations for rotating and static electrical m iate the importance of magnetic circuit calculations gn and analyze single, three phase transformer and DC machines gn and analyze stator and rotor of induction motor gn and analyze stator and rotor of synchronous motor gn of special machines by computer aided methods s: /, A.K., 'A Course in Electrical Machine Design', Dhanpat Rai& Sons, I ifth Edition, 1984. , V.S Nagarajan, 'Electrical Machine Design', Pearson, 2017.	nachines
CO1: Unde and apprec CO2: Desig CO3: Desig CO4: Desig CO5: Desig Text Book 1. Sawhney Delhi, F 2. V Rajini Reference	erstand basics of design considerations for rotating and static electrical m iate the importance of magnetic circuit calculations gn and analyze single, three phase transformer and DC machines gn and analyze stator and rotor of induction motor gn and analyze stator and rotor of synchronous motor gn of special machines by computer aided methods s: /, A.K., 'A Course in Electrical Machine Design', Dhanpat Rai& Sons, I ifth Edition, 1984. , V.S Nagarajan, 'Electrical Machine Design', Pearson, 2017.	New
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CO1: Unde and apprec CO2: Desig CO3: Desig CO4: Desig CO5: Desig Text Book 1. Sawhney Delhi, F 2. V Rajini Reference 2. V.N. Mi Distribu 3. Sen, S.	erstand basics of design considerations for rotating and static electrical militate the importance of magnetic circuit calculations gn and analyze single, three phase transformer and DC machines gn and analyze stator and rotor of induction motor gn and analyze stator and rotor of synchronous motor gn of special machines by computer aided methods s: 7, A.K., 'A Course in Electrical Machine Design', Dhanpat Rai& Sons, I ifth Edition, 1984. , V.S Nagarajan, 'Electrical Machine Design', Pearson, 2017. S: ttle and A. Mittle, 'Design of Electrical Machines', Standard Publications a tors, Delhi, 2002.	New
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CO1: Unde and apprec CO2: Desig CO3: Desig CO4: Desig CO5: Desig Text Book 1. Sawhney Delhi, F 2. V Rajini References 2. V.N. Mi Distribu 3. Sen, S.I IBH Pu 4. M.V.K. Problem 5. K.G. U 6. R.K. Ag 2002.	erstand basics of design considerations for rotating and static electrical mitiate the importance of magnetic circuit calculations gn and analyze single, three phase transformer and DC machines gn and analyze stator and rotor of induction motor gn and analyze stator and rotor of synchronous motor gn of special machines by computer aided methods s: /, A.K., 'A Course in Electrical Machine Design', Dhanpat Rai& Sons, I ifth Edition, 1984. , V.S Nagarajan, 'Electrical Machine Design', Pearson, 2017. s: ttle and A. Mittle, 'Design of Electrical Machines', Standard Publications a tors, Delhi, 2002. K, "Principles of Electric Machine Design with Computer Programmes", C blishing Co. Pvt. Ltd., 2001, Reprint 2004. Chari and P.P. Silvester, "Finite Elements in Electric and Magnetic Field ns", John Wiley, 1980. padhyay, 'Design of Electrical Machines', New Age International Publisher	New New Ind Dxford & rs,2008. Pelhi,

COs	POs PSC													
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3	3	3	3	1	3	3	2		1	1	1	1	3	3
4	3	3	3	1	3	3	2		1	1	1	1	3	3
5	2	2	2	2	2	2			2	2	1	3	3	3

PROFESSIONAL ELECTIVE – IV (SEMESTER- VII)

Course									
Code									
UEE2721	SMART GRID	3	0	0	3				
Objectives:									
• To u	nderstand the function of smart grid and the components use	ed in	it.						
• To u	nderstand various technologies and control used in smart gri	d.							
Unit I	INTRODUCTION TO SMART GRID			ç)				
Evolution of	Electric Grid, Need for Smart Grid, Difference between con	nvent	iona	l &Sı	nart				
Grid, Smart	grid drivers, Benefits, Functions of smart grid components	s, Ov	ervie	w of	the				
technologies	required for the Smart Grid, National and International In	nitiat	ives	in Sı	nart				
Grid.									
Unit II	SMART GRID TECHNOLOGIES			Ģ)				
Technology	Drivers, Smart energy resources: Renewable generation	, En	ergy	stor	age,				
Electric Veh	icles, Microgrids, Smart substations: protection, monito	oring	and	con	trol,				
Transmission	n systems: EMS, FACTS and HVDC, Wide area monitor	oring	, Dis	stribu	tion				
systems: DM	S, Volt/VAR control, Fault Detection, Isolation and service	esto	ration	ı, Ou	tage				
management	, High-Efficiency Distribution Transformers.Distribution	tion	au	toma	tion				
equipment.									
Unit III	SENSING, CONTROL AND AUTOMATION			9)				
	TECHNOLOGIES								
Smart meter	ing, Smart meters: An overview of the hardware used,	Co	mmu	nicat	ions				
infrastructure	e and protocols for smart metering, Advanced Metering Inf	rastr	uctur	e (Al	MI),				
	and Benefits, AMIN needs in smart grid, AMI standards and	secu	rity, I	Dema	and-				
side integrati	on.								
	COMMUNICATION TECHNOLOGIES FOR THE SM GRID	ARI	[Ģ)				
Data commu	nication- Switching techniques, Communication channels, La	ayere	d arc	hitec	ture				
	s, Communication Technologies-Communications Requirem	-							
Grid, Wirele	ss Network Solutions, Communication Standards and Proto	cols,	Stan	dards	s for				
information e	exchange, Communications Challenges in the Smart Grid.								
Unit V	HIGH PERFORMANCE COMPUTING AND CYBER			Ģ)				
	SECURITY								
Computation	al Challenges in a Smart Grid, Existing Functions Improved a	and N	lew I	Funct	ions				
Enabled by H	IPC, Cyber security in the Smart Grid- Definitions, Security I	Funct	ions,	Secu	ırity				
Threats, Cyb	er security in the Smart Grid, Digital signatures, Cyber secu	rity s	tanda	ards.					
	Total	Peri	ods	4	5				
Course Out	comes: Upon successful completion of the course, students w	will b	e abl	e to					
CO1: Explain	n the concepts of smart grid and its latest developments								
	be the different smart grid technologies in energy utilization,	, con	trol a	nd					
automation									

CO3: Illustrate smart metering infrastructure and demand side management

CO4: Explain the data communication and computing techniques for smart grid applications

CO5: Describe high performance computing and information security for smart grid **Text Books:**

Text Books:

1. Stuart Borlase "Smart Grid: Infrastructure, Technology and Solutions", CRC Press 2013.

2.JanakaEkanayake,NickJenkins,KithsiriLiyanage,JianzhongWu,AkihikoYokoyama, "Smart Grid: Technology and Applications",Wiley 2012.

References:

- 1. James Momoh, "Smart Grid Fundamentals of Design and Analysis", Wiley, 2012 .
- 2. Tony Flick, Justin morehouse, "Securing the smart grid: Next generation power grid security", Elsevier, 2010
- 3. Daphne Mah, Peter Hills, Victor O.K. Li, Richard Balme -Smart Grid Applications and Developments-Springer, 2014.

COs		POs													
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	
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2	3	2		1									1	2	
3	3	2		1	1								1	3	
4	3	2	2	1								1		2	
5	3		2	1								1	1	2	

Course	Course Title	L	Т	Р	С					
Code										
UEE2722	PRINCIPLES OF ROBOTICS	3	0	0	3					
Objectives:										
• To introdu	ce the functional elements of Robotics									
• To impart	• To impart knowledge on the direct and inverse kinematics									
• To introduce the manipulator differential motion and control										
• To educate	• To educate on various path planning techniques									
• To introdu	ce the dynamics and control of manipulators									
Unit I	BASIC CONCEPTS – CONFIGURATION SPACE & RI	GID)	ç)					
	BODY MOTION									
Robot Mech	nanism - Types, Joints - Degree of freedom - configu	ratio	n sp	pace	and					
constraints-	constraintsRotation- linear and angular velocities- Homogeneous transformation matrix -									
twists -wren	twists -wrench -exponential coordinate representation of rigid body									
Unit II	FORWARD KINEMATICS AND MANUPLATOR MOT	IOI	N	ç)					
Mathematica	Mathematical representation - DenavitHatenberg parameters - Product of exponents -									

Manipulato	r Jacobian – Singularity analysis – Manipulability – static analysis -	- force and
motion bala		
Unit III	INVERSE AND DIFFERENTIAL KINEMATICS	9
Inverse Kin	ematics PUMA 6R & Stanford Type arm robots- Solvability - Solutio	n methods-
	n solution-numerical algorithms – Differential Kinematics - Stew	
	General Parallel Mechanis	
Unit IV	TRAJECTORY AND MOTION PLANNING	9
	oint trajectories - Joint space technique- Time Scaling - Use o	-
	-Cubic polynomial- S-Curve - Cartesian space technique – Methods	
	Grid method - Graph search -A* search- Sampling method – Rapid	
	ee (RRT) & Probabilistic Road map (PRM)	r - 8
Unit V	DYNAMICS AND CONTROL	9
	mechanics-2DOF Manipulator-Lagrange Euler formulation- New	
	– Constrained dynamics - Manipulator control problem-Linear control	
	l scheme-Motion control - Force control and Impedance control	
manipulato		
1	Total Period	s 45
Course Ou	tcomes: Upon successful completion of the course, students will be a	ble to
CO1: Unde	rstand the dynamics of Robot in constrained space.	
CO2: Unde	rstand and Analyze Forward Kinematics and differential motion.	
CO3: Abili	y to Apply Different Control techniques to Robotics	
CO4: Abili	y to Apply Trajectory and Motion planning in Robotics.	
CO5: Abili	ty to understand and analyse Robotic systems and their applications	to various
industries		
Text Books	:	
1. Kevin M	. Lynch & Frank C. Park, Modern Robotics Mechanics, Planning, and	nd Control,
Cambrid	ge University press, 1st Print ,2017	
2.R.K.Mitta	l and I.J.Nagrath, Robotics and Control, Tata McGraw Hill, New	Delhi,4th
Reprint,	2005.	
3.JohnJ.Cra	ig ,Introduction to Robotics Mechanics and Control, Third editio	n, Pearson
Educatio	n, 2009	
4.M.P.Groo	ver, M.Weiss, R.N. Nageland N. G.Odrej, Industrial Robotics, Me	cGraw-Hill
Singapor	re, 1996	
References	:	
1.Ashitava	Ghoshal, Robotics-Fundamental Concepts and Analysis', Oxford	University
Press, Si	xth impression, 2010.	
2. K. K.Ap	buKuttan, Robotics, I K International, 2007.	
3. Edwin W	ise, Applied Robotics, Cengage Learning, 2003.	
4.R.D.Klaft	er,T.A.Chimielewski and M.Negin, Robotic Engineering-An	Integrated
Approac	h, Prentice Hall of India, New Delhi, 1994.	
COs	POs	PSOs

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1	3	3											3	3
2	3	3											3	3
3				3	2								3	3
4				3	2								3	3
5	3	3	3	3									3	3

Course	Course Title	L	Т	Р	С
Code					
UEE2723	INTERNET OF THINGS IN POWER SYSTEM	3	0	0	3
	ENGINEERING	3	U	U	3
Objectives:					
•	To understand the basics of IoT and its architecture				
•	To learn the various IoT protocols				
•	To implement big data analytics and use cloud compu	iting	for	real-	time
	applications in power system				
Unit I I	BASICS OF IoT			ļ)
Evolution of I	Internet of Things - Enabling Technologies – IoT Architectu	ires:	oneN	12M,	IoT
World Forum	(IoTWF) and Alternative IoT models - Simplified IoT Arc	hited	ture	and C	Core
IoT Functiona	al Stack Fog, Edge and Cloud in IoT Functional blocks o	f an 1	loT e	cosys	stem
– Sensors, Ac	tuators, Smart Objects and Connecting Smart Objects				
Unit II I	oT PROTOCOLS			ļ)
IoT Access	Technologies: Physical and MAC layers, topology	and	Sec	curity	of
IEEE802.15.4	4,802.15.4g, 802.15.4e, 1901.2a, 802.11ah and LoRaWAN	- N	etwo	rk La	yer:
IPversions, C	Constrained Nodes and Constrained Networks - Optim	izing	IP	for	IoT:
From6LoWPA	AN to 6Lo, Routing over Low Power and Lossy Netwo	orks -	– Ap	plica	tion
TransportMet	hods: Supervisory Control and Data Acquisition – A	Appli	catic	n L	ayer
Protocols: Co	AP and MQTT				
Unit III I	DESIGN AND DEVELOPMENT			Ģ)
Design Metho	odology - Embedded computing logic - Microcontroller, Systematics	tem o	on Ch	ips –	IoT
system buildi	ing blocks - Arduino - Board details, IDE programming	- R	aspbe	erry]	Pi –
Interfaces and	Raspberry Pi with Python Programming.				
Unit IV I	DATA ANALYTICS AND SUPPORTING SERVICES			ļ)
	s Unstructured Data and Data in Motion Vs Data in				
MachineLear	ning –No SQL Databases – Hadoop Ecosystem – Apache Ka	ıfka,	Apac	che S	park
– Edge Stream	ning Analytics and Network Analytics - Xively Cloud for	· IoT	, Pyt	hon V	Web
	ramework – Django – AWS for IoT – System Managemen	t wit	h NE	TCO	NF-
YANG					
Unit V (CASE STUDIES/INDUSTRIAL APPLICATIONS			ļ)
-	stem - IBM Watson IoT platform - Manufacturing - Con	-	-		
Ethernet Mod	lel (CPwE) – Power Utility Industry – Grid Blocks Referen	nce N	Лode	l - Sı	nart

and Connected Cities: Layered architecture, Smart Lighting, Smart Parking Architecture and Smart TrafficControl

Total Periods

45

Course Outcomes: Upon successful completion of the course, students will be able to

CO1 Explain the concept of IoT.

CO2: Analyze various protocols for IoT.

CO3: Design a PoC of an IoT system using Rasperry Pi/Arduino

CO4: Apply data analytics and use cloud offerings related to IoT.

CO5: Analyze applications of IoT in real time scenario in Electric

Text Books:

1. David Hanes, Gonzalo Salgueiro, Patrick Grossetete, Rob Barton and Jerome Henry, — IoT Fundamentals: Networking Technologies, Protocols and Use Cases for Internet of Things, Cisco Press, 2017

References:

1.ArshdeepBahga, Vijay Madisetti, —Internet of Things – A hands-on approach, Universities Press, 2015

2. Olivier Hersent, David Boswarthick, Omar Elloumi, —The Internet of Things – Keyapplications and Protocols, Wiley, 2012 (for Unit 2).

3. Jan Ho⁻⁻ ller, VlasiosTsiatsis, Catherine Mulligan, Stamatis, Karnouskos, Stefan Avesand.

4. Dieter Uckelmann, Mark Harrison, Michahelles, Florian (Eds), —Architecting the Internetof Things I, Springer, 2011.

5.Michael Margolis, Arduino Cookbook, Recipes to Begin, Expand, and Enhance Your Projects, 2 nd Edition, O'Reilly Media, 2011.

6. David Boyle, "From Machine-to-Machine to the Internet of Things - Introduction to a New Age of Intelligence", Elsevier, 2014.

COs								POs					PSC	Os
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3	3		3		2	1	1	2			2	2	1	
4	3		3		3	1	2	2			2	2		
5	3		3	1	3	1	2	2			3	2		

Course Code	Course Title	L	Т	Р	С
UEE2724	POWER SEMICONDUCTOR DEVICES	3	0	0	3
Objectives:					

The student should be made to:

- Understand the static and dynamic characteristics of various current controlled and voltage controlled power semiconductor devices.
- Learn the advanced devices and new materials for power devices
- Explore the design and selection of devices for different power electronics applications.
- Familiarize the control and firing circuit for different power devices

- I un	niliarize the control and firing circuit for different power devices	
Unit I	INTRODUCTION	9
Power swit	ching devices overview – Attributes of an ideal switch, application requi	irements
Safe operat	ing Area; Device selection strategy – On-state and switching losses, EN	
switching -	Power diodes - operation, static and switching characteristics- Types.	
Unit II	CURRENT CONTROLLED DEVICES	9
BJT-Cons	truction, static and switching characteristic, second breakdown; - Thyris	stors –
1 0	node, Two transistor analogy; Gate and switching characteristics; Gate	turn-off
	comparison of BJT and Thyristor.	
Unit III	VOLTAGE CONTROLLED DEVICES	9
-	f voltage controlled devices; Power MOSFETs and IGBTs – construction	on, types
	circuits, static and switching characteristics, Comparison.	
Unit IV	EMERGING DEVICES	9
MCT, FC	Г, RCT, IGCT; New semiconductor materials for devices - Super	junction
Structures,	Silicon Carbide Power Devices, Gallium Nitride Power Devices	– Powe
Integrated	Circuits	
Unit V	FIRING AND PROTECTING CIRCUITS	9
Necessity of	f isolation, pulse transformer, optocoupler – Gate drives circuit: SCR, M	IOSFET
•		
IGBTs and	base driving for power BJT Over voltage, over current and gate pro-	
IGBTs and		
IGBTs and	base driving for power BJT Over voltage, over current and gate pro- rcuits; Thermal protection - heat sink types and design	otections
IGBTs and Snubber cir	base driving for power BJT Over voltage, over current and gate pro- rcuits; Thermal protection - heat sink types and design	otections 45
IGBTs and Snubber cir Course Ou	base driving for power BJT Over voltage, over current and gate pro rcuits; Thermal protection - heat sink types and design Total Periods	otections 45
IGBTs and Snubber cir Course Ou CO1: deter	base driving for power BJT Over voltage, over current and gate pro- rcuits; Thermal protection - heat sink types and design Total Periods Itcomes: Upon successful completion of the course, students will be abl	e to
IGBTs and Snubber cir Course Ou CO1: deter CO2: descr	base driving for power BJT Over voltage, over current and gate pro- rcuits; Thermal protection - heat sink types and design Total Periods Itcomes: Upon successful completion of the course, students will be abl mine the suitable device for an application	e to
IGBTs and Snubber cir Course Ou CO1: deter CO2: descr	base driving for power BJT Over voltage, over current and gate pro- rcuits; Thermal protection - heat sink types and design Total Periods tcomes: Upon successful completion of the course, students will be abl mine the suitable device for an application tibe the physical operation and characteristics of power semiconductor d	e to
IGBTs and Snubber cir Course Ou CO1: deter CO2: descr CO3: emph fabrication	base driving for power BJT Over voltage, over current and gate pro- rcuits; Thermal protection - heat sink types and design Total Periods tcomes: Upon successful completion of the course, students will be abl mine the suitable device for an application tibe the physical operation and characteristics of power semiconductor d	e to
IGBTs and Snubber cir Course Ou CO1: deter CO2: descr CO3: emph fabrication CO4: desig	base driving for power BJT Over voltage, over current and gate pro- rcuits; Thermal protection - heat sink types and design Total Periods Itcomes: Upon successful completion of the course, students will be abl mine the suitable device for an application ibe the physical operation and characteristics of power semiconductor d hasize the principle of advanced power devices and new materials for de	e to
IGBTs and Snubber cir Course Ou CO1: deter CO2: descr CO3: emph fabrication CO4: desig	base driving for power BJT Over voltage, over current and gate pro- rcuits; Thermal protection - heat sink types and design Total Periods Itcomes: Upon successful completion of the course, students will be abl mine the suitable device for an application ibe the physical operation and characteristics of power semiconductor d hasize the principle of advanced power devices and new materials for de m of protection circuits and control circuits termine the reliability of the system	e to
IGBTs and Snubber cir Course Ou CO1: deter CO2: descr CO3: empt fabrication CO4: desig CO5: to de Text Book	base driving for power BJT Over voltage, over current and gate pro- rcuits; Thermal protection - heat sink types and design Total Periods Itcomes: Upon successful completion of the course, students will be abl mine the suitable device for an application ibe the physical operation and characteristics of power semiconductor d hasize the principle of advanced power devices and new materials for de m of protection circuits and control circuits termine the reliability of the system	e to levice
IGBTs and Snubber cir Course Ou CO1: deter CO2: descr CO3: empt fabrication CO4: desig CO5: to de Text Book 1. Mo	base driving for power BJT Over voltage, over current and gate pro- rcuits; Thermal protection - heat sink types and design Total Periods T	e to levice
IGBTs and Snubber cir Course Ou CO1: deter CO2: descr CO3: empt fabrication CO4: desig CO5: to de Text Book 1. Mo Des	base driving for power BJT Over voltage, over current and gate pro- reuits; Thermal protection - heat sink types and design Total Periods Total Periods Itcomes: Upon successful completion of the course, students will be abl mine the suitable device for an application ibe the physical operation and characteristics of power semiconductor d hasize the principle of advanced power devices and new materials for de m of protection circuits and control circuits termine the reliability of the system s: han, Undeland and Robins, Power Electronics – Concepts, Applications	e to levice wice and
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IGBTs and Snubber cir Course Ou CO1: deter CO2: descr CO3: empt fabrication CO4: desig CO5: to de Text Book 1. Mo Des 2. Yun Dev 3. Ras	base driving for power BJT Over voltage, over current and gate pro- recuits; Thermal protection - heat sink types and design Total Periods ttcomes: Upon successful completion of the course, students will be abl mine the suitable device for an application ibe the physical operation and characteristics of power semiconductor d hasize the principle of advanced power devices and new materials for de n of protection circuits and control circuits termine the reliability of the system s: han, Undeland and Robins, Power Electronics – Concepts, Applications han, Undeland and Robins, Singapore, 2000. ng C Liang, Ganesh S Samudra, Chih-Fang Huang, Power Microelectron vice and Process Technologies World Scientific, 2nd Edition, 2017. hid M.H., Power Electronics Circuits, Devices and Applications, Prentic	e to le to levice wice and nics:
IGBTs and Snubber cir Course Ou CO1: deter CO2: descr CO3: empt fabrication CO4: desig CO5: to de Text Book 1. Mo Des 2. Yun Dev 3. Ras	base driving for power BJT Over voltage, over current and gate pro- rcuits; Thermal protection - heat sink types and design Total Periods Iteomes: Upon successful completion of the course, students will be abl mine the suitable device for an application ibe the physical operation and characteristics of power semiconductor d hasize the principle of advanced power devices and new materials for de n of protection circuits and control circuits termine the reliability of the system s: han, Undeland and Robins, Power Electronics – Concepts, Applications fign, John Wiley and Sons, Singapore, 2000. ng C Liang, Ganesh S Samudra, Chih-Fang Huang, Power Microelectron vice and Process Technologies World Scientific, 2nd Edition, 2017. hid M.H., Power Electronics Circuits, Devices and Applications, Prenticia, Third Edition, New Delhi, 2004.	e to le to levice wice and nics:

- 1. Williams B.W., Power Electronics Circuit Devices and Applications.
- 2. Singh M.D., and Khanchandani K.B., Power Electronics, Tata McGraw Hill, 2001.
- 3. Joseph Vithayathil, Power Electronics: Principles and Applications, Delhi, Tata McGraw-Hill, 2010.
- 4. P. S. Bimbhra, Power Electronics, Khanna Publishers.

Cos								POs					PSO	S
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2	3	3	2											2
3	3	3	2	2										2
4	3	3	2	2								1		2
5	3	3	2									1		2

Course Code	Course Title	L	Т	Р	С
UEE2725	FLEXIBLE AC TRANSMISSION SYSTEMS AND	3	0	3	3
	CUSTOM POWER DEVICES	5	v	5	5
Objectives					
• To i	dentify the need for FACTS controllers along with the classif	icatio	on of	vario	ous
	TS controllers under certain sub-categories based on the pow				
	ponents and connection.				
	nalyze the various application of SVC, TCSC and Voltage	Sou	rce (Conve	erter
	d FACTS controllers.				
Unit I	INTRODUCTION			-)
Control of	power flow in AC transmission line, analysis of uncompen	sated	l line	, pas	sive
reactive pow	ver compensation - effect of series and shunt compensation	on p	owe	r tran	sfer
capability, 1	need for FACTS controllers, classification of FACTS control	ollers	s - F2	ACTS	S vs
custom pow	er devices.				
Unit II	STATIC VAR COMPENSATOR (SVC)			1	2
Analysis of	Thyristor Controlled Reactor (TCR), configuration of SVC,	volta	ige c	ontro	l by
SVC, mode	lling of SVC for load flow and transient stability studies, desi	gn o	f SV(C vol	tage
regulator ba	sed on the concept of system gain, Applications: transient sta	bility	enha	ancen	nent
- power osc	llation damping and prevention of voltage instability.				
Unit III	THYRISTOR CONTROLLED SERIES CAPACITOR (TCS	C)	ç)
Need for co	ntrolled series compensation, modes of operation of TCSC, r	node	lling	of TO	CSC
for load flow	v and transient stability studies, applications of TCSC.		-		
Unit IV	VOLTAGE SOURCE CONVERTER BASED FACTS			9)

	I	
	CONTROLLERS	
-	f Static Synchronous Compensator (STATCOM) and Static Synchrono	
Compensat	or (SSSC), power flow control with STATCOM and SSSC, modes of c	operation
in Unified I	Power Flow Controller (UPFC) - applications.	
Unit V	CO-ORDINATION OF FACTS CONTROLLERS	6
Controller i	nteractions, SVC-SVC interaction, Co-ordination of multiple controlle	ers using
linear contr	ol techniques, Control co-ordination using Genetic Algorithm (GA).	
	Total Periods	45
Course Ou	tcomes: Upon successful completion of the course, students will be abl	e to
CO1: Sun	marize the need for FACTS controllers based reactive power compensation	ation.
CO2: Ana	lyze the various application of SVC and subsequently model SVC for p	ower
system stud	ies.	
CO3: Ana	lyze the need for variable series compensation and elaborate the ope	ration of
TCSC.		
CO4: Ana	lyze the operation of Voltage Source Converter based FACTS controlle	ers.
CO5: Des	cribe the FACTS controller interaction and control coordination.	
Text Books	:	
1. R. Moha	nMathur, Rajiv K.Varma, "Thyristor - Based FACTS Controllers for H	Electrical
Transmissio	on Systems ", IEEE press and JohnWiley& Sons, Inc, 2002.	
2.Narain G.	Hingorani, "Understanding FACTS - Concepts and Technology of Flex	xible AC
Transmissio	on Systems ", Standard Publishers Distributors, Delhi, 2011.	
References	:	
1. K.R. Pad	iyar, "FACTS Controllers in Power Transmission and Distribution", N	lew Age
Internationa	l (P) Limited, Publishers, New Delhi, 2008.	-
2. V.K. Soc	d, "HVDC and FACTS controllers - Applications of Static Converters	in

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Power System	", Kluwer Academic	Publishers,	2004.

COs								PO	S				PSC	Ds	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
1	3	3	3	2	1										
2	3	3	3	3	3										
3	3	3													
4	3	3													
5	3	3													

PROFESSIONAL ELECTIVE - V (SEMESTER - VII)

Course	Course Title	L	Τ	Р	С
Code					
UEE2726	DISTRIBUTED GENERATION AND MICRO	3	Δ	0	2
	GRID	3	0	0	3
Objectives:					
To impart kno	owledge about the following topics:				
• To illu	strate the concept of distributed generation				
• To ana	alyze the impact of grid integration.				
• To stu	dy concept of Microgrid and its configuration				
	NTRODUCTION			ļ	9
Conventional	power generation: advantages and disadvantages, Ene	rgy	cris	es, N	Non-
conventional e	energy (NCE) resources: review of Solar PV, Wind Energy sy	ysten	ns, F	uel C	ells.
	s, biomass, and tidal sources.				
Unit II I	DISTRIBUTED GENERATIONS (DG)			ļ	9
Concept of	distributed generations, topologies, selection of sou	urces	s, r	egula	tory
-	nework, Standards for interconnecting Distributed resources			-	-
systems: IEEE	E 1547. DG installation classes, security issues in DG implem	nente	4:	- F	
		icita	ation	s. En	ergy
storage eleme	nts: Batteries, ultra-capacitors, flywheels. Captive power pla		uion	s. En	ergy
				[ergy
Unit III I	nts: Batteries, ultra-capacitors, flywheels. Captive power pla	ants		ļ	9
Unit III I Requirements	nts: Batteries, ultra-capacitors, flywheels. Captive power pla MPACT OF GRID INTEGRATION	ants voltag	ge, fr	eque	9 ncy
Unit IIIIRequirementsTHD, response	nts: Batteries, ultra-capacitors, flywheels. Captive power pla MPACT OF GRID INTEGRATION for grid interconnection, limits on operational parameters,: v	ants voltag es. Ir	ge, fr npac	eque t of) ncy grid
Unit IIIIRequirementsTHD, response	nts: Batteries, ultra-capacitors, flywheels. Captive power plate MPACT OF GRID INTEGRATION for grid interconnection, limits on operational parameters,: v se to grid abnormal operating conditions, islanding issue ith NCE sources on existing power system: reliability, sta	ants voltag es. Ir	ge, fr npac	eque t of) ncy grid
Unit IIIIRequirementsTHD, responseintegrationquality issues	nts: Batteries, ultra-capacitors, flywheels. Captive power plate MPACT OF GRID INTEGRATION for grid interconnection, limits on operational parameters,: v se to grid abnormal operating conditions, islanding issue ith NCE sources on existing power system: reliability, sta	ants voltag es. Ir	ge, fr npac	reque t of nd po) ncy grid
Unit IIIIRequirementsTHD, responsiintegrationwith quality issuesUnit IVF	nts: Batteries, ultra-capacitors, flywheels. Captive power pla MPACT OF GRID INTEGRATION for grid interconnection, limits on operational parameters,: v se to grid abnormal operating conditions, islanding issue ith NCE sources on existing power system: reliability, sta	ants voltaș es. Ir abili	ge, fr npac ty ar	reque t of nd po	ncy grid ower
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Unit IIIIRequirementsTHD, responseintegrationwarequality issuesUnit IVEConcept and amicrogrids, tyPower ElectroUnit VQModes of oper	nts: Batteries, ultra-capacitors, flywheels. Captive power plants: Batteries, ultra-capacitors, flywheels. Captive power plants of the second	ants voltag es. Ir abili view d D d	ge, fr npac ty ar of s C mi	reque t of nd po ource icrog	p ncy grid owe p es o rids nd
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Unit IIIIRequirementsTHD, responsionintegrationunit IVQuality issuesUnit IVPower ElectroUnit VOwner ElectroUnit VOdes of operreactive powercommunicationissues in microsity	nts: Batteries, ultra-capacitors, flywheels. Captive power pla MPACT OF GRID INTEGRATION for grid interconnection, limits on operational parameters,: v se to grid abnormal operating conditions, islanding issue ith NCE sources on existing power system: reliability, sta BASICS OF A MICROGRID definition of microgrids, microgrid drivers and benefits, rev vpical structure and configuration of a microgrids, AC an- onics interfaces in DC and AC microgrids CONTROL AND OPERATION OF MICROGRID ration and control of microgrid: grid connected and islanded er control, protection issues, anti-islanding schemes: pa on based techniques, microgrid communication infrastructure trogrids, regulatory standards, Microgrid economics, Intro-	ants voltag es. Ir abili view d Do mod ssive ure, l oduc	ge, fr npac ty ar of s C mi le, A e, ac Powe tion	reque t of nd po ource icrogi ctive ctive ctive to si	p incy gric ower ower ower ower anc anc anc anc anc
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Unit IIIIRequirementsTHD, responsionintegrationwith quality issuesUnit IVFConcept and amicrogrids, tyPower ElectroUnit VQModes of operreactive powercommunicationissues in micmicrogrids.	nts: Batteries, ultra-capacitors, flywheels. Captive power pla MPACT OF GRID INTEGRATION for grid interconnection, limits on operational parameters,: v se to grid abnormal operating conditions, islanding issue ith NCE sources on existing power system: reliability, sta BASICS OF A MICROGRID definition of microgrids, microgrid drivers and benefits, rev vpical structure and configuration of a microgrids, AC an- onics interfaces in DC and AC microgrids CONTROL AND OPERATION OF MICROGRID ration and control of microgrid: grid connected and islanded er control, protection issues, anti-islanding schemes: pa on based techniques, microgrid communication infrastructure trogrids, regulatory standards, Microgrid economics, Intro- Total I	ants voltag es. Ir abili view d De ssive ure, I oduc Perie	ge, fr npac ty ar of s C m de, A e, ac Powe tion	reque t of nd po ource icrogr ctive ctive er qua to su 4 le to	p ncy gric gric ower ower ower anc anc anc anc anc anc

CO2: Understand the knowledge on the topologies and energy sources of distributed generation.

CO3: Understand and analyse the requirements for grid interconnection and its impact with NCE sources

CO4: Understand the fundamental concept of Microgrid.

CO5: Analyze power quality issues and control operation of micro grid.

Text Books:

- 1.Gevork B. Gharehpetian, S. Mohammad Mousavi Aga, "Distributed Generation Systems: Design, Operation and Grid Integration ", Elsevier, 2017.
- 2. S. Chowdhury, P. Crossley, "Microgrids and Active Distribution Networks", Institution of Engineering and Technology, 2009.

References:

- 1.AmirnaserYezdani, and Reza Iravani, "Voltage Source Converters in Power Systems: Modelling, Control and Applications", IEEE John Wiley Publications, 2010.
- 2.DorinNeacsu, "Power Switching Converters: Medium and High Power", CRC Press, Taylor & Francis, 2006.

3. Chetan Singh Solanki, "Solar Photo Voltaics", PHI learning Pvt. Ltd., New Delhi, 2009.

- 4. J.F. Manwell, J.G. McGowan "Wind Energy Explained, theory design and applications", Wiley publication 2010.
- 5. D. D. Hall and R. P. Grover, "Biomass Regenerable Energy", John Wiley, New York, 1987.
- 6. John Twidell and Tony Weir, "Renewable Energy Resources" Taylor and Francis Publications, Second edition 2006.

COs								Pos					PSOs		
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2	3	2		2										1	
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4	3	2			2		1			1		1	1	2	
5	3	3	3	2	2	1	1		1	1		1	2	3	

Course	Course Title	L	Т	Р	С				
Code									
UEE2727	PLC AND SCADA	3	0	0	3				
Objectives:									
• To ur	derstand automation and control system								
• To understand general PLC and related issues									
• To understand the operation of a PLC, Programming of PLCs									

To understand and able to units simple ledden being more some	
• To understand and able to write simple ladder logic programs	1
Working with SCADA software, implementation of Distributed Control Section 2014 (1997) (Т
Unit I INTRODUCTION TO AUTOMATION	9
Brief Description of a Control System, Pneumatic Controller, PID Control	
Controller, History & Need of Industrial Automation, Application of Industrial Au	tomation,
Basic Components of Automation, Hardware Classification of Automation	1
Unit II GETTING FAMILIAR WITH PLC	9
Type of PLC, Hardware & Architecture of PLC, Application and Advantage	
Sourcing and Sinking concept, Programming Language of a PLC. Introductio	
Device (Input / Output), Data files in PLC Programming, Brief Description of a Lo	-
Simulator analysis of a PLC Programming, Communication with PLC, Wiring diffe	
device to PLC, Uploading, Downloading & Monitoring programs. Introduction	n to SFC,
Introduction to Instruction List, Introduction to Ladder Logic	
Unit III ADVANCE PROGRAMMING IN PLC	9
Introduction to jump and label instruction, Introduction to SBR and JSR instruction	n, Forcing
of I/O, Monitoring/Modifying Data table values, Hands on experience on	real time
applications, Fault finding/troubleshooting and documentation. Interfacing proxim	ity sensor
with PLC, Interfacing with Relay, Control circuit designing with feedback concep	t
Unit IV LADDER LOGIC PROGRAMMING	9
Comparison b/w Gates, Relay Logic & ladder logic, Description of using Memo	ry bit in a
programming, Mathematical Concept ADD, SUB, MUL, DIV and etc. Logical	l Concept
AND, ANI, OR, ORI, EXOR, NOT etc, Special Function, MOV, SET, RST, C	MP, INC,
DEC, Programming based on Timer and Counter	
Unit V GETTING FAMILIAR WITH SCADA	9
Introduction to SCADA Software, Creating new SCADA Project, GUI Design	ning, Tag
Substitutions, Dynamic Process Mimic, Real Time Trend, Historical Trend, How	to create
Alarms & Event, Recipe Management. Introduction to graphic Properties like	te Sizing,
Blinking, Filling, Analog Entry, Movement of Objects, Visibility etc., N	Net DDE
Communication, Application of scripts, Communication with PLC	
Total Periods	45
Course Outcomes: Upon successful completion of the course, students will be ab	ole to
CO1: Explain the concept of automation and control system	
CO2: Explain general PLC and related issues	
CO3: Explain the operation of a PLC, Programming of PLCs	
CO4: Write simple ladder logic programs	
CO5: Explain the working of SCADA software, implementation of Distribute	d Control
Scheme	
Text Books:	
1. Gary Dunning, "Introduction to Programmable Logic Controllers", Thomson, 21	nd Edition
2. John R. Hackworth, Frederick D., Hackworth Jr., "Programmable Logic Contro	ollers
2. John R. Hackworth, Frederick D., Hackworth Jr., "Programmable Logic Contro Programming Methods and Applications	ollers

Application", 5th Edition

4. Ronald L. Krutz, "Securing SCADA System", Wiley Publishing

5. Stuart A Boyer, "SCADA supervisory control and data acquisition"

References:

1. Batten G. L., "Programmable Controllers", McGraw Hill Inc., Second Edition

2. Bennett Stuart, "Real Time Computer Control", Prentice Hall, 1988

3.Doebelin E. O., "Measurement Systems", McGraw-Hill International Editions, Fourth Edition, 1990

4. Gordan Clark, Deem Reynders, "Practical Modem SCADA Protocols"

5. Krishna Kant, "Computer Based Industrial Control", PHI

6. M. Chidambaram, "Computer Control of Process", Narosha Publishing

7. P. K. Srivstava, "Programmable Logic Controllers with Applications", BPB Publications

8.PoppovikBhatkar, "Distributed Computer Control for Industrial Automation", Dekkar Publications

9. S. K. Singh, "Computer Aided Process Control", PHI

10. Sunil S. Rao, "Switchgear and Protections", Khanna Publication

11. Webb J. W, "Programmable Controllers", Merrill Publishing Company, 1988

COs								POs	5				PSOs		
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Course	Course Title	L	Τ	Р	С					
Code										
UEE2728	POWER SYSTEM TRANSIENTS	OWER SYSTEM TRANSIENTS30								
Objectives:										
• To st	udy the different types, causes and effects of power system t	ransi	ents							
• To st	udy the mechanism of lighting strokes.									
• To u	nderstand the generation of switching transients.									
• To u	nderstand and analyse the propagation, reflection and refra	ction	of t	ravel	ling					
wave	s in power transmission lines.									
• To a	nalyse the impact of voltage transients caused by various type	es of	fault	s in						
integ	rated power system.									
Unit I	INTRODUCTION			ç	9					

Doviou	l importance of the study of transients - causes for transients. RL circuit	tranciant
	•	
	ave excitation - double frequency transients - basic transforms of the RI	
	Different types of power system transients - effect of transients on powe	r systems
	e study of transients in system planning.	1
Unit II	SWITCHING TRANSIENTS	9
Over voltag	ges due to switching transients - resistance switching and the equivale	nt circuit
for interrup	ting the resistor current - load switching and equivalent circuit - wave	forms for
transientvo	ltage across the load and the switch - normal and abnormal switching t	ransients.
Current sup	pression - current chopping - effective equivalent circuit. Capacitance s	switching
- effect of s	ource regulation - capacitance switching with a restrike, with multiple	restrikes.
Illustration	for multiple restriking transients - ferro resonance.	
Unit III	LIGHTNING TRANSIENTS	9
Review of	he theories in the formation of clouds and charge formation - rate of ch	arging of
	uds – mechanism of lightning discharges and characteristics of lightnin	
- model fo	r lightning stroke - factors contributing to good line design - protect	ion using
	es – tower footing resistance - Interaction between lightning and power	-
Unit IV	TRAVELING WAVES ON TRANSMISSION LINE	9
Computatio	on of transients - transient response of systems with series and shun	t lumped
-	and distributed lines. Traveling wave concept - step response - Bewely	-
	standing waves and natural frequencies - reflection and refraction of	
waves.		0
Unit V	TRANSIENTS IN INTEGRATED POWER SYSTEM	9
The short	line and kilometric fault - distribution of voltages in a power syste	m - Line
	nd load rejection - voltage transients on closing and reclosing lines - over	
	faults -switching surges on integrated system Qualitative application	-
for transien	t computation	
	Total Periods	45
Course Ou	tcomes: Upon successful completion of the course, students will be ab	le to
CO1: Abili	ty to study various types and causes of power system transients and stu	dy the
effect of tra	insients on power systems	
CO2: Abili	ty to understand the generation of switching transients and their control	using
circuit – the	eoretical concept.	-
CO3: Abili	ty to study the mechanism of lighting strokes and the production of lighting strokes and the production of lighting strokes and the production of lighting strokes are strokes as the production of lighting strokes as the producting strokes as the production of lighting	nting
surges.		e
_	y to analyse the propagation, reflection and refraction of travelling way	es.
	y to analyse the impact of voltage transients caused by faults, circuit	
	rejection on integrated power system.	
Text Book		
	eenwood, 'Electrical Transients in Power Systems', Wiley Inter Scient	nce. New
	2nd Edition, 1991.	,
	Chowdhari, "Electromagnetic transients in Power System", John Wiley	and Sone
	cond Edition, 2009.	and 20118
шс.,5е	Conu Luiuon, 2007.	

3. C.S. Indulkar, D.P.Kothari, K. Ramalingam, 'Power System Transients – A statistical approach', PHI Learning Private Limited, Second Edition, 2010.

References:

- 1.M.S.Naidu and V.Kamaraju, 'High Voltage Engineering', Tata McGraw Hill, Fifth Edition, 2013.
- 2. R.D. Begamudre, 'Extra High Voltage AC Transmission Engineering', Wiley Eastern Limited,1986.
- 3.Y.Hase, Handbook of Power System Engineering," Wiley India, 2012.
- 4.J.L.Kirtley, "Electric Power Principles, Sources, Conversion, Distribution and use," Wiley, 2012.

COs								PO	S				PSC	Os	
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5	3	3	3	2	3										

Course Code	Course Title	L	Т	P	С
UEE2729	EMBEDDED SYSTEMS	3	0	0	3
Objectives:			L		
• To un	derstand the Building Blocks and architectures of l	Embed	ded Syste	em	
• To lea	arn various communication protocols used in Embe	edded r	networkin	ıg	
• To g	ain knowledge about RTOS and embedded s	system	based a	applic	ation
devel	opment				
Unit I I	NTRODUCTION TO EMBEDDED SYSTEM				9
Introduction to I	Embedded Systems -Structural units in Embedded	ed pro	cessor, s	electio	on of
processor & mer	nory devices- DMA – Memory management meth	nods- 7	Timer and	d Cou	nting
devices, Watchdo	og Timer, Real Time Clock, In circuit emulator, Ta	rget Ha	ardware I	Debug	ging.
Unit II F	EMBEDDED NETWORKING			(9
Embedded Netw	orking: Introduction, I/O Device Ports & Buses-S	Serial 1	Bus com	munic	ation
protocols RS232	standard - RS422 - RS 485 - CAN Bus -Serial P	eriphei	al Interfa	ace (S	PI) –
Inter Integrated C	Circuits (I2C) – Ethernet - need for device drivers.				
Unit III F	EMBEDDED ARCHITECTURES				9
Instruction Set A	Architecture-CISC architecture [8051] and RISC i	nstruct	tion set a	rchite	cture
[ARM processor	s], DSP Processors, Harvard Architecture-PIC. Co	oproces	ssors and	Hard	lware
Accelerators, Pro	ocessor Performance Enhancement-Pipelining, Sup	per-sca	lar Execu	ition,	CPU
Power Consump	otion, Memory System Architecture-, Caches, V	/irtual	Memory	, Me	mory
management unit	t and address Translation.				

Unit IV RTOS BASED SYSTEM DESIGN	9
Introduction to basic concepts of RTOS- Task, process & threads, interrupt routine	s in RTOS,
Multiprocessing and Multitasking, Preemptive and non-preemptive schedu	ling, Task
communication shared memory, message passing-, Inter process Commu	nication –
synchronization between processes-semaphores, Mailbox, pipes, priority inversi	on, priority
inheritance	
Unit V EMBEDDED SYSTEM APPLICATION	9
Open-loop and Closed Loop Control Systems-Application Examples-Washing	g Machine,
Automotive Systems, Smart Card system, Auto-focusing digital camera, Air-o	conditioner,
Elevator Control System, ATM System.	
Total Periods	45
Course Outcomes: Upon successful completion of the course, students will be abl	le to
CO1: Explain and use the basic modules of embedded system	
CO2: Explain and use fundamentals and standards of communication framework a	mong the
modules of embedded system	
CO3: Select a suitable processor for the system design	
CO4: Illustrate the salient features in designing a real time system using RTOS	
CO5:Analyse and understand various case studies of system development.	
Text Books:	
1.Peckol, "Embedded system Design", John Wiley & Sons,2010	
2. Shibu. K.V, "Introduction to Embedded Systems", 2e, Mcgraw Hill, 2017.	
References:	
1. Raj Kamal, 'Embedded System-Architecture, Programming, Design', McGraw	Hill, 2013.
2. Lyla B Das," Embedded Systems-An Integrated Approach", Pearson, 2013	
3.C.R.Sarma, "Embedded Systems Engineering", University Press (India) Pvt. Ltd	, 2013.
4. Tammy Noergaard, "Embedded Systems Architecture", Elsevier, 2006.	
5. Han-Way Huang, "Embedded system Design Using C8051", Cengage Learning	, 2009.
6.Rajib Mall "Real-Time systems Theory and Practice" Pearson Education, 2007.	
7. David E. Simon, "An Embedded Software Primer", Pearson Education, 1999.	
8.Waynewolf, "Computers as components", Morgan Kaufmann publishers, 2nd Ec	lition2008.
9.Dr. Prasad, "Embedded Real Time System", Wiley Dreamtech, 2004.	
10. Jean J.Labrosse, "Embedded system building blocks", CMP books, 2ndEdition	, 1999.
	<u>-</u>
COs POs	PSOs
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2	3		2										2	2
3	3	2	2										2	2
4	3			2	2								1	
5	2	3	3	3	2	1						2	1	2

Course Code	Course Title	L	Т	Р	С
UEE2731	HIGH VOLTAGE DIRECT CURRENT				
	TRANSMISSION	3	0	0	3
Objectives:					
0	lerstand the principles and types of HVDC system.				
	niliarize with the control and protection techniques in HVD0	C sy	stem		
	NTRODUCTION	5		9)
Development	of HVDC technology, Advantages of HVDC Systems, HVI	DC S	Syste	m Co	osts,
-	d Organization of HVDC Systems, HVDC System R		-		
	s and Economic Aspects, Planning for HVDC transmission,		-		
	logy, HVDC Applications.				
	NALYSIS OF HVDC CONVERTERS			9)
Basic convers	ion principle, Selection of converter configuration, Com	muta	ation	proc	ess,
	inverter operation, Analysis of Graetz circuit with and				
Converter brid	ge characteristics.				-
Unit III C	CONTROL OF HVDC CONVERTERS AND SYSTEMS)		ç)
Principles of I	DC link control, Converter control - characteristics, System	cont	rol h	ierar	chy,
Firing angle co	ontrol, Current and extinction angle control, Starting and sto	oppii	ng of	DC l	ink,
Power control	Higher level controllers, HVDC Control Functions.				
Unit IV R	EACTIVE POWER CONTROL AND HARMONICS			Ģ)
Reactive powe	er requirements in steady state, Sources of reactive power, Sta	atic V	VAR	syste	ems,
Generation of	harmonics, Effect of increasing pulse number, Determin	atio	n of	resul	ting
harmonic imp	edance, AC filters, DC side filters, Active power filters.				
Unit V F	AULT DEVELOPMENT AND PROTECTION			Ģ)
Converter dist	curbances, AC system fault, DC line fault, Fault analysis,	Val	lve p	rotec	tion
functions, Pro	tective action of an HVDC system, Protection by control	act	ions,	DC	line
protection, Fil	ter protection				
	Total	Peri	ods	4	5
Course Outco	omes: Upon successful completion of the course, students w	vill b	e abl	e to	
-	the principle and types of HVDC system				
	HVDC converters and their performance characteristics				
CO3: Describe	e the control of converters and reactive power management	in H	VDC	2	
CO4: Analyze	the harmonics and fault conditions in HVDC				
CO5: Design t	he controllers, filters and protection circuits for HVDC				
Text Books:					
1.Padiyar,K.R	.,"HVDC power transmission system", New Age In	tern	ation	al(P)	Ltd.
NewDelh	i, Second Edition,2010.				
2.Arrillaga,J.,	High Voltage Direct Current Transmission", Peter Pregrinu	ıs, L	ondc	on,19	83.
3.DraganJovci	c and Khaled Ahmed, High Voltage Direct Current Transmi	ssio	n: Co	nver	ters,
Systems a	nd DC Grids, Wiley, 2015.				

1.KundurP.," Power System Stability and Control", McGraw-Hill, 1993.

- 2. Colin Adamson and HingoraniNG," High Voltage Direct Current Power Transmission", Garraway Limited, London, 1960.
- 3. Edward Wilson Kimbark," Direct Current Transmission", Vol.I, Wiley inter science, New York, London, Sydney, 1971.
- 4. Chan-Ki Kim, "HVDC TRANSMISSION Power Conversion Applications in Power Systems", John Wiley & Sons Pvt. Ltd., 2009

COs								PO	s				PSOs	
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1	3			1								1		
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3	3	2	2											
4	3	2			1								2	1
5	3	2	2	2	3							2	2	1

PROFESSIONAL ELECTIVE – VI (SEMESTER – VIII)

Course	Course Title	L	Т	Р	C
Code					
UEE2821	ELECTRIC VEHICLES AND POWER	3	0	0	3
	MANAGEMENT	5	U	U	5
Objectives:					
• To provid	le knowledge about electric vehicle architecture and power tra	in c	omp	onen	ts.
• To know	the concepts of dynamics of electrical vehicles				
• To impart vehicles(t knowledge on vehicle control for standard drive cycles of HEVs)	hyl	orid	elect	rical
• To under	stand the concept of energy storage systems.				
	le knowledge about different energy sources and energy mana	gen	nent	in HE	EVs
Unit I	HYBRID ELECTRIC VEHICLE ARCHITECTURE POWER TRAIN COMPONENTS	<u> </u>			9
History of e	volution of Electric Vehicles - Comparison of Electric Vehic	cles	with	ı Inte	rna
•	Engines - Architecture of Electric Vehicles (EV) and Hybrid				
	ug-in Hybrid Electric Vehicles (PHEV)- Power train compo				
	hes, Transmission and Brakes – Tamil Nadu Electric Vehicle				0
Unit II	MECHANICS OF HYBRID ELECTRIC VEHICLES				9
Fundamenta	ls of vehicle mechanics - tractive force, power and energy	req	uirer	nents	fo
	ve cycles of HEV's - motor torque and power rating and batter	-			
Unit III	CONTROL OF DC AND AC MOTOR DRIVES	-			9
Speed contr	ol for constant torque, constant HP operation of all electric	mot	ors	- DC	/DC
chopper bas	ed four quadrant operation of DC motor drives, inverter bas	ed Y	V/f (Opera	tior
(motoring a	nd braking) of induction motor drives, vector control opera	tion	of	Induc	tior
motor and P	MSM, Brushless DC motor drives, Switched reluctance motor	r (SI	RM)	drive	es
Unit IV	ENERGY STORAGE SYSTEMS			9	9
Battery: Prin	nciple of operation, types, models, estimation of parameters,	batte	ery r	node	ling
SOC of batt	ery, Traction Batteries and their capacity for standard drive of	cycle	es, V	vehic]	le to
Grid operati	on of EV's. Alternate sources: Fuel cells, Ultra capacitors, Fly	wh	eels.		
Unit V	HYBRID VEHICLE CONTROL STRATEGY AND ENE MANAGEMENT	CRG	Y	-	9
HEV superv	isory control - Selection of modes - power spilt mode - paral	lel r	node	e - en	gine
brake mode	- regeneration mode - series parallel mode - energy management	ent o	of Hl	EV's.	
	Total F	Perio	ods	4	5
Course Out	comes: Upon successful completion of the course, students w	ill b	e ab	le to	
	ate the electric vehicle architecture and power train componen				
	ate the concepts of electric vehicle dynamics.				
	ne the AC and DC motor drive controls employed in electric	vehi	cles.		
CO4: Descri	be the energy storage systems used in electric vehicles.				

electric vehicles.
Text Books:
1. Iqbal Husain, 'Electric and Hybrid Electric Vehicles', CRC Press, 2011.
2. M. Ehsani, Y. Gao, S. Gay and Ali Emadi, "Modern Electric, Hybrid Electric, and Fuel
Cell Vehicles: Fundamentals, Theory, and Design", CRC Press, 2015.
References:

- 1. Wei Liu, 'Hybrid Electric Vehicle System Modeling and Control', Second Edition, Wiley, 2017.
- 2. James Larminie, John Lowry, Electric Vehicle Technology Explained, Wiley, 2003.
- 3. Iqbal Hussain, "Electric & Hybrid Vechicles Design Fundamentals", Second Edition, CRC Press, 2011.
- 4. Sheldon S. Williamson, Energy Management Strategies for Electric and Plug-in Hybrid Electric Vehicles, Springer, 2013.

COs	POs											PSO	PSOs		
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2	3	2	3		2								1	2	
3	3			2	2	1	1		1		1			2	
4	3	2	3	2	2	1	1		1		1		1	2	
5	3		3	2	2	1	1		1		1		2	3	

Course Code	Course Title	L	Τ	Р	C
UEE2822	DIGITAL CONTROL SYSTEM	3	0	0	3
Objectives:			•	-	

Objectives:

To impart knowledge about the following topics:

- Importance of digital control and transforms.
- Introduction to MIMO system and its time response. •
- Concept of Stability in MIMO systems.
- Design digital PID controllers.
- State space analysis of MIMO systems.

Unit I	INTRODUCTION	9								
Introduction to digital control - Sampling Process - Sample and Hold Circuit - Zero and										
First Order hold – Z-Transform – Inverse Z- Transform – Region of convergence – Initial										
and Final V	alue Theorem									
Unit II	PULSE TRANSFER FUNCTION AND TIME RESPONSE	9								
Block diagr	am reduction methods – Reduction Rules- Multi-loop – MIMO Systems	s – Signal								

Flow Grap	oh- steady state error - error transfer functions- Error Constants-Time	-Don	nair
Analysis o	f Second Order Systems-Time Response.		
Unit III	STABILITY	9	
Introductio	on-Jury Stability Test- Schur-Cohn stability Test- Bilinear transfo	ormati	on
Stability b	y Pole Location – Root locus method- Bode Plot- Nyquist Plot.		
Unit IV	DIGITAL PID CONTROLLER	9	
Cascade C	ompensation- Digital Lag Lead Compensator by Bode method- Design	n of I	P,P
and PID C	ontroller- Ziegler's- Nichols Method, Cohen-Coon Method.		
Unit V	STATE SPACE ANALYSIS	9	
Realization	n of Pulse Transfer Function- Diagonalisation- discretization of Continu	ious t	im
systems, S	tate Transition Matrix- Solution of Discrete-time state equations- Contr	ollabi	lit
and Obser	vability.		
	Total Periods	4	5
Course O	utcomes: Upon successful completion of the course, students will be abl	le to	
CO1: Abil	ity to understand the importance of digital Control		
CO2: Abil	ity to solve multi input multi output system MIMO		
CO3: Abil	ity to investigate the stability of MIMO system		
CO4: Abil	ity to apply advanced control theory to practical engineering problems		
Text Book	S:		
1.V.I.Geor	ge and C.P.Kurien, Digital Control System, Cengage Learning, 2012.		
2.B.C.Kuo	, Digital Control System, 2nd Edition, Oxford University Press, 2010.		
3.M.Samil	Fadali, Antonio Visioli, Digital Control Engineering Analysis and	Dest	ign
Acaden	nic.		
Reference	s:		
1.M.Gopal	, 'Digital Control and State Variable Methods', Tata McGraw Hill, 3rd	l Edit	ior
2009.			
2.С.М. Но	oupis, G.B.Lamount, ' Digital Control Systems- Theory, Hardware, S	oftwa	re
	ional Student Edition, McGraw Hill Book Co., 1985.		
	A.Moddgalya, Digital Control, Wiley India, 2007.		
4.C.L.Phil	ips and J.M.Pan, "Feedback Control System, Pearson, 2013.		
COs	Pos PS	Os	
1	2 3 4 5 6 7 8 9 10 11 12 1	2	3

COs	Pos												PSOs			
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3	
1	3	3	3	2	3											
2	3	3	3	3	3											
3	3	3	3	3	3											
4	3	3	3	3	3				3			3				

Course	Course Title	L	Т	Р	С
Code					
UEE2823	ENERGY MANAGEMENT AND AUDITING	3	0	0	3
Objectives:					
-	ne Energy management and auditing process.				
	luce energy management in electrical system				
	ss energy management techniques with respect to motor and	light	ning	load	s.
	ss energy management techniques for buildings.				
	in energy audit process.				<u> </u>
	ENERGY MANAGEMENT IN ELECTRICAL SYSTEM		1'	-)
-	illing - Power Factor improvements and benefits - transform				
	strial system - Assessment of T&D losses in power system	ns -	Dem	and	side
management					<u> </u>
	ELECTRIC ENERGY MANAGEMENT FOR MOTOR			Ç)
	LOADS				
	balanced Voltages on the Performance of Motors - Determin	0			
	oads - Motor Efficiency Management - Motor Performa	ance	Mar	nagen	nent
Process					
	ELECTRIC ENERGY MANAGEMENT FOR LIGHTN SYSTEMS	ING		ļ	9
Rasic narow	eters and terms - light sources and lamp types - Metho	ada a	C	11.	
Dasic parall	icities and terms - light sources and lamp types - when	Jus (of ca	licula	ting
	energy efficient lightning controls - standards and labelling p			licula	iting
luminance -					iting
luminance - Unit IV	energy efficient lightning controls - standards and labelling p	orogra	ams	9	•
luminance -Unit IVEnergy const	energy efficient lightning controls - standards and labelling p ENERGY MANAGEMENT IN BUILDINGS	orogra	ams ntilat	g tion,) Air
luminance - Unit IV Energy cons conditioning	energy efficient lightning controls - standards and labelling p ENERGY MANAGEMENT IN BUILDINGS servation building code (ECBC) - Guidelines on heating	g ve ply, e	ams ntilat escala	tion, ators) Air and
luminance - Unit IV Energy const conditioning elevators - E	energy efficient lightning controls - standards and labelling p ENERGY MANAGEMENT IN BUILDINGS servation building code (ECBC) - Guidelines on heating system, water pumping system, Uninterruptible power supp	g ve ply, e	ams ntilat escala	tion, ators) Air and
luminance - Unit IV Energy cons conditioning elevators - E energy savin	energy efficient lightning controls - standards and labelling p ENERGY MANAGEMENT IN BUILDINGS servation building code (ECBC) - Guidelines on heating system, water pumping system, Uninterruptible power supp energy efficiency measures in buildings - Energy performance	g ve ply, e	ams ntilat escala	tion, ators	Air and and
luminance -Unit IVEnergy constconditioningelevators - Eenergy savinUnit V	energy efficient lightning controls - standards and labelling p ENERGY MANAGEMENT IN BUILDINGS servation building code (ECBC) - Guidelines on heating system, water pumping system, Uninterruptible power supp energy efficiency measures in buildings - Energy performan- gs measures of DG sets	g ve g ve ply, e ce as	ams ntilat escala sessi	tion, ators ment	Air and and
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luminance - Unit IV Energy constructioning conditioning elevators - E energy savin Unit V Energy Aud benchmarkin	energy efficient lightning controls - standards and labelling p ENERGY MANAGEMENT IN BUILDINGS servation building code (ECBC) - Guidelines on heating system, water pumping system, Uninterruptible power supp energy efficiency measures in buildings - Energy performan- gs measures of DG sets ENERGY AUDIT it definition - Need for energy audit - Types of energy audit	g ve ply, e ce as	ams ntilat scala sessi	tion, ators ment	Air and and Ch -
luminance - Unit IV Energy constructioning conditioning elevators - E energy savin Unit V Energy Aud benchmarkir	energy efficient lightning controls - standards and labelling p ENERGY MANAGEMENT IN BUILDINGS servation building code (ECBC) - Guidelines on heating system, water pumping system, Uninterruptible power supplements of provide the system of the system	g ve ply, e ce as dit ar	ams ntilat escala sessi nd ap onito	tion, ators ment	Air and and Ch - and
luminance - Unit IV Energy constructioning conditioning elevators - E energy savin Unit V Energy Aud benchmarking targeting - E	energy efficient lightning controls - standards and labelling p ENERGY MANAGEMENT IN BUILDINGS servation building code (ECBC) - Guidelines on heating system, water pumping system, Uninterruptible power supp energy efficiency measures in buildings - Energy performan- gs measures of DG sets ENERGY AUDIT it definition - Need for energy audit - Types of energy audit of energy efficiency regulation 2008 - energy nergy management information system (EMIS) Total	g ve ply, e ce as dit ar y me	ams ntilat escala sessi nd ap onito	tion, ators ment oproa oring 4	Air and and Ch - and
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luminance - Unit IV Energy constructioning conditioning elevators - E energy savin Unit V Energy Aud benchmarking targeting - E Course Out CO1: Explain	energy efficient lightning controls - standards and labelling p ENERGY MANAGEMENT IN BUILDINGS servation building code (ECBC) - Guidelines on heating system, water pumping system, Uninterruptible power supp energy efficiency measures in buildings - Energy performance gs measures of DG sets ENERGY AUDIT it definition - Need for energy audit - Types of energy audit g - Bureau of energy efficiency regulation 2008 - energy nergy management information system (EMIS) Total comes: Upon successful completion of the course, students v n the concept of electricity billing, power factor improvement	g ve ply, e ce as dit ar gy mo Perio will b	ams ntilat escala sessi ad ap onito ods e abl	tion, ators ment oproa oring 4	Air and and Cch - and 5
luminance - Unit IV Energy constructioning conditioning elevators - E energy savin Unit V Energy Aud benchmarking targeting - E Course Out CO1: Explaig side manage	energy efficient lightning controls - standards and labelling p ENERGY MANAGEMENT IN BUILDINGS servation building code (ECBC) - Guidelines on heating system, water pumping system, Uninterruptible power supp energy efficiency measures in buildings - Energy performan- gs measures of DG sets ENERGY AUDIT it definition - Need for energy audit - Types of energy audit ag - Bureau of energy efficiency regulation 2008 - energy nergy management information system (EMIS) Total comes: Upon successful completion of the course, students v n the concept of electricity billing, power factor improvement ment	g ve ply, e ce as dit ar gy mo Perio will b	ams ntilat escala sessi ad ap onito ods e abl	tion, ators ment oproa oring 4 e to	Air and and Ch - and 5
luminance - Unit IV Energy constructioning conditioning elevators - E energy savin Unit V Energy Aud benchmarking targeting - E Course Out CO1: Explai side manage CO2: Descri	energy efficient lightning controls - standards and labelling p ENERGY MANAGEMENT IN BUILDINGS servation building code (ECBC) - Guidelines on heating system, water pumping system, Uninterruptible power supp energy efficiency measures in buildings - Energy performance gs measures of DG sets ENERGY AUDIT it definition - Need for energy audit - Types of energy audit g - Bureau of energy efficiency regulation 2008 - energy nergy management information system (EMIS) Total comes: Upon successful completion of the course, students v n the concept of electricity billing, power factor improvement ment be the energy performance of Electrical Motors	g ve ply, e ce as dit ar gy mo Perio will b	ams ntilat escala sessi ad ap onito ods e abl	tion, ators ment oproa oring 4 e to	Air and and Ch - and 5
luminance - Unit IV Energy constructioning conditioning elevators - E energy savin Unit V Energy Aud benchmarking targeting - E Course Out CO1: Explais side manage: CO2: Descrit CO3:Descrit	energy efficient lightning controls - standards and labelling p ENERGY MANAGEMENT IN BUILDINGS servation building code (ECBC) - Guidelines on heating system, water pumping system, Uninterruptible power supp energy efficiency measures in buildings - Energy performance gs measures of DG sets ENERGY AUDIT it definition - Need for energy audit - Types of energy audit g - Bureau of energy efficiency regulation 2008 - energy nergy management information system (EMIS) Total comes: Upon successful completion of the course, students v n the concept of electricity billing, power factor improvement ment be the energy performance of Electrical Motors be the energy performance of Lighting System	g ve ply, e ce as dit ar y mo Perio will b at and	ams ntilat escala sessi nd ap onito ods	tion, ators ment oproa ring 4 e to dema	Air and and ch - and 5
luminance - Unit IV Energy constructioning conditioning elevators - E energy savin Unit V Energy Aud benchmarkin targeting - E Course Out CO1: Explai side manage: CO2: Descrit CO4:Explain	energy efficient lightning controls - standards and labelling p ENERGY MANAGEMENT IN BUILDINGS servation building code (ECBC) - Guidelines on heating system, water pumping system, Uninterruptible power supp energy efficiency measures in buildings - Energy performance gs measures of DG sets ENERGY AUDIT it definition - Need for energy audit - Types of energy audit g - Bureau of energy efficiency regulation 2008 - energy nergy management information system (EMIS) Total comes: Upon successful completion of the course, students v n the concept of electricity billing, power factor improvement ment be the energy performance of Electrical Motors be the energy performance of Lighting System n the Energy Conservation building code, Energy Performan	g ve ply, e ce as dit ar y mo Perio will b at and	ams ntilat escala sessi nd ap onito ods	tion, ators ment oproa ring 4 e to dema	Air and and ch - and 5
luminance - Unit IV Energy constructioning conditioning elevators - E energy savin Unit V Energy Aud benchmarking targeting - E Course Out CO1: Explai side manage: CO2: Descrit	energy efficient lightning controls - standards and labelling p ENERGY MANAGEMENT IN BUILDINGS servation building code (ECBC) - Guidelines on heating system, water pumping system, Uninterruptible power supp energy efficiency measures in buildings - Energy performance gs measures of DG sets ENERGY AUDIT it definition - Need for energy audit - Types of energy audit g - Bureau of energy efficiency regulation 2008 - energy nergy management information system (EMIS) Total comes: Upon successful completion of the course, students v n the concept of electricity billing, power factor improvement ment be the energy performance of Electrical Motors be the energy performance of Lighting System n the Energy Conservation building code, Energy Performan	g ve ply, e ce as dit ar y mo Perio will b at and	ams ntilat escala sessi nd ap onito ods	tion, ators ment oproa ring 4 e to dema	Air and and ch - and 5
luminance - Unit IV Energy constructioning conditioning elevators - E energy savin Unit V Energy Aud benchmarkint targeting - E Course Out CO1: Explait side manage: CO2: Descrit CO3:Descrit CO4:Explain energy savin	energy efficient lightning controls - standards and labelling p ENERGY MANAGEMENT IN BUILDINGS servation building code (ECBC) - Guidelines on heating system, water pumping system, Uninterruptible power supp energy efficiency measures in buildings - Energy performance gs measures of DG sets ENERGY AUDIT it definition - Need for energy audit - Types of energy audit g - Bureau of energy efficiency regulation 2008 - energy nergy management information system (EMIS) Total comes: Upon successful completion of the course, students v n the concept of electricity billing, power factor improvement ment be the energy performance of Electrical Motors be the energy performance of Lighting System n the Energy Conservation building code, Energy Performan	g ve ply, e ce as dit ar y me Perio will b at and ce as	ams ntilat escala sessi nd ap onito ods e abl	tion, ators ment oproa ring 4 e to dema	Air and and ch - and 5

Text Books:

- 1. Barney L. Capehart, Wayne C. Turner, and William J. Kennedy, Guide to Energy Management, Fifth Edition, The Fairmont Press, Inc., 2006
- 2. Book I General aspect of energy management and energy audit, Second Edition 2005, By Bureau of Energy Efficiency, Ministry of Power, India.
- 3. Book III Energy efficiency in electrical utilities, Second Edition 2005, By Bureau of Energy Efficiency, Ministry of Power, India.

References:

1. Albert Thumann, "Handbook of Energy Audit", Fairmont Press, 2008.

2.Sonal Desai, "Handbook Of Energy Audit", Mc Graw Hill India, 2015.

3. Wayne C. Turner, "Energy management handbook", Fairmont Press; Marcel Dekker, 2004.

COs						POs								
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
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2	3	3		2	1									
3	3	3		2	1									
4	3	2		2		2	2							
5	3	2	2		2		3		2	2		1		

Course	Course Title	L	Т	Р	С								
Code													
UEE2824	MICROCONTROLLER BASED SYSTEM	R BASED SYSTEM 3 0											
	DESIGN												
Objectives:													
• To g	ain knowledge about PIC architecture and its peripheral inter	facin	g tec	hniq	ues								
• To u	inderstand the significant features of ARM processor, its an	chite	cture	es and	d its								
orga	nization												
Unit I	INTRODUCTION TO PIC MICROCONTROLLER			ç)								
Introduction	to PIC Microcontroller-PIC 16C6x and PIC16C7x Archi	tectu	re-IC	C16cz	XX								
Pipelining -	Program Memory considerations - Register File Structure	- Ins	truct	ion S	Set -								
Addressing	modes – Simple Operations												
Unit II	INTERRUPTS AND TIMER			ç)								
PIC micro	controller Interrupts- External Interrupts-Interrupt Program	nmin	g–Lo	oop t	time								
subroutine 7	Fimers -Timer Programming- Front panel I/O-Soft Keys- S	tate	macł	nines	and								
key switche	s– Display of Constant and Variability strings.												
Unit III	PERIPHERALS AND INTERFACING			Ģ)								

I2C Bus for	r Peripherals Chip Access- Bus operation-Bus subroutines- Serial EEI	PROM—
Analog to I	Digital Converter–UART-Baud rate selection–Data handling circuit–Initi	ialization
- LCD and	keyboard Interfacing -ADC, DAC, and Sensor Interfacing.	
Unit IV	INTRODUCTION TO ARM PROCESSOR	9
Architectur	e –ARM programmer's model –ARM Development tools- Memory Hid	erarchy –
ARM Asse	embly Language Programming-Simple Examples-Architectural Sur	port for
Operating s	ystems	
Unit V	ARM ORGANIZATION	9
3- Stage Pip	beline ARM Organization-5Stage Pipeline ARM Organization-ARM In	struction
Execution-	ARM Implementation- ARM Instruction Set- ARM coprocessor in	nterface-
	ARM Implementation– ARM Instruction Set– ARM coprocessor in al support for High Level Languages – Embedded ARM Applications.	nterface-
		nterface– 45
	al support for High Level Languages – Embedded ARM Applications.	
Architectur	al support for High Level Languages – Embedded ARM Applications.	45

CO2: Program on PIC to activate interrupt and timer modules.

CO3: Illustrate the interfacing of peripheral devices with PIC for data communication

CO4: Explain the significant features and architectural support of ARM processor

CO5: Elaborate on use of the organization of ARM towards operating systems and embedded applications

Text Books:

1.Peatman, J.B., "Design with PIC Micro Controllers" PearsonEducation, 3rd Edition, 2004.

2.Furber,S., "ARM System on Chip Architecture" Addison Wesley trade Computer Publication,2000.

References:

1.Mazidi, M.A., "PIC Microcontroller" Rollin Mckinlay, Danny causey ,Prentice Hall of India, 2007

COs	POs												PSOs	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	2												2	1
2	1		3	3	2								2	
3	1		3	3	2								2	
4	2				3							2	1	1
5	1		2		3							2	1	2

Course	Course Title	L	Т	Р	С
Code					
UEE2825	POWER QUALITY	3	0	0	3
Objectives:	- <u> </u>				
To impart kn	owledge about the following topics:				
• Cause	es & Mitigation techniques of various PQ events.				
• Vario	us Active & Passive power filters.				
Unit I	CHARACTERISATION OF POWER QUALITY			ç)
Introduction	- Characterization of Electric Power Quality: Transients, sl	nort	dura	ation	and
long duration	n voltage variations, Voltage imbalance, waveform dis	stort	ion,	Vol	tage
fluctuations,	Power frequency variation, Power acceptability curves	– p	owe	r qua	lity
problems: po	oor load power factor, Non linear and unbalanced loads, DC	C of	fset	in lo	ads,
Notching in 1	oad voltage, Disturbance in supply voltage - Power quality st	tand	ards	•	
Unit II	ANALYSIS OF SINGLE PHASE AND THREE PHASE			ç)
	SYSTEM				
Single phase	sinusoidal, non sinusoidal source supplying linear and nonlin	ear	load	s - T	nree
phase Balan	ce system – Three phase unbalanced system – Three phase	e un	bala	nced	and
distorted sou	rce supplying non linear loads – Concept of PF – Three phase t	hree	e wir	e - T	nree
phase four w	ire system.				
Unit III	CONVENTIONAL LOAD COMPENSATION METHOD	S		Ģ)
Principle of]	Load compensation and Voltage regulation – Classical load b	alan	cing	prob	lem
: Open loop b	alancing – Closed loop balancing, Current balancing – Harmo	nic	redu	ction	and
voltage sag i	reduction - Analysis of unbalance - instantaneous real and r	react	ive	powe	rs –
Extraction of	fundamental sequence component.				
Unit IV	LOAD COMPENSATION USING DSTATCOM			ç)
Compensatir	g single phase loads - Ideal three phase shunt compens	sato	r str	uctur	e –
Generating r	eference currents using instantaneous PQ theory - Instantane	eous	s syn	nmeti	rical
components	theory - Generating reference currents when the source	is ı	ınba	lance	d –
Realization a	nd control of DSTATCOM - DSTATCOM in Voltage control	ol m	ode.		
	SERIES COMPENSATION OF POWER DISTRIBUTIO	N		ç)
Unit V					
	SYSTEM				
	SYSTEM ported Dynamic Voltage Restorer – DC Capacitor support	ed 1	DVR	L – D	VR
Rectifier sup					
Rectifier sup Structure – v	ported Dynamic Voltage Restorer – DC Capacitor support				
Rectifier sup Structure – v	ported Dynamic Voltage Restorer – DC Capacitor support oltage Restoration – Series Active Filter – Unified Power Qua	ality	Cor		ner:
Rectifier sup Structure – v	ported Dynamic Voltage Restorer – DC Capacitor support oltage Restoration – Series Active Filter – Unified Power Qua ns and characteristics.	ality	Cor	nditio	ner:
Rectifier sup Structure – v Configuratio	ported Dynamic Voltage Restorer – DC Capacitor support oltage Restoration – Series Active Filter – Unified Power Qua ns and characteristics. Total P comes: Upon successful completion of the course, students wa	ality Perio ill b	ods e abl	ditio 4 le to	ner: 5
Rectifier sup Structure – v Configuratio Course Out CO1: Sum	ported Dynamic Voltage Restorer – DC Capacitor support oltage Restoration – Series Active Filter – Unified Power Qua ns and characteristics. Total P comes: Upon successful completion of the course, students was narize the various power quality issues and power quality star	ality Perio ill b	ods e abl	ditio 4 le to	ner: 5
Rectifier sup Structure – v Configuratio	ported Dynamic Voltage Restorer – DC Capacitor support oltage Restoration – Series Active Filter – Unified Power Qua ns and characteristics. Total P comes: Upon successful completion of the course, students wa	ality Perio ill b	ods e abl	ditio 4 le to	ner: 5
Rectifier sup Structure – v Configuratio Course Out CO1: Sum with electric CO2: Analy	ported Dynamic Voltage Restorer – DC Capacitor support oltage Restoration – Series Active Filter – Unified Power Qua ns and characteristics. Total P comes: Upon successful completion of the course, students with narize the various power quality issues and power quality star power system yze single phase and three phase system supplying linear and p	ality Perio ill b ndar	ods e abl ds as	4 le to	ner: 5
Rectifier sup Structure – v Configuratio Configuratio CO1: Sum with electric CO2: Anal CO3: Descri	ported Dynamic Voltage Restorer – DC Capacitor support oltage Restoration – Series Active Filter – Unified Power Qua ns and characteristics. Total P comes: Upon successful completion of the course, students was narize the various power quality issues and power quality star power system vze single phase and three phase system supplying linear and the power the principle of conventional load compensation methods.	ality Perio ill b ndar	ods e abl ds as	4 le to	ner: 5
Rectifier sup Structure – v Configuratio Configuratio CO1: Sum with electric CO2: Anal CO3: Descri	ported Dynamic Voltage Restorer – DC Capacitor support oltage Restoration – Series Active Filter – Unified Power Qua ns and characteristics. Total P comes: Upon successful completion of the course, students with narize the various power quality issues and power quality star power system yze single phase and three phase system supplying linear and p	ality Perio ill b ndar	ods e abl ds as	4 le to	ner: 5

Text Books:

1.ArindamGhosh —Power Quality Enhancement Using Custom Power Devices^{II}, Kluwer Academic Publishers, 2002

2.G.T.Heydt, —Electric Power Quality, Stars in a Circle Publications, 1994(2nd edition) **References:**

1. Barry W.Kennedy: Power Quality Primer, McGraw-Hill, New York, 2000

2.Sankaran.C: Power Quality, CRC Press, Washington D.C., 2002

- 3. Roger C. Dugan, Mark F. McGranaghan and H.WayneBeaty: Electrical Power System Quality, McGraw-Hill, New York, 2nd Edition, 2002
- 4. Math H.J.Bollen, "Understanding Power Quality Problems: Voltage Sags and Interruptions", IEEE Press, New York, 2000

5.Arrillaga.J, Watson.N.R and Chen.S, "Power System Quality Assessment", John Wiley & Sons Ltd., England, 2000

COs	POs											PSOs		
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4	3	2	3	3	2		2	1		1		1	2	1
5	3	2	3	3	2		2	1		1		1	2	1

HONORS DEGREE (Minimum 6 courses)

Specialization title: Artificial Intelligence and Machine Learning for Electrical Systems

Code	Course Title	L	Т	Р	С
Cour					
UEE2H21	PRINCIPLES OF ARTIFICIAL INTELLIGENCE	3	0	0	3
Objectives:					
The obje	ective of this course is to enable the students to				
	erstand the basic concepts of intelligent agents				
	elop general-purpose problem-solving agents, logical reasoni	ng a	igen	ts, an	nd
-	ts that reason under uncertainty				
	n about solving problems with various constraints.				
	ly A.I to various application problems.	·1	4		
-	ain learning problem related to a collection of input–output parautput for new inputs.	irs u	nat p	reatc	ts
Unit I	INTRODUCTION TO AI AND INTELLIGENT AGENT	S		9)
	to AI – Agents and Environments – Good behavior concep		rati		
	nvironments – structure of agents. goal-based agents, util				-
	ents Problem solving agents – search algorithms – uninformed	-		-	
Unit II	SEARCH TECHNIQUES	sear		g	
				-	
	arch strategies – heuristic functions. Local search and optimiz		-		
	in continuous space – search with non-deterministic actions – s			-	-
	environments – online search agents and unknown enviro				-
	uristic search: local search algorithms & optimization probler	ms:	H1II	clim	oing
	lated annealing search, local beam search				
Unit III	CONSTRAINT SATISFACTION PROBLEM (CSP) ANI)		9)
	GAME THEORY				
-	based agents - propositional logic - propositional the		-		g –
propositiona	based agents – propositional logic – propositional the al model checking – agents based on propositional logic. Fi	irst-0	orde	r log	g – ic –
propositional syntax and s	based agents – propositional logic – propositional the al model checking – agents based on propositional logic. Fi semantics – knowledge representation and engineering – inferen	irst-0 nces	orde in f	r log irst-o	g – ic – rder
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propositional syntax and s logic – forv search. Unit IV Knowledge- propositional syntax and s logic – forv search. Unit V Learning fro Ensemble le learning, Le	based agents – propositional logic – propositional theo al model checking – agents based on propositional logic. Fi semantics – knowledge representation and engineering – inferen- ward chaining – backward chaining – Algorithms for planning LOGICAL AGENTS based agents – propositional logic – propositional theo al model checking – agents based on propositional logic. Fi semantics – knowledge representation and engineering – inferen- ward chaining – backward chaining – Algorithms for planning LEARNING om observations: Forms of learning, Inductive learning, learning earning probabilistic models. Learning with hidden variable	irst-(nces ng a orem irst-(nces ng a ng d ng, I es R	orde in f s sta s sta n pr orde in f s sta ecis: Xnov	r log irst-o ate sp g roving r log irst-o ate sp g ion tr wledg orcen	g – rder pace g – rder pace pace
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Course Outcomes: Upon successful completion of the course, students will be able to

CO1: Explain autonomous agents that make effective decisions in fully informed, partially observable, and adversarial settings

CO2: Choose appropriate algorithms for solving given AI problems

CO3: Explain CSP and game theory approach in AI

CO4: Design and implement logical reasoning agents

CO5: Describe learning problem from a collection of input–output pairs, learn a function that predicts the output for new inputs.

Text Books:

1. S. Russell and P. Norvig, Artificial Intelligence: A Modern Approach, Prentice Hall, Third Edition, 2015.

2. Nils J. Nilsson, Artificial Intelligence: A New Synthesis (1 ed.), Morgan-Kaufmann, 1998.

References:

1. Elaine Rich, Kevin Knight, & Shivashankar B Nair, Artificial Intelligence, McGraw Hill, 3rd ed., 2017.

2. Introduction to Artificial Intelligence & Expert Systems, Patterson, Pearson, 1st ed. 2015

3. Logic & Prolog Programming, Saroj Kaushik, New Age International, Ist edition, 2002.

COs								PC)s				PSOs	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	3	1	2		1							2		
2	3	2	3	2	1							2	3	1
3		2	3	2									2	1
4	2		3	1	3							3		1
5	3	3	2	3	3							3	1	

Course	Course Title	L	Τ	Р	С
Code					
UEE2H22	FUNDAMENTALS OF MACHINE LEARNING	3	0	0	3
Objectives:					
The objectiv	e of this course is to enable the students to				
• Unde	rstand the fundamentals of machine learning.				
• Expo	se to linear models.				
• Fami	liarize with basic machine learning algorithms with classifica	tion.			
• Unde	rstand machine learning algorithms with clustering.				
• Learn	and apply reinforcement learning techniques.				
Unit I	MODELS OF MACHINE LEARNING			Ģ)
Components	of learning - learning models - geometric models - proba	abilis	stic 1	mode	els –

logical mo	dels – grouping and grading – learning versus design – types of l	earning _
	– unsupervised – reinforcement – theory of learning – feasibility of l	
-		-
	bise – training versus testing – theory of generalization – generalization	n bound –
	ion generalization trade off – bias and variance – learning curve.	
	LINEAR MODELS	9
	ification – univariate linear regression - bivariate regression – multivar	
regression	- regularized regression - Logistic regression. Naïve Baye's - Dis	criminant
Functions	-Probabilistic Generative Models -Probabilistic Discriminative M	Models –
Bayesian L	ogistic Regression	
Unit III	SUPERVISED LEARNING	9
Perceptron	: – multilayer neural networks – back propagation - learning neural	networks
structures -	- Support vector machines: – soft margin SVM – going beyond la	inearity –
	on and over fitting – regularization – validation. Decision trees: Tra	-
-	a Decision Tree - Making Predictions - Estimating Class Probabilit	-
	ning Algorithm - Computational Complexity - Gini Impurity or Entrop	
	UNSUPERVISED LEARNING	9
	Introduction, Mixture densities – K-means clustering – clustering	-
	silhouttes – hierarchical clustering – k-d trees. Dimensionality Red	
	criminant Analysis – Principal Component Analysis – Factor A	
	t Component Analysis.	
<u> </u>	REINFORCED LEARNING	9
Passive reir	forcement learning – direct utility estimation – adaptive dynamic prog	gramming
	difference learning – active reinforcement learning – exploration – le	
-	ty function – Generalization in reinforcement learning – policy	-
applications	s in game playing – applications in robot control.	
	Total Periods	45
Course Ou	tcomes: Upon successful completion of the course, students will be ab	le to
CO1: Unde	rstand fundamentals of machine learning.	
CO2: Apply	y the linear models for tuning parameters.	
CO 3: Unde	erstand and explore the machine learning algorithms with classification	l.
	y machine learning algorithms with clustering and feature extraction.	
	y reinforcement learning techniques for various applications.	
Text Books	:	
	mAlpaydin, "Introduction to Machine Learning", MIT Press, Fourth I	Edition,
2020.		
References		
	Mitchell, "Machine Learning", McGraw Hill, 3rd Edition, 1997.	
2. Charu 2014	I C. Aggarwal, "Data Classification Algorithms and Applications", Cl	RC Press,
	yar Mohri, Afshin Rostamizadeh, Ameet Talwalkar, "Foundations of	Machine
	ning", MIT Press, 2012.	
	ood fellow, Yoshua Bengio, Aaron Courville, "Deep Learning", MIT Pr	ress, 2016
	stain Raschka, "Python Machine Learning", Packt publishing (open so	
	stopher M. Bishop, "Pattern Recognition and Machine Learning", Sprin	

COs								PO	S				PSOs	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	3		2		3							3	1	1
2	3	3	2	1	2							2	3	2
3	3		2	1	2			2				3	1	2
4	3		2	1	2								2	2
5	3		2	3	2								1	1

Course	Course Title	L	Т	Р	С
Code					
UEE2H23	FUNDAMENTALS OF INFORMATION THEORY	3	0	0	3
Objectives:					
The objective	e of this course is to enable the students to				
• To lea	rn fundamentals of random variables				
• To lea	rn information units, entropy and entropy rate				
	lerstand concepts of data compression				
• Be fan techni	niliar with the methods for the generation of these codes and iques.	l the	ir de	codir	ng
• To app	bly information theory in the fields of coding, image processir	ng, a	nd m	achir	ne
learning					
Unit I	REVIEW OF PROBABILITY THEORY			Ģ)
	ndamentals, Review of Probability theory: Probability measu				
•	Random variable, Probability Distribution, discrete and cont	inuc	ous, o	densi	ty
	nistogram - Parzen window using Gaussian Kernel.				
	ENTROPY, RELATIVE ENTROPY AND MUTUAL			ç)
]	INFORMATION				
	nount of information, information units Entropy: marginal, c				
	entropies, Chain rules for entropy, Relative entropy and Mutu	ial Ii	nforr	natio	n,
	ns, Entropy Rate, Functions of Markove's Chain				
Unit III	INFORMATION THEORETIC DATA COMPRESSION	I		9)
-	Codes, Kraft Inequality, Optimal codes, Bounds on the optim			0	
-	lity for uniquely decodable codes, Huffman codes, Optmal				
	etetive optimality of the shannon's code, Generation of discr	rete	distr	ibutio	on
from fair coin					
	CHANNEL CAPACITY			-)
	Channel Capacity: Noisless Binary Channel, Noisy C				
•	hannel, Binary erasure channel, Symmetric Channel, Proper				
	annel coding theorem, Fano's Inequality, Hamming codes,	Sou	rce c	hann	el
separation the					
	INFORMATION THEORETIC CLASSIFICATION			-)
	tem, Cost function - Mean square error – Least mean square e				18
of LMS, Entr	opy as cost function - Minimum error entropy, Decision tree	algo	orith	m.	

Total Periods	45

Course Outcomes: Upon successful completion of the course, students will be able to

CO1: Apply mathematical tools for Information theory

CO2:Explain and estimate information theory metrics, entropy, and cross entropy.

CO3:Design an application with error control.

CO4: Analyze the channel capacity and optimize the probability of error

CO5:Describe information theoretic Errors

Text Books:

1. Thomas Cover, Joy Thomas, Elements of Information Theory, Wiley Inderscience, 2nd Edition, 2006.

References:

- 1. David J C MacKay Information theory, Inference and Learning Algorithms, Cambridge University Press, 2005.
- 2. Christopher M Bishop, Pattern Recognition and Machine Learning, Springer, 2006.
- 3. Monica Borda, Fundamentals in Information Theory and Coding, Springer, 2011.
- 4. R C Gonzalez, and R E Woods, Digital Image Processing, Pearson, 2018.
- 5. Mark Nelson, "Data Compression Book", BPB Publication 1992

COs					POs								PSOs	
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1	2	3	1	2	2							2		
2		2	2	2	2									
3			2		3							1	2	1
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5	2	1	3	1	1									

Course	Course Title	L	Τ	Р	С
Code					
UEE2H24	BIG DATA ANALYTICS	3	0	0	3
Objectives:					
The objective	of this course is to enable the students to				
• To une	derstand about big data.				
• To lea	rn and use NoSQL big data management.				
• To lea	rn map-reduce analytics using Hadoop and related tools.				
• To une	derstand the usage of Hadoop related tools for Big Data Ana	lytic	S		
Unit I I	NTRODUCTION TO BIG DATA			9)
Classification	of digital data, Structured data, semi structured data, u	Instr	uctu	red d	lata,
characteristics	s and evolution of Big data, Challenges with Big data, B	ig d	ata:	Volu	me,
	Variety, Traditional Business Interest Vs Big Data, D	Data	Wa	re ho	ouse
Environment	and Hadoop Environment				
Unit II F	BIG DATA ANALYTICS			9)

Introduction	n to Big Data Analytics: In memory analysis, In database processing, Sy	mmetric
	essor System, Massively parallel processing, difference between par	
	system open source analytic tools	aner anu
Unit III	NOSQL DATA MANAGEMENT	9
	n to NoSQL – aggregate data models – aggregates – key-value and doc	-
	s - relationships - graph databases - schemeless databases - materialized	
	on models – sharding – master-slave replication – peer-peer replica	
	nd replication – consistency – relaxing consistency – version stamps -	
-	rtitioning and combining – composing map-reduce calculations	mup
Unit IV	BASICS OF HADOOP	9
	t – analysing data with Hadoop – scaling out – Hadoop streaming – Hado	
	Hadoop distributed file system (HDFS) – HDFS concepts – Java interfa	
	loop I/O – data integrity – compression – serialization – Avro – file-ba	
structures.	sop 1 o unu mogney compression semunization me o	abea aata
Unit V	HADOOP RELATED TOOLS	9
	data model and implementations – Hbase clients – Hbase exa	
	andra – cassandra data model – cassandra examples – cassandra clients -	
	Pig – Grunt – pig data model – Pig Latin – developing and testing l	
	ve – data types and file formats – HiveQL data definition – Hive	
	on – HiveQL queries.	Z
<u> </u>	Total Periods	45
Course Ou	tcomes: Upon successful completion of the course, students will be abl	e to
CO1.	Describe big data and use cases from selected business domains.	
CO2.	Explain NoSQL big data management.	
CO3.	Install, configure, and run Hadoop and HDFS.	
CO4.	Perform map-reduce analytics using Hadoop.	
CO5.	Use Hadoop related tools such as HBase, Cassandra, Pig, and Hive	for big
	data analytics.	U
Text Books	s:	
1. Tom W	White, "Hadoop: The Definitive Guide", Third Edition, O'Reilley, 2012.	
2. P. J. Sa	adalage and M. Fowler, "NoSQL Distilled: A Brief Guide to the Emergi	ng
World	of Polyglot Persistence", Addison-Wesley Professional, 2012.	U
	Acharya, Subhashini Chellappan, "Big Data and Analytics", Wiley Pul	olication.
2015.	Tienarja, Suomashini Chenappan, Dig Data and Emargines , (Filey Fat	, and a second
References		
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Emergir	Minelli, Michelle Chambers, and Ambiga Dhiraj, "Big Data, Big Ang Business Intelligence and Analytic Trends for Today's Businesses	-
2013.		
2. Eric Sam	nmer, "Hadoop Operations", O'Reilley, 2012.	D1 D
2 E C '	olo, D. Wampler, and J. Rutherglen, "Programming Hive", O'Reilley, 20	J12.
4. Lars Geo	orge, "HBase: The Definitive Guide", O'Reilley, 2011.	
4. Lars Geo5. Eben Her	orge, "HBase: The Definitive Guide", O'Reilley, 2011. witt, "Cassandra: The Definitive Guide", O'Reilley, 2010. res, "Programming Pig", O'Reilley, 2011.	

COs								PO	S			PSOs		
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3					3							2		
4		3	2	1	3							1		
5		2	2	3	3							2	2	2

Course	Course Title	L	Т	Р	С					
Code										
UEE2H25	APPLICATION OF MACHINE LEARNING AND									
	DEEP LEARNING TO POWER SYSTEM	0	3							
PROBLEMS										
Objectives:										
The objectiv	e of this course is to enable the students to									
	er System Challenges and Issues									
• Mac	hine Learning Methods in Energy Engineering									
	view of the Application of Machine Learning for Controllin	g an	d Pl	annir	ıg					
	er Systems									
• App	lication of Machine Learning for Clustering in Power Systems									
•	Application of Machine Learning for Forecasting Power S	yster	n							
Unit I	INTRODUCTION			Ç)					
	Future Challenges - Big data in future Power System Netwo									
	- Energy Storage Integrity, Decentralization and Smart Contra	ct -R	Relia	bility	and					
	blems -ML Applications and its Challenges.									
Unit II	MACHINE LEARNING AND POWER SYSTEM PLAN	NIN	G	9)					
Structure of	Power System Network- GEP, NEP and SEP, Classification	n of	diffe	erent	ML					
	Power System, Support Vector Machine, Machine Le		<u> </u>							
	Formulation for a power system, Group method data handl	ing,	SVF	R, GR	NN					
-	tree, Convolutional Neural Networks)					
Unit III MACHINE LEARNING APPLICATION TO CONTROL PROBLEMS OF POWER SYSTEM										
ML Methods Categorization, Subsystems of a Power System and their control, Evaluation										
of operating modes of power system using ML methods, Application of ML in evaluating										
-	Security and stability of power system, Voltage and transient stability, Power Quality									
	disturbances assessment.									
Unit IV	CLUSTERING IN POWER SYSTEM USING MACHIN	E		ç)					
	LEARNING									

Steps of clustering a dataset of time-series variations, Power system clustering for dynamic equivalencing, Typical test system with 16-machine, 68-bus, Feature extraction methods, Power System Clustering Using Supervised Learning Methods, Artificial Neural Networks, Decision Trees, Power System Clustering Using Unsupervised Learning Methods-Means Clustering Algorithm, Fuzzy C-Means Clustering Algorithm, Subtractive Clustering Algorithm, Support Vector Clustering Algorithm

U	0 / 11	6 6
Unit V	MACHINE LEARN	NING APPLICATION TO LOAD
	FORECASTING	

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Electrical load forecasting approaches, Overview on load forecasting categories, Challenges in Power Systems Short-, Medium-, and Long-Term Load Forecasting, Performance Assessment of Algorithms

Total Periods 45

Course Outcomes: Upon successful completion of the course, students will be able to

CO1. Explain Machine Learning Methods for Energy Engineering

CO2. Choose appropriate algorithms for control and planning of Power System

CO3. Apply Machine Learning algorithms for power system planning

CO4. Apply principles of Clustering in Machine Learning for Power Systems

CO5. Apply Machine Learning techniques for load forecasting in Power System

Text Books:

1. Morteza Nazari-Heris, "Application of Machine Learning and Deep Learning Methods to Power System Problems", Springer, 2022.

References:

1. Denis N. Sidorov, "Machine Learning for Energy Systems", MDPI Books, 2020

2. Aanand Kumbhas." A comprehensive review: Machine learning and its application in integrated power system", Elsevier Energy Reports, 2021.

COs								PO	s				PSOs		
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2	3	2	3	2	1							2	3	1	
3	1	2	3	2	1								2	1	
4	2	2	3	1	3							3		1	
5	3	3	2	3	3							3	3	3	

Course	Course Title	L	Т	P	C				
Code									
UEE2H26	ARTIFICIAL INTELLIGENCE APPLICATION IN POWER SYSTEMS	3	0	0	3				
Objectives:									
The objective of this course is to enable the students to									

• The	emerging area of AI techniques.	
	zy logic systems, artificial neural networks and optimization techniques	!
• 1 uZZ	by logic systems, artificial neural networks and optimization teeninques	•
Unit I	AI TECHNIQUES IN POWER SYSTEMS	9
History and	Applications Knowledge based systems, Structure and definitions, Kr	owledge
acquisition,	Inference Engine, Basics of Fuzzy Systems, Artificial Neural Netw	orks and
	y Computing	
Unit II	ARTIFICIAL NEURAL NETWORK	9
	lifference between human and machine intelligence, biological neural	
	uron model, Concept of Perceptron, ADALINE, Feedbackin Neural	
	work Architectures: Neural Learning, Application of Neural Network	in Power
-	c security assessment problem	0
Unit III	FUZZY LOGIC	9
	n, Foundation of Fuzzy Systems, Representing Fuzzy Elements, Basic T	
	Properties of Fuzzy Sets, Fuzzification, Arithmetic Operations of the alpha aut method. The automation method, Linguistic Descriptions	
	he alpha cut method, The extension method, Linguistic Descriptions Forms, Fuzzy Linguistic Descriptions, Fuzzy Relation Inferences	
•	and Algorithms, Defuzzification Methods, Centre of Area Defuzz	•
-	ums Defuzzification, Fuzzy techniques for voltage control.	incution
Unit IV	Genetic Algorithms and Evolutionary Programming	9
	n, Genetic Algorithms, Procedure of Genetic Algorithms, C	Genetic
	ions, Initilization and Selection, Genetic Operators, Mutation, The W	
-	Algorithms, Evolutionary Programming.	0
Unit V	Application of AI in Power Systems	9
	curity assessment, Schedule Maintenance of Electrical Power Transn sing Genetic Algorithm, Intelligent Systems for Demand Forecasting	nission
	Total Periods	45
Course Out	tcomes: Upon successful completion of the course, students will be abl	e to
	late the concept of AI techniques and their applications.	0 10
	n neural network controller for security assessment of power system.	
U	ibe Fuzzy Logic application for real world problems.	
	ibe the concepts of Evolutionary Algorithm.	
	ibe the application of ANN and Expert system for power system proble	ems.
Text Books		
1. Siva	nandam S.N., Deepa S.N., "Principles of Soft Computing", Wiley In	ndia Pvt
Ltd., 2nd Ec		
2. Jace	k.M.Zurada, "Introduction to Artificial Neural Systems", Jaico Pr	ublishing
House, New	Edition, 2012.	
References	•	
1. KOS 1994	SKO B., "Neural Networks and Fuzzy Systems", Prentice-Hall of India 14.	Pvt. Ltd.
2. Zim	merman H.J., "Fuzzy set theory-and its Applications"-Kluwer A lishers, 3rd Edition, 1996.	cademic
1 401	nsilers, 514 Edition, 1770.	

- 3. Timothy J. Ross, "Fuzzy Logic with Engineering Applications" Wiley India, 3rd Edition, 2012.
- 4. KLIR G.J., FOLGER T.A., "Fuzzy sets, uncertainty and Information", Prentice-Hall of India Pvt. Ltd., 1993.
- 5. Goldberg D.E., "Genetic algorithms in Search, Optimization and Machine learning", Addison Wesley, 1989.

Cos								PO	S				PSOs		
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3	3	1	2	1	2							2	1	2	
4	3		2	1	2								1	1	
5	3		2	3	2								1	1	

Course	Course Title	L	Т	Р	C
Code					
UEE2H27	INTRODUCTION TO AUTONOMOUS MOBILE	3	0	0	2
	ROBOTS	3	U	U	3

Objectives:

The objective of this course is to enable the students to

- Compare different robotic systems that navigate independently in complex environments.
- Develop knowledge on basic sensor systems related to state measurements, navigation and localization.
- Study computer vision perception and learn sensors for environment perception.
- Understand mobile robot locomotion, kinematics, probabilistic map based localization.

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Unit I FUNDAMENTALS OF ROBOT TECHNOLOGY

 Robot Anatomy, Robot drive systems, Robotic sensors, AI and Robotics – key issues for robot locomotion – legged mobile robots – wheeled mobile robots – aerial mobile robots.

 Practice Exercise

 Unit II
 MOBILE ROBOT MOTION ANALYSIS AND CONTROL
 9

Unit IIMOBILE ROBOT MOTION ANALYSIS AND CONTROL9Transformations and Robot Kinematics Kinematic models and constraints – mobile robotmaneuverability – mobile robot workspace – advanced kinematics – motion control-

Kinematic control-Sensors for mobile robots – computer vision for robots – image
processing for robotics – place recognition – range data. Practice Exercise9Unit IIILOCALIZATION OF MOBILE ROBOTS9

Introduction to localization – noise and aliasing – localization-based navigation – belief representation – map representation – probabilistic map-based localization – autonomous map building. Practice Exercise

Planning and navigation - planning and reacting - path planning - obstacle avoidance navigation architectures. Practice Exercise

ROBOT CELL DESIGN AND ECONOMIC ANALYSIS FOR Unit V ROBOTICS

Robot cell layouts, Multiple Robot and Machine Interference, Work cell controls and Inter locks, Economic Analysis: Basic data required, Methods of economic analysis.

Total Periods 45

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Course Outcomes: Upon successful completion of the course, students will be able to

CO1. Understand and analysis algorithmic approaches, compare the mathematical models on various mobile robots.

CO2. Address several key challenges in localization, and mapping, and find research issues in visual object detection.

CO3. Develop knowledge on motion planning and navigation schemes for mobile robots

- Apply and implement path planning and kinematics for mobile robots. CO4.
- CO5. Plan and design

Text Books:

1. R. Siegwart, I. R. Nourbaksh, and D. Scarramuzza, "Introduction to Autonomous Mobile Robots", Second Edition, MIT Press, 2011.

References:

1. Stuart Russel and Peter Norvig, "Artificial Intelligence: A Modern Approach", Fourth Edition, Pearson Education, 2020.

COs								PO	S				PSOs		
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3	1	1	2	1	3							1	1	1	
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5	3	1	3	1	1										

Course	Course Title	L	Τ	Р	C				
Code									
UEE2H28	UEE2H28 FUNDAMENTALS OF DEEP LEARNING 3								
Objectives:									
The objectiv	e of this course is to enable the students to								
• Expl	in the mathematical and computational demands of building r	leura	l net	work	s.				
• Stud	the concepts of deep learning.								
• Introduce dimensionality reduction techniques.									
• Apply deep learning techniques for real time applications.									
Unit I	MATHEMATICAL AND COMPUTATIONAL ASPECT	ſS		Ģ)				

Unit I	MATHEN	IATICAL AND	COMPUTATIONAL ASPEC	TS

Machine Le	arning Basics	
Unith	DEEP NETWORKS	9
	forward networks: Gradient based Learning, Hidden Units, Back propa	-
	ntiation algorithms, Regularization of Deep Learning: Parameter	
	ataset augmentation, Multitask learning, Advarsarial training, optimizat	
training dee		
Unit III	CONVOLUTIONAL NETWORKS	9
Convolution	n, Pooling, variants of the basic convolution function, Structured output	s, Data
	olution algorithm, Random or unsupervised features, neuroscientific ba	
convolution	al networks.	
Unit IV	SEQUENCE MODELING: RECURRENT AND RECURSIVE	9
	NETS	
Recurrent 1	Neural Networks (RNN), Bidirectional RNN, Long Short-Term M	emory
(LSTM), G	RU; Case Study - Language Modelling, Image Captioning using RNNs	•
Unit V	DEEP REINFORCEMENT LEARNING	9
	Total Periods	45
Course Ou	tcomes: Upon successful completion of the course, students will be abl	
CO1.	comest epon successful completion of the course, students will be use	e to
	Explain mathematical and computational aspects of neural network	e to
CO2.	Explain mathematical and computational aspects of neural network Understand the deep networks along with its limitations.	e to
CO2. CO3.	Understand the deep networks along with its limitations.	e to
	Understand the deep networks along with its limitations. Analyze convolutional networks	e to
CO3.	Understand the deep networks along with its limitations. Analyze convolutional networks Apply sequence modeling in practice	e to
CO3. CO4. CO5.	Understand the deep networks along with its limitations. Analyze convolutional networks Apply sequence modeling in practice Apply Deep Learning algorithms in practice	
CO3. CO4. CO5.	Understand the deep networks along with its limitations. Analyze convolutional networks Apply sequence modeling in practice Apply Deep Learning algorithms in practice :	
CO3. CO4. CO5.	Understand the deep networks along with its limitations. Analyze convolutional networks Apply sequence modeling in practice Apply Deep Learning algorithms in practice	
CO3. CO4. CO5. Text Books	 Understand the deep networks along with its limitations. Analyze convolutional networks Apply sequence modeling in practice Apply Deep Learning algorithms in practice Ian Goodfellow, YoshuaBengio, Aaron Courville, "Deep Learning' Press, 2016. 	
CO3. CO4. CO5. Text Books References	 Understand the deep networks along with its limitations. Analyze convolutional networks Apply sequence modeling in practice Apply Deep Learning algorithms in practice Ian Goodfellow, YoshuaBengio, Aaron Courville, "Deep Learning' Press, 2016. 	', MIT
CO3. CO4. CO5. Text Books References	 Understand the deep networks along with its limitations. Analyze convolutional networks Apply sequence modeling in practice Apply Deep Learning algorithms in practice Ian Goodfellow, YoshuaBengio, Aaron Courville, "Deep Learning" Press, 2016. 	', MIT
CO3. CO4. CO5. Text Books	Understand the deep networks along with its limitations. Analyze convolutional networks Apply sequence modeling in practice Apply Deep Learning algorithms in practice In Goodfellow, YoshuaBengio, Aaron Courville, "Deep Learning' Press, 2016. I. Josh Patterson, Adam Gibson, "Deep Learning: A Practiti	', MIT
CO3. CO4. CO5. Text Books References	 Understand the deep networks along with its limitations. Analyze convolutional networks Apply sequence modeling in practice Apply Deep Learning algorithms in practice Ian Goodfellow, YoshuaBengio, Aaron Courville, "Deep Learning' Press, 2016. Josh Patterson, Adam Gibson, "Deep Learning: A Practitic Approach", O'Reilly Media, 2017. Tom Mitchell, "Machine Learning", McGraw Hill, 3rd Edition, 1997 Francois Chollet, "Deep Learning with Python", Manning, 2018. 	', MIT
CO3. CO4. CO5. Text Books References	 Understand the deep networks along with its limitations. Analyze convolutional networks Apply sequence modeling in practice Apply Deep Learning algorithms in practice Ian Goodfellow, YoshuaBengio, Aaron Courville, "Deep Learning' Press, 2016. Josh Patterson, Adam Gibson, "Deep Learning: A Practiti Approach", O'Reilly Media, 2017. Tom Mitchell, "Machine Learning", McGraw Hill, 3rd Edition,1997 Francois Chollet, "Deep Learning with Python", Manning, 2018. Charu C. Aggarwal, Neural Networks and Deep Learning: A Tex 	', MIT
CO3. CO4. CO5. Text Books References	 Understand the deep networks along with its limitations. Analyze convolutional networks Apply sequence modeling in practice Apply Deep Learning algorithms in practice Ian Goodfellow, YoshuaBengio, Aaron Courville, "Deep Learning' Press, 2016. Iosh Patterson, Adam Gibson, "Deep Learning: A Practitic Approach", O'Reilly Media, 2017. Tom Mitchell, "Machine Learning", McGraw Hill, 3rd Edition, 1997 Francois Chollet, "Deep Learning with Python", Manning, 2018. Charu C. Aggarwal, Neural Networks and Deep Learning: A Tex Springer, 2018. 	', MIT ioner's 7. tbook,
CO3. CO4. CO5. Text Books References	 Understand the deep networks along with its limitations. Analyze convolutional networks Apply sequence modeling in practice Apply Deep Learning algorithms in practice Ian Goodfellow, YoshuaBengio, Aaron Courville, "Deep Learning' Press, 2016. Josh Patterson, Adam Gibson, "Deep Learning: A Practiti Approach", O'Reilly Media, 2017. Tom Mitchell, "Machine Learning", McGraw Hill, 3rd Edition,1997 Francois Chollet, "Deep Learning with Python", Manning, 2018. Charu C. Aggarwal, Neural Networks and Deep Learning: A Tex 	', MIT ioner's 7. tbook,

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5	2	2	2	3	3							1	2	2

Course	Course Title	L	Τ	Р	C
Code					
UEE2H29	FOUNDATIONS OF HUMAN-COMPUTER INTERACTION	3	0	0	3
Objectives:					

The objective of this course is to enable the students to

- To learn the learn the terminologies of Human Computer Interaction.
- To be familiar with the design technologies for individuals and persons with disabilities.

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- To be aware of mobile HCI.
- To learn the guidelines for user interface.

Unit I **INTRODUCTION TO HCI**

The Human: I/O channels – Memory – Reasoning and problem solving; The computer: Devices - Memory - processing and networks; Interaction: Models - frameworks -Ergonomics – styles – elements – interactivity- design of interactive systems- Physical controls sensors and spatial devices

Unit II MODELS OF INTERACTION AND DESIGN PROCESS

Interactive Design basics – process – scenarios – navigation – screen design – Iteration and prototyping. HCI in software process -Elements of WIMP interface, software life cycle usability engineering – Prototyping in practice – design rationale; Design rules – principles, standards, guidelines, rules; Evaluation Techniques.

MODELS AND THEORIES Unit III

Cognitive models – Socio-Organizational issues and stake holder requirements Communication and collaboration models - Hypertext, Multimedia and WWW, User interface management system, Elements of windowing system.

Unit IV **MOBILE HCI**

Mobile Ecosystem: Platforms, Application frameworks - Types of Mobile Applications: Widgets, Applications, Games - Mobile Information Architecture, Mobile Design: Elements of Mobile Design, Tools, Mobile 2.0. 9

Unit V **DESIGNING WEB INTERFACES**

Designing Web Interfaces - Drag & Drop, Direct Selection, Contextual Tools, Overlays, Inlays and Virtual Pages, Process Flow. Designing user support system

Total Periods 45
Course Outcomes: Upon successful completion of the course, students will be able to
CO1. Design effective dialog for HCI.
CO2. Design effective HCI for individuals and persons with disabilities.
CO3. Assess the importance of user feedback.
CO4. Explain the HCI implications for designing multimedia/ ecommerce/ e-learning Web
sites.
CO5. Develop meaningful user interface.
Text Books:
1. Alan Dix, Janet Finlay, Gregory Abowd, Russell Beale, "Human Computer
Interaction", 3rd Edition, Pearson Education, 2004.
References:
1. Brian Fling, "Mobile Design and Development", First Edition ,O"Reilly Media
Inc., 2009.
2. Bill Scott and Theresa Neil, "Designing Web Interfaces", First Edition,
O"Reilly, 2009.
3. Ben Shneiderman, Designing for Effective Human/Computer Interaction,
Pearson, 2010.
4. Jenifer Tidwell, Designing Interfaces, Second Edition, O'Reilly publishers,
2011.
5. David Benyon, Designing Interactive Systems: A Comprehensive Guide to HCI,
UX and Interaction Design, Third Edition, Pearson, 2013.

COs	POs											PSOs		
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5		1	3	1	1									

Course	Course Title	L	Τ	Р	С
Code					
UEE2H30	FUNDAMENTALS OF IMAGE PROCESSING	3 0		0	2
	AND ANALYSIS	3	U	U	3
Objectives:					
The objectiv	e of this course is to enable the students to				
	Fo understand the image processing concepts and analysis				
	Fo understand the image processing techniques				
	Fo familiarize the image processing environment and the appl		ons,		
•	To appreciate the use of image processing in various application	ons.			
Unit I	IMAGE PROCESSING FUNDAMENTALS			9	9

muoducuo	n Elements of visual percention Stong in Image Processing Systems	Digital						
Imaging St	n – Elements of visual perception, Steps in Image Processing Systems - stem - Image Acquisition – Sampling and Quantization – Pixel Relatio							
	s-colourimagesandmodels-ImageOperations-	nsnips –						
	logical, statistical and spatial operations.							
Unit II	IMAGE TRANSFORMS AND MODELS	9						
	nsforms-Discrete and Fast Fourier Transform and Discrete Cosine Tr							
U	main - Gray level Transformations Histogram Processing Spatial Fi	,						
	and Sharpening. Frequency Domain: Filtering in Frequency D							
Smoothing	and Sharpening filters – Homomorphic Filtering., Noise models, Constr							
	ned restoration models.							
Unit III	IMAGE SEGMENTATION AND MORPHOLOGY	9						
	of Discontinuities – Edge Operators – Edge Linking and Boundary De							
	ng – Region Based Segmentation – Motion Segmentation, Image Mor	1 0.						
	Gray level morphology operations - Erosion, Dilation, Opening and							
1	Distance Transforms- Basic morphological Algorithms. Features – T							
	representations and Descriptions- Component Labeling – Regional de	escriptors						
	e Selection Techniques.	•						
Unit IV	IMAGE ANALYSIS AND CLASSIFICATION	9						
0 0	nentation- pixel based, edge based, region based segmentation. Active							
	Level sets for medical image segmentation, Image representation and	•						
	traction and representation, Statistical, Shape, Texture, feature and s	statistical						
image class		0						
Unit V	IMAGE REGISTRATION AND VISUALIZATION	9						
	visualization, Principal axis registration, Interactive principal axis registration	stration,						
Feature bas								
display me	ed registration, Elastic deformation based registration, Image visualizat hods, 3D display methods, virtual reality based interactive visualization	1.						
display me								
	hods, 3D display methods, virtual reality based interactive visualization Total Periods	n. 45						
Course Ou	thods, 3D display methods, virtual reality based interactive visualization Total Periods Itcomes: Upon successful completion of the course, students will be abl	n. 45 le to						
Course Ou CO1: Desig	thods, 3D display methods, virtual reality based interactive visualization Total Periods Itcomes: Upon successful completion of the course, students will be able and implement algorithms for image processing applications that income	n. 45 le to						
Course Ou CO1: Desig	thods, 3D display methods, virtual reality based interactive visualization Total Periods Itcomes: Upon successful completion of the course, students will be able on and implement algorithms for image processing applications that incomcepts of medical Image Processing	n. 45 le to orporates						
Course Ou CO1: Desig	thods, 3D display methods, virtual reality based interactive visualization Total Periods Itcomes: Upon successful completion of the course, students will be able and implement algorithms for image processing applications that income	n. 45 le to orporates						
Course Ou CO1: Desig different co CO2: Be	thods, 3D display methods, virtual reality based interactive visualization Total Periods Itcomes: Upon successful completion of the course, students will be able on and implement algorithms for image processing applications that incomcepts of medical Image Processing	n. 45 le to orporates						
Course Ou CO1: Desig different co CO2: Be I proo	thods, 3D display methods, virtual reality based interactive visualization Total Periods tecomes: Upon successful completion of the course, students will be able on and implement algorithms for image processing applications that incom- sencepts of medical Image Processing Familiar with the use of MATLAB and its equivalent open-source	n. 45 le to orporates						
Course Ou CO1: Desig different co CO2: Be l proo CO3: Critic	thods, 3D display methods, virtual reality based interactive visualization Total Periods tecomes: Upon successful completion of the course, students will be able on and implement algorithms for image processing applications that incomcepts of medical Image Processing Familiar with the use of MATLAB and its equivalent open-source ressing Images	n. 45 le to orporates						
Course Ou CO1: Desig different co CO2: Be l proo CO3: Critic	thods, 3D display methods, virtual reality based interactive visualization Total Periods Itcomes: Upon successful completion of the course, students will be able generation and implement algorithms for image processing applications that incomposition of medical Image Processing Familiar with the use of MATLAB and its equivalent open-source ressing Images cally analyze different approaches to image processing applications processing applications	n. 45 le to orporates						
Course Ou CO1: Desig different co CO2: Be proo CO3: Critic CO4: Expl Text Book	thods, 3D display methods, virtual reality based interactive visualization Total Periods Itcomes: Upon successful completion of the course, students will be able on and implement algorithms for image processing applications that incom- encepts of medical Image Processing Familiar with the use of MATLAB and its equivalent open-source ressing Images cally analyze different approaches to image processing applications ore the possibility of applying Image processing concepts in various S :	h. 45 le to orporates tools for						
Course Ou CO1: Desig different co CO2: Be I proo CO3: Critic CO4: Explo Text Book 1. Ala	thods, 3D display methods, virtual reality based interactive visualization Total Periods Itcomes: Upon successful completion of the course, students will be able generation and implement algorithms for image processing applications that incomposition of medical Image Processing Familiar with the use of MATLAB and its equivalent open-source ressing Images cally analyze different approaches to image processing applications processing applications	h. 45 le to orporates tools for						
Course Ou CO1: Desig different co CO2: Be I proo CO3: Critic CO4: Explo Text Book 1. Ala	thods, 3D display methods, virtual reality based interactive visualization Total Periods Total Periods and implement algorithms for image processing applications that inconcepts of medical Image Processing Familiar with the use of MATLAB and its equivalent open-source ressing Images cally analyze different approaches to image processing applications ore the possibility of applying Image processing concepts in various si sdair McAndrew,—Introduction to Digital Image Processing with M	h. 45 le to orporates tools for						
Course Ou CO1: Desig different co CO2: Be I proo CO3: Critic CO4: Expl Text Book 1. Ala Cer Reference	thods, 3D display methods, virtual reality based interactive visualization Total Periods Total Periods and implement algorithms for image processing applications that inconcepts of medical Image Processing Familiar with the use of MATLAB and its equivalent open-source ressing Images cally analyze different approaches to image processing applications ore the possibility of applying Image processing concepts in various si sdair McAndrew,—Introduction to Digital Image Processing with M	h. 45 le to orporates tools for						
Course Ou CO1: Desig different co CO2: Be J proc CO3: Critic CO4: Expl Text Book 1. Ala Cer References 1. Ani	thods, 3D display methods, virtual reality based interactive visualization Total Periods Itcomes: Upon successful completion of the course, students will be able on and implement algorithms for image processing applications that incom- based of medical Image Processing Familiar with the use of MATLAB and its equivalent open-source cessing Images cally analyze different approaches to image processing applications ore the possibility of applying Image processing concepts in various S: sdair McAndrew,—Introduction to Digital Image Processing with Magage Learning 2011,India	n. 45 le to orporates tools for fatlabl,						
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3		3	3									1			
4	3	2	2	1	3							1	2	2	

OPEN ELECTIVES OFFERED BY OTHER DEPARTMENTS

OPEN ELECTIVE I (SEMESTER VI)

Sl. NO	DEPARTMENT OFFERING	COURSE CODE	COURSE TITLE	L	Т	Р	С
1		UEC2041	Foundation Course on Digital Signal Processing	3	0	0	3
2		UEC2042	Introduction to Communication Systems	3	0	0	3
3	ECE	UEC2043	Development of Nano Sensors	3	0	0	3
4		UEC2044	Introduction to Internet of Things	3	0	0	3
5		UEC2045	Introduction to Sensors and Actuators	3	0	0	3
6		UCS2041	Introduction to Data Structures	2	0	2	3
7	CSE	UCS2042	Object Oriented Programming Techniques	2	0	2	3
8		UCS2043	Problem Solving and Programming in C	2	0	2	3
9		UIT2041	Introduction To AR and VR	2	0	2	3
10		UIT2042	Databases and Applications Development	2	0	2	3
11	IT	UIT2043	Introduction to Artificial Intelligence	2	0	2	3
12		UIT2044	Introduction to Data Structures and Algorithms	2	0	2	3
13		UIT2045	Introduction to Object-Oriented Programming and Patterns	2	0	2	3
14	-	UIT2046	Introduction to Data Science	2	0	2	3
15		UBM2041	Principles of Biomedical Instrumentation	3	0	0	3
16	BME	UBM2042	Materials for Biomedical Applications	3	0	0	3
17		UBM2043	Hospital Planning and Waste Management	3	0	0	3
18		UCH2041	E-Waste Management	3	0	0	3
19	Chemical	UCH2042	Nanoscience for Engineers	3	0	0	3
20	1	UCH2043	Sustainable Development	3	0	0	3
21		UME2041	Six Sigma Data Analysis	2	0	2	3
22	Mechanical	UME2042	Product Engineering	3	0	0	3
23		UME2043	Operations Management	3	0	0	3
24		UCE2041	Green Building Design	3	0	0	3
25		UCE2042	Sustainable Infrastructure	3	0	0	3
26	Civil	UCE2043	Integrated Water Resource Management	3	0	0	3
27		UCE2044	Environmental Impact Assessment	3	0	0	3
28		PBA2041	Entrepreneurship	3	0	0	3
29	MBA	PBA2042	Supply Chain and Logistics	3	0	0	3

			Management				
30		PBA2043	Design Thinking	2	0	2	3
31		UMA2041	Introduction to Linear Algebra	3	0	0	3
32	Mathematics	UMA2042	Numerical Methods for Engineering	3	0	0	3
33	Dhusing	UPH2041	Optical and Luminescence Characteristics of Materials	3	0	0	3
34		UPH2042	Nanotechnology and Imaging Techniques	3	0	0	3
35	Physics	UPH2043	Nuclear Radiation Hazards and Safety Standards	3	0	0	3
36		UPH2044	Crystal Growth and Radiation Detection Measurements	3	0	0	3
37		UEN2041	English for Career Needs	3	0	0	3
38	English	UEN2042	Word Power for Academic Needs	3	0	0	3
39	English	UEN2043	Writing Skills for University Admission	3	0	0	3

C.		TIVE II (SEMESTER VIII)	1	-	1		
SI. NO	DEPARTMENT OFFERING	COURSE CODE	Course Title	L	Т	Р	С
1		UEC2046	Foundations of Cryptography	3	0	0	3
2		UEC2047	Introduction to Wireless Networks	3	0	0	3
3		UEC2048	Introduction to Microcontrollers	3	0	0	3
4		UEC2049	Consumer Electronics	3	0	0	3
	ECE	UEC2051	Introduction to Bio	_			-
5			Electromagnetics	3	0	0	3
		UEC2052	Machine Learning for Signal and				
6		0202002	Image Processing	3	0	0	3
7		UCS2044	Introduction to Big Data Analytics	2	0	2	3
8	CSE UCS2045 Machine Learning Applications					2	3
9	CDL	UCS2045	Web Technology	22	0	2	3
10	UIT2047 Introduction To Cyber Security					2	3
10	-	UIT2047 UIT2048	Introduction To Cyber Security	2	0	2	5
11				2	0	2	3
	-	UIT2049	Engineering IoT Architectures and				
12	IT	0112049		2	0	2	3
12	-	11172051	Programming	2	0	2	2
13		UIT2051	Introduction To Deep Learning	2	0	2	3
14		UIT2052	Introduction To Machine Learning	2	0	2	3
15		UIT2053	Web Services and Devops	2	0	2	3
16		UBM2044	Brain Machine Interface	3	0	0	3
17	BME	UBM2045	Biomedical Physics	3	0	0	3
18		UBM2046	Telehealth Technology	3	0	0	3
19		UCH2044	Industrial Safety	3	0	0	3
20	Chemical	UCH2045	Industrial Waste Management and Audit	3	0	0	3
21		UCH2046	Energy Conservation and Audit	3	0	0	3
22		UME2044	Enterprise Resource Planning	3	0	0	3
23		UME2045	Project Management and Planning	3	0	0	3
-	Mechanical	UME2046	Introduction to Industrial	-	-	-	
24		011111010	Engineering	3	0	0	3
25		UCE2045	Experimental Techniques and	3	0	0	3
			Instrumentation	5			5
26	Civil	UCE2046	Air Pollution and Control	3	0	0	3
20	CIVII		Engineering	5	U	0	5
27		UCE2047	Remote Sensing and GIS	3	0	0	3
28		UCE2048	Environmental Geo-Technology	3	0	0	3
29		PBA2044	Innovation and Creativity	3	0	0	3
30	MBA	PBA2045	Intellectual Property Rights	3	0	0	3
31		UPH2045	Advanced Functional Materials	3	0	0	3
32	Physics	UPH2047	Astrophysics	3	0	0	3
33		UEN2044	Creative Writing	2	1	0	3
	English	UEN2045	Introduction to Children's				
34			Literature	2	0	2	3
		UCV20/1 Electrochemical Energy Storage		-	_	_	_
35	Chemistry		Technology	3	0	0	3
L		1		l	I	I	L

OPEN ELECTIVE II (SEMESTER VIII)